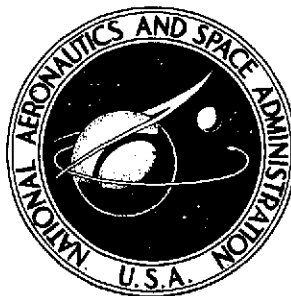


NASA TECHNICAL NOTE



NASA TN D-7621

NASA TN D-7621

(NASA-TN-D-7621) REDUCE 2: A COMPUTER
PROGRAM FOR THE SYMBOLIC REDUCTION OF
LARGE BLOCK DIAGRAMS (NASA) 100 p HC
\$4.00

CSCL 09B

N74-28689

Unclas

H1/08 43726

REDUCE II - A COMPUTER PROGRAM FOR THE SYMBOLIC REDUCTION OF LARGE BLOCK DIAGRAMS

by Carl F. Lorenzo and John P. Riehl

Lewis Research Center

Cleveland, Ohio 44135

NATIONAL AERONAUTICS AND SPACE ADMINISTRATION • WASHINGTON, D. C. • MAY 1974

1. Report No. NASA TN D-7621		2. Government Accession No.		3. Recipient's Catalog No.	
4. Title and Subtitle REDUCE II - A COMPUTER PROGRAM FOR THE SYMBOLIC REDUCTION OF LARGE BLOCK DIAGRAMS				5. Report Date MAY 1974	
				6. Performing Organization Code	
7. Author(s) Carl F. Lorenzo and John P. Riehl				8. Performing Organization Report No. E-5860	
9. Performing Organization Name and Address Lewis Research Center National Aeronautics and Space Administration Cleveland, Ohio 44135				10. Work Unit No. 501-24	
				11. Contract or Grant No.	
				13. Type of Report and Period Covered Technical Note	
12. Sponsoring Agency Name and Address National Aeronautics and Space Administration Washington, D.C. 20546				14. Sponsoring Agency Code	
15. Supplementary Notes					
16. Abstract <p>REDUCE II is a FORMAC program which symbolically calculates the transfer function(s) of <u>any</u> linear-block-diagram output variable to any or all input variables. The program requires as input a set of algebraic expressions representing the block diagram, the desired transfer function(s), and a string of variables indicating the desired order of reduction. The solution is presented in the compact form of a set of nested functions (super G's). The program can handle systems as large as 600 equations and is intended as a tool for the analysis of complex control and dynamic systems. A companion FORTRAN program, EVAL II, which numerically evaluates the solution set to obtain amplitude ratio and phase angle as functions of frequency is also presented.</p>					
17. Key Words (Suggested by Author(s)) FORMAC Symbolic manipulation Block diagram reduction Block diagrams Dynamics Control				18. Distribution Statement Unclassified - unlimited CAT-08	
19. Security Classif. (of this report) Unclassified		20. Security Classif. (of this page) Unclassified		21. No. of Pages 98	
				22. Price* \$4.00	

CONTENTS

	Page
SUMMARY	1
INTRODUCTION	1
REDUCTION TECHNIQUE	2
Basic Philosophy	3
Technique	3
Program Flow	6
APPLICATIONS	11
Application 1: Simple Ladder	11
Application 2: Complex Ladder	15
Application 3: Jet-Engine-Inlet Shock-Position Control	17
Applications: Some Comments	28
Execution time	28
Storage	28
CONCLUSIONS	30
APPENDIXES	
A - SYMBOLS	32
B - ORDER STRING	33
C - PROGRAM IMPLEMENTATION	35
D - DESCRIPTION, FLOW CHARTS, AND LISTINGS FOR COMPUTER PROGRAMS	39
E - USER'S MANUAL	85
REFERENCES	96

PRECEDING PAGE BLANK NOT FILMED

REDUCE II - A COMPUTER PROGRAM FOR THE SYMBOLIC REDUCTION OF LARGE BLOCK DIAGRAMS

by Carl F. Lorenzo and John P. Riehl
Lewis Research Center

SUMMARY

A computer program, REDUCE II, has been written to reduce very large (linear) block diagrams. The program requires as input a set of algebraic expressions representing the block diagram, the desired transfer function(s), and a string of variables indicating the desired order of reduction. REDUCE II then calculates the transfer function(s) of any output variable to any or all input variables. The program is premised on reduction, by loops, of the block diagram. The solution is presented in the compact form of a set of nested functions (super G's). The super G's define the transfer functions in terms of the system information (G's) and the preceding super G's.

The program can handle as many as 600 equations and 600 variables and is intended as a tool for the analysis of complex control and dynamic systems. Several applications are presented.

A FORTRAN evaluation program, EVAL II, accepts the symbolic output generated by REDUCE II and evaluates it numerically to obtain amplitude ratio and phase angle as functions of frequency for any desired G functions.

INTRODUCTION

The use of block diagrams for the analysis of dynamic problems is well known and widespread. As the systems of interest increase in complexity, new techniques are sought to aid the controls engineer in the analysis and reduction of such systems.

Indeed, at least part of the motivation of modern control theory is to deal with the problem of large system complexities through the organizational features provided by the matrix approach.

The concept of block diagram reduction is to simplify the complex diagram to an equivalent diagram composed of a single block or a few blocks, that is, to topologically

simplify the block diagram.

In reference 1, the predecessor of this effort, a program was evolved which symbolically reduced block diagrams to obtain S form and $i\omega$ form algebraic solutions for desired transfer functions. This approach suffices for intermediate-size diagrams and also gives fully expanded closed-form solutions. However, the method is limited to systems of approximately 30 equations (for transfer functions (G's) which are not too complicated) due to storage limitations (for the IBM 7094 computer). Experience with the predecessor program has shown that while the closed-form solutions are desirable for many scientific endeavors, the bulk of the potential applications were of an engineering nature and could not be performed due to the size limitation. Most of these engineering applications required only numerical results representing the desired transfer function. However, the applications tended to be large and quite complex.

Direct matrix methods (ref. 2), for example, could be applied to these systems. However, these methods would require a complete matrix manipulation for each frequency and would become quite expensive in terms of computer time.

Another possible approach is to use the symbolic techniques as a part of a reduction scheme, together with a decomposition method which would not allow the solution to grow within the computer. The development of this approach is the objective of this study.

The report develops the mathematical concepts and a computer program (REDUCE II) to implement this approach. A numerical evaluation program (EVAL II) to use these symbolic results is also developed. Applications of the programs are presented.

REDUCTION TECHNIQUE

In general, dynamic and control systems are analyzed by considering the characteristics of the elements (individual transfer functions) and combining these elements into a system which is the block diagram. The block diagram elements are (1) summers, which add or subtract two or more signals X's; (2) blocks, which accept one signal and modify it through multiplication by a frequency-sensitive operator $G(S)$; and (3) nodes, which split a signal into two or more parts. These elements are then combined to yield linear block diagrams. For details of block diagrams and their reductions, refer to reference 1. This study addresses itself to the reduction of very large linear block diagrams (of arbitrary topology) to obtain the transfer functions of a desired output to any or all inputs. The symbolic computer language FORMAC (ref. 3) is used to achieve the reduction. The FORMAC language is an experimental extension of FORTRAN IV for the IBM 7094 computer.

Basic Philosophy

The fundamental philosophy of reduction used in the REDUCE II program entails two points which are incorporated to maximize block-diagram-size capability. First, any steps which promote significant expansion of the forms within the computer are avoided. For example, substitution of values of the G's is not done in the reduction program. Second, the reduction of the block diagram must proceed in such a manner as to have the system of equations collapse rather than grow in the computer. That is, as variables are eliminated in the reduction process, the coefficients of the remaining variables become combinations of the original coefficients (G's). As this occurs, these combinations are replaced by single-element coefficients (super G's), and the mathematical equation defined by this substitution is immediately output from the computer.

Technique

The general approach to the reduction is as follows:

(1) The system of linear algebraic equations which represent the block diagram is input to the computer in symbolic form.

(2) Input is an order string, that is, a string of variables which guides the manner in which the reduction is to be performed and indicates when a substitution is to be made. From these data, the program reduces the block diagram by loops and, after each loop is reduced, substitutes a new G (a super G) for combinations of G's formed by the reduction process. By reduction of a loop is meant the elimination of those variables which form a cycle or a circuit in the graph theoretical sense (e.g., see refs. 4 and 5). By virtue of this technique, the system of equations in the computer can only collapse; and hence, the largest system which can be handled is approximately the largest system of equations which can be initially input to the computer, or in practical terms, that set of equations which can be held in core.

From the mathematical point of view then, we are starting with a set of linear equations in the variable X with coefficients (G's) which are considered to be constant. Through the reduction and substitution process, we are transforming the original set of equations into a new set of equations which define the super G's in terms of the original G's and previous super G's and into a single equation involving the X 's of the transfer functions.

Even within this framework, a large number of ways exist to proceed, since the form of the equations composing the solution set has not been stipulated. However, the following desirable properties of the solution set can be projected from the intended use:

(1) Since eventually the solution set is to be evaluated numerically for amplitude ratio, phase angle, and so forth, the super G's formed should be nested. That is, a

given super G should depend only on the G's which precede it and on the original G's of the block diagram.

(2) A zero divide occurs when the denominator of a super G is evaluated to be identically zero. The solution set should be of such a form that the likelihood of a zero divide occurring when the solution set is evaluated is minimal.

(3) The solution set should be of such a form that subsequent equation scaling is not necessary. For example, the process could be carried out in such a manner as to allow only super G's of a sum-product form, that is,

$$G_{\text{SUPER}} = G_a G_b G_c + G_d G_e G_f + \dots \text{etc.}$$

Symbols are defined in appendix A. Now, while this form would be highly desirable in terms of property 2, it leads to a scaling problem. Experience has shown that for certain common block diagram topologies (notably some of the ladder networks) the last super G, even for relatively small diagrams, can be a function of ω to a very large power. This, of course, would only allow evaluation to a very small value of ω without some form of scaling. If scaling is to be done, it should be integral with the formation of the solution set.

(4) Finally, it is desired that the solution set be as compact or concise as possible. This is a purely practical requirement, since for very large block diagrams the volume of punched cards and printout could become unwieldy.

Properties 2 and 3 can be conflicting requirements. Consideration of properties 2 and 3 suggests that a most desirable form for the super G's composing the solution set would be

$$G_{\text{SUPER}} = \frac{G_a G_b + G_c G_d \dots}{1 + G_e G_f + G_h G_i G_j \dots} \quad (1)$$

or as close to this form as possible. This form is characterized by the fact that, for G's of the same order, the super G would be of net order 1 and since the denominator has a unity additive term, the possibility of a zero-divide condition (by allowing any G to equal zero) is null. The $G = 0$ special case is considered important since it is the fundamental method of simplifying block diagram topology. It appears that super G's of the form of equation (1) can always be made to occur if the block diagram is reduced by loops.

This is demonstrated by the following simple example. Figure 1 is a block diagram of a loop which is being considered separately from a larger block diagram which contains it. The defining equations for the embedded loop are

$$X_1 - X_2 - X_5 = 0$$

$$X_3 - X_4 - X_6 = 0$$

$$X_3 - G_1 X_5 = 0$$

$$X_2 - G_2 X_4 = 0$$

Eliminating the loop by eliminating the variables X_4 and X_5 yields

$$X_2 = \frac{G_1 G_2}{1 + G_1 G_2} X_1 - \frac{G_2}{1 + G_1 G_2} X_6$$

and

$$X_3 = \frac{G_1}{1 + G_1 G_2} X_1 + \frac{G_1 G_2}{1 + G_1 G_2} X_6$$

where X_2 and X_3 are the loop outputs defined in terms of X_1 and X_6 , the loop inputs. The coefficients of X_1 and X_6 are the super G 's associated with the reduction of the loop. These super G 's are seen to be of the same form as equation (1).

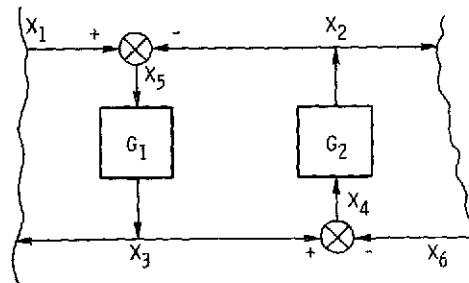


Figure 1. - Block diagram of embedded loop.

The fact that this kind of a solution form is possible, even for a loop embedded in a large block diagram, has been used as a fundamental premise in the structure of the computer program presented in this report. Not every equation affected in the reduction of a loop will contain the $1 + GG + \dots$ coefficient form. That is, those equations outside the loop, but containing loop variables, will not at this stage of the reduction contain the $1 + GG + \dots$ form. They might at a later stage. However, postponement of the

super G substitution is not advised, since the coefficients can grow unreasonably large, defeating the program purpose. Contingencies arise when the loops are very large or difficult to identify. These details are considered later.

Program Flow

Before considering the flow of the reduction program it will be helpful to consider the relation between the reduction and evaluation programs. This relation is indicated in figure 2. The flow chart is composed of two basic parts: the algebraic manipulations

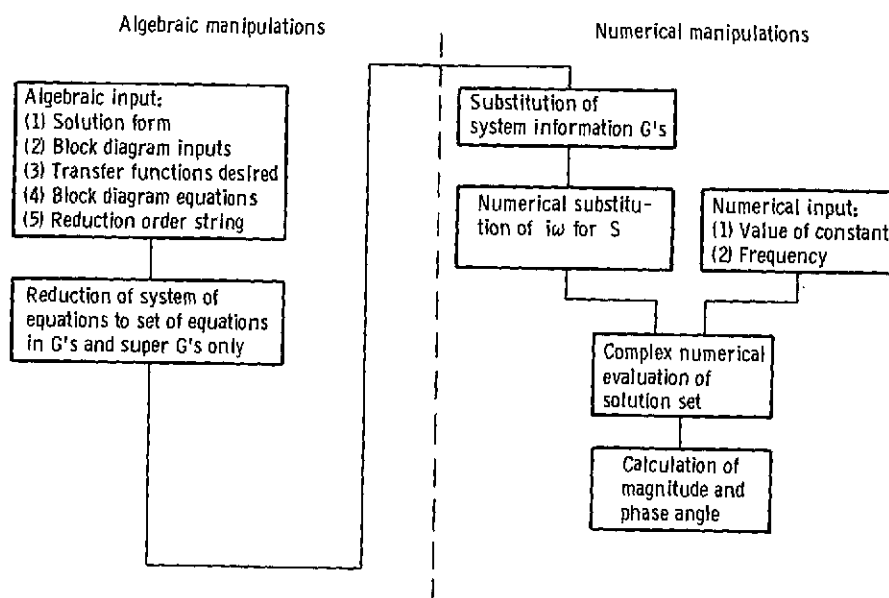


Figure 2. - Relation of algebraic and numerical programs.

are done in FORMAC, and the numerical calculations are done in the companion FORTRAN evaluation program. The expansive step of substituting the values for the G functions into the solution set is postponed until the evaluation program. Thus, larger block diagrams can be reduced. Also flexibility is added since the G's can be changed at will when the numerical evaluations are performed. Hence, it is not necessary to repeat the reduction of a block diagram in order to change the system. The only requirement is that the topology of the block diagram is not changed. Specifically, the topology can be simplified by letting G equal zero, but not made more complex.

The logic and flow of the reduction program are illustrated in the flow chart of figure 3. An understanding of most of the program function is best obtained by referring to a sample reduction as it would be performed by the program. The system to be reduced is shown in block diagram form in figure 4.

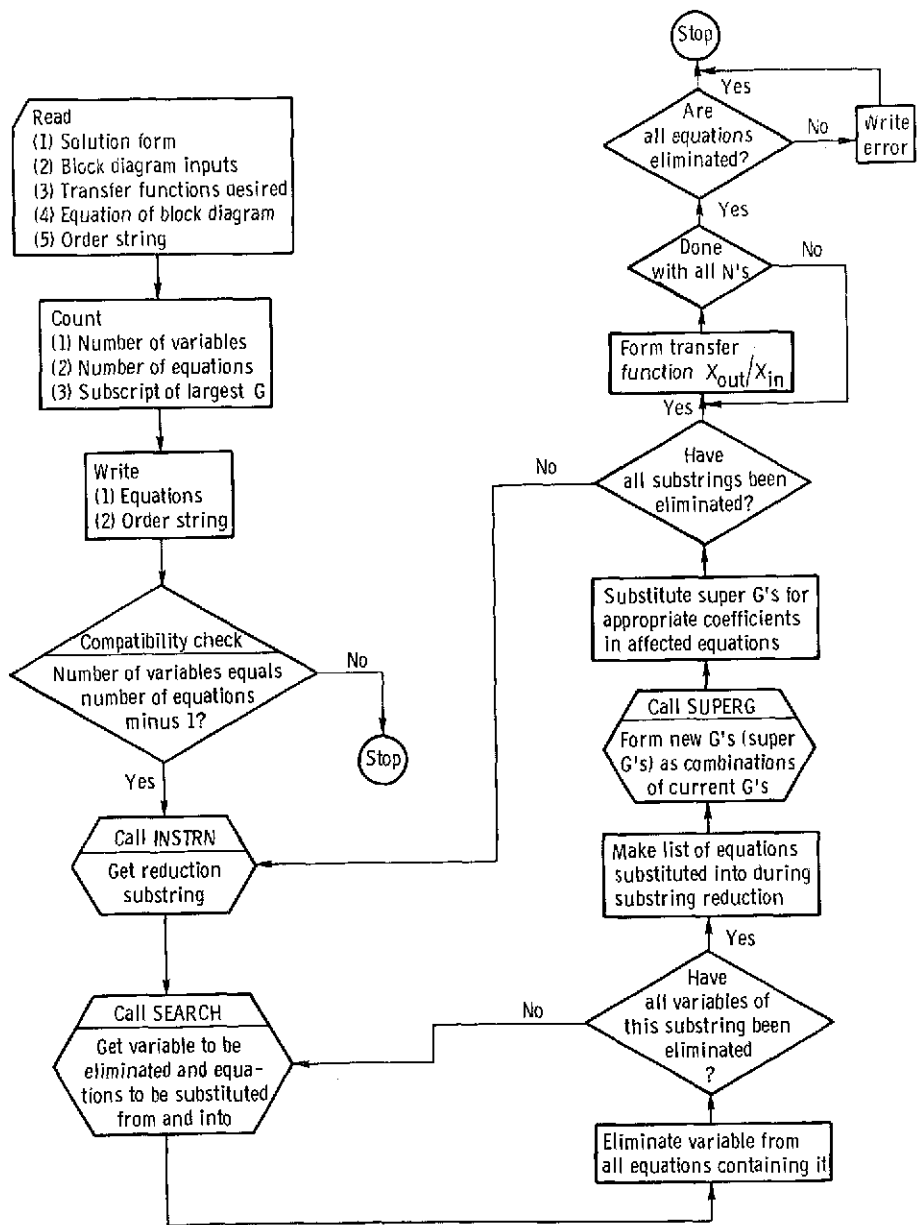


Figure 3. - Reduction program flow chart.

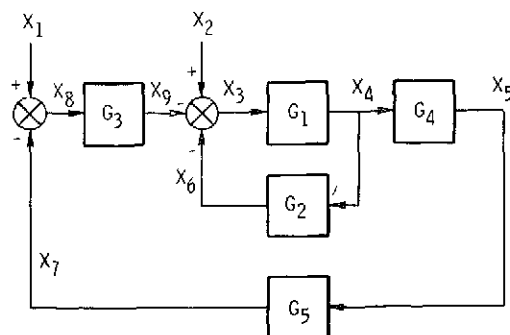


Figure 4. - Block diagram of system to be reduced.

The defining equations for this system are

$$X_1 - X_7 - X_8 = 0 \quad (2)$$

$$X_2 - X_3 - X_6 - X_9 = 0 \quad (3)$$

$$X_4 - G_1 X_3 = 0 \quad (4)$$

$$X_6 - G_2 X_4 = 0 \quad (5)$$

$$X_9 - G_3 X_8 = 0 \quad (6)$$

$$X_5 - G_4 X_4 = 0 \quad (7)$$

$$X_7 - G_5 X_5 = 0 \quad (8)$$

The inputs are X_1 and X_2 , and the desired output is X_5 ; that is, form the transfer functions X_5/X_1 and X_5/X_2 . Since the program reduces by loops, the order string first eliminates the inner loop, that is, the variables X_3 and X_6 . After these are eliminated, a super G substitution is made and the next loop (X_4 , X_7 , X_8 , and X_9) is eliminated. The process is continued until all variables but the output and inputs are eliminated. A reasonable order string for this problem then is

$$X_3, X_6, , X_4, X_7, X_8, X_9, ,$$

where the single commas denote a variable elimination and the double commas denote a variable elimination followed by a super G substitution for those coefficients containing more than two G's. A discussion of the order string selection is included in appendix B.

The system of equations is reduced in the following steps in the same manner as

would occur in the program based on the order string given:

STEP 1: Eliminate variable X_3 . Since X_3 occurs in equations (3) and (4), the simpler expression (eq. (4)) is substituted into the more complex (eq. (3)). Then, multiplying equation (3) by G_1 and substituting X_4 for G_1X_3 yields

$$G_1X_2 - X_4 - G_1X_6 - G_1X_9 = 0 \quad (3a)$$

$$0 = 0 \quad (4a)$$

STEP 2: Eliminate variable X_6 and make super G substitution. Here X_6 occurs in equations (3a) and (5). Again, results from equation (5) are substituted into equation (3a), giving

$$G_1X_2 - X_4 - G_1G_2X_4 - G_1X_9 = 0 \quad (3b)$$

$$0 = 0 \quad (5b)$$

Combining coefficients yields

$$G_1X_2 - (1 + G_1G_2)X_4 - G_1X_9 = 0 \quad (3c)$$

In making the super G substitution, the coefficients of the X's of all effected equations (here only eq. (3c)) are now searched for a $\pm 1 \pm \left\{ \sum_j \prod_k G \right\}$ form. If the form occurs, the equation is divided through by it and super G's are formed. Hence, equation (3c) becomes

$$G_6X_2 + X_4 - G_6X_9 = 0 \quad (3d)$$

where

$$G_6 = \frac{-G_1}{1 + G_1G_2}$$

is the first super G.

STEP 3: Eliminate variable X_4 . Equation (7) is used to eliminate X_4 in equation (3d); then

$$G_4G_6X_2 + X_5 - G_4G_6X_9 = 0 \quad (3e)$$

$$0 = 0 \quad (7a)$$

STEP 4: Eliminate variable X_7 . Here X_7 occurs in equations (2) and (8); hence,

$$X_1 - G_5 X_5 - X_8 = 0 \quad (2a)$$

$$0 = 0 \quad (8a)$$

STEP 5: Eliminate variable X_8 . Using equation (6) in equation (2a) gives

$$G_3 X_1 - G_3 G_5 X_5 - X_9 = 0 \quad (2b)$$

$$0 = 0 \quad (6a)$$

STEP 6: Eliminate variable X_9 and make super G substitution. Substituting from equation (2b) into equation (3e) gives

$$G_4 G_6 X_2 + X_5 - G_3 G_4 G_6 X_1 + G_3 G_4 G_5 G_6 X_5 = 0 \quad (3f)$$

Combining coefficients yields

$$G_3 G_4 G_6 X_1 - G_4 G_6 X_2 - (1 + G_3 G_4 G_5 G_6) X_5 = 0 \quad (3g)$$

Recognizing the $1\pm$ form and forming the super G's gives

$$G_7 X_1 + G_8 X_2 + X_5 = 0 \quad (3h)$$

where

$$G_7 = \frac{G_3 G_4 G_6}{-(1 + G_3 G_4 G_5 G_6)}$$

and

$$G_8 = \frac{-G_4 G_6}{-(1 + G_3 G_4 G_5 G_6)}$$

This completes the reduction as indicated by the order string. The only remaining step is to form the desired transfer functions X_5/X_1 and X_5/X_2 . To form X_5/X_1 , let $X_2 = 0$ in equation (3h); hence,

$$G_7 X_1 = -X_5$$

$$\frac{X_5}{X_1} = \frac{G_7}{-1}$$

Likewise for X_5/X_2 , let $X_1 = 0$ to give

$$G_8 X_2 = -X_5$$

$$\frac{X_5}{X_2} = \frac{G_8}{-1}$$

While it did not occur in this reduction, if at some step a variable to be eliminated occurs in three or more equations, the simplest equation is used to eliminate it in all equations in which it occurs. Also, if a substitution is called for by the order string and an effected equation does not have a $\left(\pm 1 \pm \sum_j \prod_k G \right)$ form coefficient, a 1.0 can be added to the largest coefficient and this factor used to scale the equation. If this is done, the solution is said to be of the ARTIFICIAL form. If 1.0 is not added but the coefficient itself is used to scale the equation, the solution is called the NATURAL form. The choice of form is made by the user. The details of program implementation are covered in appendix C. The descriptions, listings, and flow charts for the computer programs are detailed in appendix D. A user's manual is provided in appendix E.

Discussion of the companion program EVAL II is also contained in these appendices.

APPLICATIONS

Applications of the program were chosen to achieve two objectives: first, to study certain operating characteristics of the program, namely, operating time and size capabilities; and second, to demonstrate the program for typical controls block diagrams.

Application 1: Simple Ladder

For this first study, a simple ladder block diagram of the form of figure 5 was reduced. This topology is typical of finite difference approximations to the wave or diffusion equations. For wave equations, this would be a string of coupled oscillators.

The basic equation form for each of the ladder's 600 rungs is

$$X_{n+1} - G_n X_n + G_n X_{n+2} = 0 \quad \text{for } n = 1, 2, \dots, 598$$

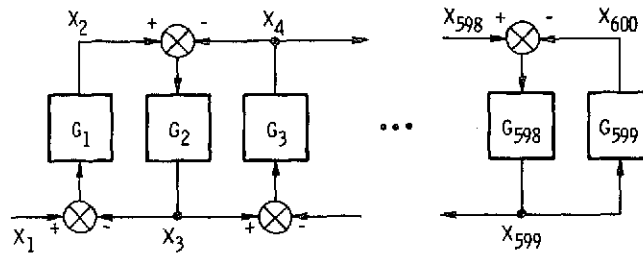


Figure 5. - Block diagram of simple ladder network.

To terminate the ladder, the equation

$$X_{600} - G_{599}X_{599} = 0$$

was used.

The reduction order string for this problem is

$$X_{600}, X_{599}, X_{598}, \dots, X_5, X_4, X_3$$

The transfer function desired is that for X_2/X_1 . Typical input equations and the first and last parts of the solution set of equations as generated by the program are presented in figure 6. The solution set (fig. 6) is output in the form of FORTRAN expression and not as a mathematical equation. That is, mathematically

$$G(601) = \frac{G_{598}}{\text{DENOM}(1)} = \frac{G_{598}}{-G_{598}G_{599} - 1.0}$$

The time history of reduction of the 600-equation set is shown in figure 7. As might be expected, the slope of the curve indicates that the reduction proceeds more quickly as variables are eliminated. The total reduction time for the 600-rung ladder is about 3500 seconds.

The repetitive nature of block diagram topology allows the solution to be readily checked. Also, the repetition, together with the order of solution chosen, allows one to consider the problem as a new ladder one rung shorter after each variable is eliminated. Hence, it could appear as though 600 ladder networks of lengths 1 to 600 were reduced. The initial rate of reduction of each of these ladders against the ladder size is shown in figure 8. Here the rates vary from 0.1 variable per second for the 600-equation ladder to 0.5 variable per second for a 25-equation ladder.

The 600-equation ladder is the practical upper limit for the computing system used for this study. Larger problems could be input; however, peripheral storage (noncore) would be required, thus heavily penalizing computing time.

THE BLOCK DIAGRAM INPUTS

X(1)\$

THE SOLUTION IS FOR X(2)\$ TO X(1)\$

THE BLOCK DIAGRAM EXPRESSIONS

```

1 X( 2)-G( 1)*X( 1)+G( 1)*X( 3)$
2 X( 3)-G( 2)*X( 2)+G( 2)*X( 4)$
3 X( 4)-G( 3)*X( 3)+G( 3)*X( 5)$
4 X( 5)-G( 4)*X( 4)+G( 4)*X( 6)$
5 X( 6)-G( 5)*X( 5)+G( 5)*X( 7)$
6 X( 7)-G( 6)*X( 6)+G( 6)*X( 8)$
7 X( 8)-G( 7)*X( 7)+G( 7)*X( 9)$
8 X( 9)-G( 8)*X( 8)+G( 8)*X(10)$
9 X(10)-G( 9)*X( 9)+G( 9)*X(11)$
10 X(11)-G(10)*X(10)+G(10)*X(12)$
11 X(12)-G(11)*X(11)+G(11)*X(13)$
12 X(13)-G(12)*X(12)+G(12)*X(14)$
13 X(14)-G(13)*X(13)+G(13)*X(15)$
14 X(15)-G(14)*X(14)+G(14)*X(16)$
15 X(16)-G(15)*X(15)+G(15)*X(17)$
16 X(17)-G(16)*X(16)+G(16)*X(18)$
17 X(18)-G(17)*X(17)+G(17)*X(19)$
18 X(19)-G(18)*X(18)+G(18)*X(20)$

```

.
.

```

593 X( 594)-G( 593)*X( 593)+G( 593)*X( 595)$
594 X( 595)-G( 594)*X( 594)+G( 594)*X( 596)$
595 X( 596)-G( 595)*X( 595)+G( 595)*X( 597)$
596 X( 597)-G( 596)*X( 596)+G( 596)*X( 598)$
597 X( 598)-G( 597)*X( 597)+G( 597)*X( 599)$
598 X( 599)-G( 598)*X( 598)+G( 598)*X( 600)$
599 X( 600)-G( 599)*X( 599)$

```

(a) Input expressions.

*** OUTPUT FROM REDUCE II ***

DENOM(1)=-
-g(598)*g(599)-1.0

G(600)=G(598)

G(600)=G(600)/DENOM(1)

DENOM(2)=
G(597)*G(600)-1.0

G(601)=G(597)

G(601)=G(601)/DENOM(2)

DENOM(3)=
G(596)*G(601)-1.0

. . .

. . .

. . .

DENOM(597)=
G(2)*G(1195)-1.0

G(1196)=G(2)

G(1196)=G(1196)/DENOM(597)

DENOM(598)=
G(1)*G(1196)-1.0

G(1197)=G(1)

G(1197)=G(1197)/DENOM(598)

TRANSFER FUNCTION X(2)/X(1)

THE NUMERATOR
G(1197)

THE DENOMINATOR
(-1.0)

(b) Solution-set equations.

Figure 6. - Simple-ladder input and solution set

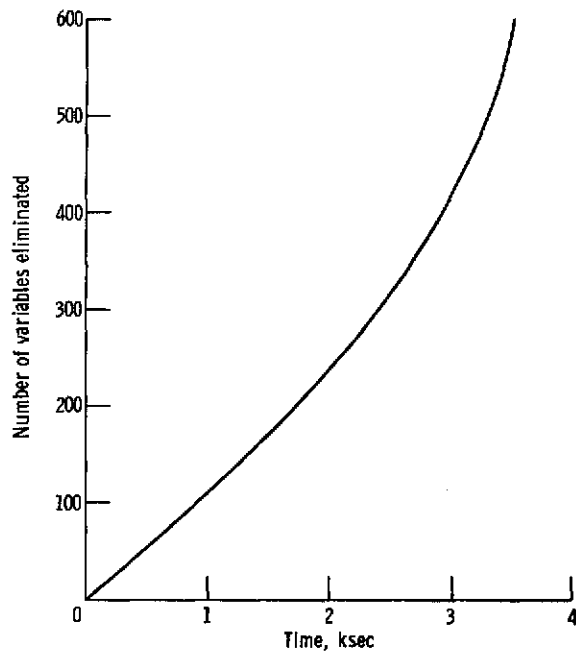


Figure 7. - Reduction history of 600-equation simple ladder.

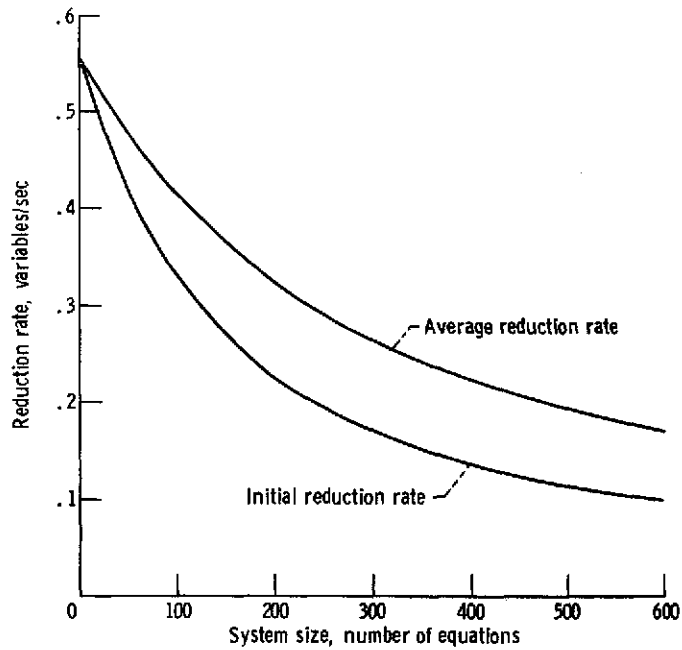


Figure 8. - Reduction rate as function of problem size for 600-equation simple ladder.

Application 2: Complex Ladder

For this application, a ladder of coupled four-terminal networks was reduced. The ladder is composed of 150 rungs, each having two equations; the block diagram is shown in figure 9. For a typical application, each rung of such a ladder would represent a distributed parameter representation of the wave equation. That is, the transfer functions of the blocks would be complex hyperbolic functions or delay times. The topology has wide application.

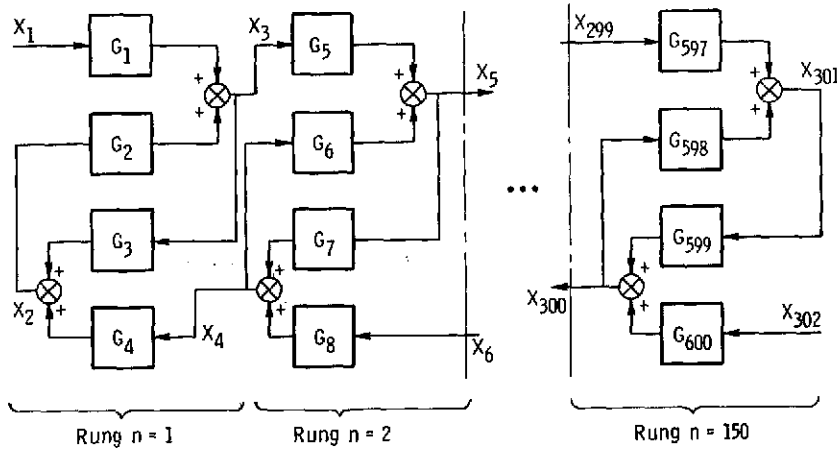


Figure 9. - Block diagram of complex ladder network (four-terminal elements).

The basic equations for each rung of the ladder, for $n = 1, 2, \dots, 150$, are

$$X_{2n+1} - G_{4n-3}X_{2n-1} - G_{4n-2}X_{2n} = 0$$

and

$$X_{2n} - G_{4n-1}X_{2n+1} - G_{4n}X_{2n+2} = 0$$

The desired transfer functions are X_2/X_1 and X_2/X_{302} . The reduction order is $X_{301}, X_{300}, X_{299}, X_{298}, X_{297}, \dots, X_6, X_5, X_4, X_3$.

The first and last parts of the solution-set input equations are presented in figure 10. The history of the reduction is shown in figure 11. The total time for the reduction is 1010 seconds.

Somewhat larger ladders of this type could be reduced with the program if the dimension of G is increased. This was not attempted in this study.

Figure 10. - Complex-ladder input and solution set

(a) Input expressions.

```

1 X( 3)-G( 1)*X( 1)-G( 2)*X( 2)
2 X( 2)-G( 3)*X( 3)-G( 4)*X( 4)
3 X( 5)-G( 5)*X( 6)*X( 3)-G( 6)*X( 4)
4 X( 4)-G( 7)*X( 8)*X( 5)-G( 10)*X( 6)
5 X( 7)-G( 9)*X( 5)-G( 10)*X( 6)
6 X( 6)-G( 11)*X( 7)-G( 12)*X( 8)
7 X( 9)-G( 13)*X( 7)-G( 14)*X( 8)
8 X( 8)-G( 15)*X( 9)-G( 16)*X( 10)
9 X( 11)-G( 17)*X( 9)-G( 18)*X( 10)
10 X( 10)-G( 19)*X( 11)-G( 20)*X( 12)
11 X( 13)-G( 21)*X( 11)-G( 22)*X( 12)
12 X( 12)-G( 23)*X( 13)-G( 24)*X( 14)
13 X( 15)-G( 25)*X( 13)-G( 26)*X( 14)
14 X( 14)-G( 27)*X( 15)-G( 28)*X( 16)
15 X( 17)-G( 29)*X( 15)-G( 30)*X( 16)
16 X( 16)-G( 31)*X( 17)-G( 32)*X( 18)
17 X( 19)-G( 33)*X( 17)-G( 34)*X( 18)
18 X( 18)-G( 35)*X( 19)-G( 36)*X( 20)

```

THE BLOCK DIAGRAM EXPRESSIONS

THE SOLUTION IS FOR X(2) \$ TO THE INPUTS

X(1)\$
X(302)

THE BLOCK DIAGRAM INPUTS

*** OUTPUT FROM REDUCE 11 ***

```

DENOM( 1)=G(598)*G(599)-1.0
G( 601)=G(597)*G(599)
G( 601)=G( 601)/DENOM( 1)
G( 602)=G(600)
G( 602)=G( 602)/DENOM( 1)
DENOM( 2)=G(594)*G(595)-G(594)*G(596)*G(601)-1.0
G( 603)=G(593)*G(595)-G(593)*G(596)*G(601)
G( 603)=G( 603)/DENOM( 2)
DENOM( 150)=G(2)*G(3)-G(2)*G(4)*G(897)-1.0
G( 899)=G(1)*G(3)-G(1)*G(4)*G(897)
G( 899)=G( 899)/DENOM( 150)
G( 900)=G(4)*G(898)
G( 900)=G( 900)/DENOM( 150)
TRANSFER FUNCTION X( 2)/X( 1)
THE NUMERATOR
G(899)
THE DENOMINATOR
(-1.0)
TRANSFER FUNCTION X( 2)/X( 302)
THE NUMERATOR
G( 900)
THE DENOMINATOR
(-1.0)

```

(b) Solution-set equations.

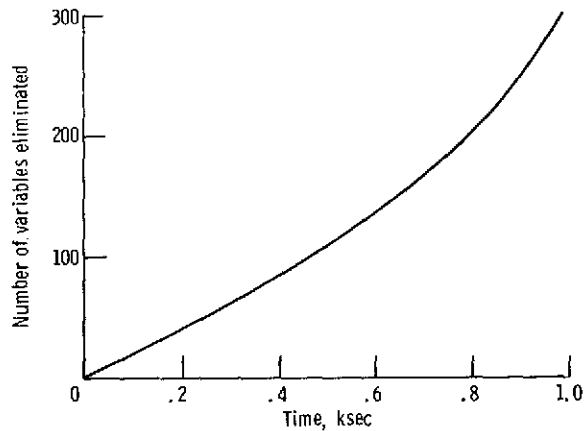


Figure 11. - Reduction history of 300-equation complex ladder.

Application 3: Jet-Engine-Inlet Shock-Position Control

The block diagram of figure 12 represents a system for control of the position of a shock wave in a supersonic inlet for a jet engine using engine fuel flow. "Modern" control techniques were used to design a controller to minimize the occurrence of inlet unstarts in the presence of a stochastic disturbance. The control designer wished to obtain specific transfer functions from which system frequency domain behavior could be studied. Since a PADE' approximation to the inlet plant dead time had been made for control design purposes, it was important to determine the effect of this approximation on dynamic performance. Transfer functions X_7/X_1 , X_7/X_2 , and X_7/X_3 were obtained for this reason. The equations representing the plant and controller (the block diagram) as input to the program are shown in figure 13(a). Also shown is the order of reduction.

The block diagram inputs are X_1 , X_2 , and X_3 . The results of this reduction (using the ARTIFICIAL form of solution) are given in figure 13(b). From these results, evaluations with different plants and controllers can be made as long as the topology of the block diagram does not become more complex. Essentially, any simplification of the topology is possible.

For example, we can check the plant transfer function by simply evaluating X_7/X_2 with G_{16} to G_{21} equal to zero. This check capability, by specifying certain G's to be zero, is useful when working with very large systems. Also, it is nearly always possible when the solution is of the ARTIFICIAL form.

The time required to execute this reduction is 25 seconds. The system is approximately equivalent to 50 elementary equations as determined by consideration of the number of simple summers and blocks of the block diagram.

Figure 12. - Block diagram of jet engine inlet control.

THE BLOCK DIAGRAM INPUTS

X(1)\$
X(2)\$
X(3)\$

THE SOLUTION IS FOR X(7)\$ TO THE INPUTS

THE BLOCK DIAGRAM EXPRESSIONS

```

1  -X(10)+X(9)-G(10)*X(16)-G(11)*X(15)-G(12)*X(14)-G(13)*X(13)-G(14)*X(12)-G(15)*X(
1  11)$
2  X(1)+X(6)-X(7)$
3  X(3)-X(17)-X(4)$
4  X(2)+X(14)-X(5)$
5  X(6)-G(1)*X(5)$
6  X(7)-X(18)-X(8)$
7  -X(9)+G(9)*X(8)+G(2)*X(4)$
8  X(11)-G(3)*X(10)$
9  -X(12)+G(3)*G(8)*X(8)+G(3)*X(11)$
10 -X(13)+G(3)*G(7)*X(8)+G(3)*X(12)$
11 -X(14)+G(3)*G(6)*X(8)+G(3)*X(13)$
12 -X(15)+G(3)*G(5)*X(8)+G(3)*X(14)$
13 -X(15)+G(3)*G(4)*X(8)+G(3)*X(15)$
14 -X(17)+G(16)*X(16)+G(17)*X(15)+G(18)*X(14)+G(19)*X(13)+G(20)*X(12)+G(21)*X(11)$
15 -X(18)+G(22)*X(16)+G(23)*X(15)+G(24)*X(14)+G(25)*X(13)$

```

THE REDUCTION ORDER IS

```

1  X(10),X(11),,X(12),,X(13),,X(14),,X(15),,X(16),,X(9),X(18),X(8),,X(6),X(17),X(4)
2  ,,X(5)$

```

THE LARGEST VARIABLE SUBSCRIPT IS 18

THE NUMBER OF EXPRESSIONS IS 15

THE LARGEST FUNCTION (G) SUBSCRIPT IS 25

(a) Input equations.

* * * OUTPUT FROM REDUCE [I] * * *

$$\text{DENOM(1)} = -G(3)*G(20)-G(21)+1.0$$

$$G(26) = \frac{-G(3)*G(20)-G(21)}{G(26)/\text{DENOM(1)}}$$

$$G(27) = \frac{G(3)*G(8)*G(21)}{G(27)/\text{DENOM(1)}}$$

$$G(28) = \frac{-G(3)*G(16)}{G(28)/\text{DENOM(1)}}$$

$$G(29) =$$

(b) Solution-set equations.

Figure 13. - Input and solution set for jet-engine-control problem.

```

      -G(3)*G(17)
G( 29)=G( 29)/DENOM( 1)

      -G(3)*G(18)
G( 30)=G( 30)/DENOM( 1)

      -G(3)*G(19)
G( 31)=G( 31)/DENOM( 1)

      G(3)
G( 32)=G( 32)/DENOM( 1)

DENOM( 2)=
      G(3)*G(15)+G(3)**2 *G(14)+1.0

      -G(3)*G(8)-G(3)**2 *G(8)*G(15)
G( 33)=G( 33)/DENOM( 2)

      G(3)**2 *G(10)
G( 34)=G( 34)/DENOM( 2)

      G(3)**2 *G(11)
G( 35)=G( 35)/DENOM( 2)

      G(3)**2 *G(12)
G( 36)=G( 36)/DENOM( 2)

      G(3)**2 *G(13)
G( 37)=G( 37)/DENOM( 2)

      -G(3)**2
G( 38)=G( 38)/DENOM( 2)

DENOM( 3)=
      G(3)*G(7)*G(26)-G(3)*G(27)+1.0

      G(3)*G(7)*G(26)-G(3)*G(27)
G( 39)=G( 39)/DENOM( 3)

```

(b) Continued.

Figure 13. - Continued.

```

G( 40)=
      -G(3)*G(28)
G( 40)=G( 40)/DENOM( 3)

G( 41)=
      -G(3)*G(29)
G( 41)=G( 41)/DENOM( 3)

G( 42)=
      -G(3)*G(30)
G( 42)=G( 42)/DENOM( 3)

G( 43)=
      -G(3)*G(31)-G(26)
G( 43)=G( 43)/DENOM( 3)

G( 44)=
      -G(3)*G(32)
G( 44)=G( 44)/DENOM( 3)

DENOM( 4)=
      -G(3)*G(37)-1.0

G( 45)=
      G(3)*G(7)-G(3)*G(33)
G( 45)=G( 45)/DENOM( 4)

G( 46)=
      -G(3)*G(34)
G( 46)=G( 46)/DENOM( 4)

G( 47)=
      -G(3)*G(35)
G( 47)=G( 47)/DENOM( 4)

G( 48)=
      -G(3)*G(36)
G( 48)=G( 48)/DENOM( 4)

G( 49)=
      -G(3)*G(38)
G( 49)=G( 49)/DENOM( 4)

DENOM( 5)=
      -G(3)*G(24)-G(25)+1.0

G( 50)=

```

(b) Continued.

Figure 13. - Continued.


```

      -G(3)*G(24)-G(25)
G( 50)=G( 50)/DENOM( 5)

G( 51)=
      G(3)*G(6)*G(25)
G( 51)=G( 51)/DENOM( 5)

G( 52)=
      -G(3)*G(22)
G( 52)=G( 52)/DENOM( 5)

G( 53)=
      -G(3)*G(23)
G( 53)=G( 53)/DENOM( 5)

G( 54)=
      G(3)
G( 54)=G( 54)/DENOM( 5)

DENOM( 6)=
      1
      G(3)*G(6)*G(43)-G(3)*G(39)+1.0

G( 55)=
      G(3)*G(6)*G(43)-G(3)*G(39)
G( 55)=G( 55)/DENOM( 6)

G( 56)=
      -G(3)*G(40)
G( 56)=G( 56)/DENOM( 6)

G( 57)=
      -G(3)*G(41)
G( 57)=G( 57)/DENOM( 6)

G( 58)=
      -G(3)*G(42)-G(43)
G( 58)=G( 58)/DENOM( 6)

G( 59)=
      -G(3)*G(44)
G( 59)=G( 59)/DENOM( 6)

DENOM( 7)=
      -G(3)*G(48)-1.0

G( 60)=
      G(3)*G(6)-G(3)*G(45)
G( 60)=G( 60)/DENOM( 7)

```

(b) Continued.

Figure 13. - Continued.

```

G( 61)=
      -G(3)*G(46)
G( 61)=G( 61)/DENOM( 7)

G( 62)=
      -G(3)*G(47)
G( 62)=G( 62)/DENOM( 7)

G( 63)=
      -G(3)*G(49)
G( 63)=G( 63)/DENOM( 7)

DENOM( 8)=
      G(3)*G(5)*G(50)-G(3)*G(51)+1.0

G( 64)=
      G(3)*G(5)*G(50)-G(3)*G(51)
G( 64)=G( 64)/DENOM( 8)

G( 65)=
      -G(3)*G(52)
G( 65)=G( 65)/DENOM( 8)

G( 66)=
      -G(3)*G(53)-G(50)
G( 66)=G( 66)/DENOM( 8)

G( 67)=
      -G(3)*G(54)
G( 67)=G( 67)/DENOM( 8)

DENOM( 9)=
      G(3)*G(5)*G(58)-G(3)*G(55)+1.0

G( 68)=
      G(3)*G(5)*G(58)-G(3)*G(55)
G( 68)=G( 68)/DENOM( 9)

G( 69)=
      -G(3)*G(56)
G( 69)=G( 69)/DENOM( 9)

G( 70)=
      -G(3)*G(57)-G(58)
G( 70)=G( 70)/DENOM( 9)

G( 71)=

```

(b) Continued.

Figure 13. - Continued.

```

      -G(3)*G(59)
G( 71)=G( 71)/DENOM( 9)

DENOM( 10)=
      -G(3)*G(62)-1.0

G( 72)=
      G(3)*G(5)-G(3)*G(60)
G( 72)=G( 72)/DENOM( 10)

G( 73)=
      -G(3)*G(61)
G( 73)=G( 73)/DENOM( 10)

G( 74)=
      -G(3)*G(63)
G( 74)=G( 74)/DENOM( 10)

DENOM( 11)=
      G(3)*G(4)*G(66)-G(3)*G(64)+1.0

G( 75)=
      G(3)*G(4)*G(66)-G(3)*G(64)
G( 75)=G( 75)/DENOM( 11)

G( 76)=
      -G(3)*G(65)-G(66)
G( 76)=G( 76)/DENOM( 11)

G( 77)=
      -G(3)*G(67)
G( 77)=G( 77)/DENOM( 11)

DENOM( 12)=
      G(3)*G(4)*G(70)-G(3)*G(68)+1.0

G( 78)=
      G(3)*G(4)*G(70)-G(3)*G(68)
G( 78)=G( 78)/DENOM( 12)

G( 79)=
      -G(3)*G(69)-G(70)
G( 79)=G( 79)/DENOM( 12)

G( 80)=
      -G(3)*G(71)
G( 80)=G( 80)/DENOM( 12)

```

(b) Continued.

Figure 13. - Continued.

DENOM(13) =
 $-G(3)*G(73)-1.0$

G(81) =
 $G(3)*G(4)-G(3)*G(72)$
 G(81) = G(81) / DENOM(13)

G(82) =
 $-G(3)*G(74)$
 G(82) = G(82) / DENOM(13)

DENOM(14) =
 $-G(75)+G(76)*G(81)+1.0$

G(83) =
 $-G(75)+G(76)*G(81)$
 G(83) = G(83) / DENOM(14)

G(84) =
 $G(76)*G(82)$
 G(84) = G(84) / DENOM(14)

G(85) =
 $-G(77)$
 G(85) = G(85) / DENOM(14)

DENOM(15) =
 $-G(78)+G(79)*G(81)+1.0$

G(85) =
 $-G(78)+G(79)*G(81)$
 G(86) = G(86) / DENOM(15)

G(87) =
 $G(79)*G(82)$
 G(87) = G(87) / DENOM(15)

G(88) =
 $-G(80)$
 G(88) = G(88) / DENOM(15)

DENOM(16) =
 $G(2)*G(83)*G(87)-G(2)*G(84)*G(86)-G(2)*G(85)*G(87)+1.0$

G(89) =
 $G(2)*G(83)*G(87)-G(2)*G(84)*G(86)-G(2)*G(85)*G(87)$
 G(89) = G(89) / DENOM(16)

(b) Continued.

Figure 13. - Continued.

```

G( 90)=
      G(9)*G(84)*G(88)+G(83)*G(88)-G(85)*G(88)
G( 90)=G( 90)/DENOM( 16)

G( 91)=
      -G(9)*G(85)*G(87)-G(85)*G(86)
G( 91)=G( 91)/DENOM( 16)

DENOM( 17)=
      G(89)-G(90)+1.0

G( 92)=
      G(89)-G(90)
G( 92)=G( 92)/DENOM( 17)

G( 93)=
      -G(89)+G(90)
G( 93)=G( 93)/DENOM( 17)

G( 94)=
      -G(90)
G( 94)=G( 94)/DENOM( 17)

G( 95)=
      -G(91)
G( 95)=G( 95)/DENOM( 17)

DENOM( 18)=
      G(1)*G(95)+G(93)+1.0

G( 96)=
      G(1)*G(95)+G(93)
G( 96)=G( 96)/DENOM( 18)

G( 97)=
      G(1)*G(92)
G( 97)=G( 97)/DENOM( 18)

G( 98)=
      G(1)*G(94)
G( 98)=G( 98)/DENOM( 18)

G( 99)=
      -G(93)
G( 99)=G( 99)/DENOM( 18)

TRANSFER FUNCTION X( 7)/X( 1)

```

(b) Continued.

Figure 13. - Continued.

```

THE NUMERATOR
G(99)

THE DENOMINATOR
-G(96)

TRANSFER FUNCTION X( 7)/X( 2)

THE NUMERATOR
G(97)

THE DENOMINATOR
-G(96)

TRANSFER FUNCTION X( 7)/X( 3)

THE NUMERATOR
G(98)

THE DENOMINATOR
-G(96)

```

(b) Concluded.

Figure 13. - Concluded.

A numerical evaluation for the following set of G's (system information) was made by using the EVAL program:

$$G_1 = \frac{846.7(-0.833 \times 10^{-2} S^3 + 0.1 S^2 - 0.5 S + 1.0)}{S^6 + 18.28 S^5 + 155.4 S^4 + 743.9 S^3 + 2038 S^2 + 2823 S + 846.7}$$

$$G_2 = 846.7$$

$$G_3 = \frac{1}{S}$$

$$G_4, G_5, \dots, G_9 = 2.041662, -0.3595, -2.54, 8.723, -1.5025, -146.932$$

$$G_{10}, G_{11}, \dots, G_{15} = 846.7, 2823, 2038, 743.9, 155.4, 18.28$$

$$G_{16}, G_{17}, \dots, G_{21} = 998.9, 600.97, 155.18, 20.745, 1.300, 0.038$$

For the nonapproximate case, the plant transfer function becomes

$$G_1 = \frac{7.06 e^{-1.0S}}{S^3 + 6.33 S^2 + 20.01 S + 7.06}$$

The frequency range of interest is 0.01 to 4.0 hertz, in steps of 0.01 hertz. (Because of time and frequency scaling requirements of the user, frequency was multiplied

by 100.) The execution time required to evaluate these 400 points plus an additional 600 points for the automated plot routine for all three transfer functions is 32 seconds. Plots of typical results for the X_7/X_1 transfer function are presented in figure 14. The difference in the plots is of course the effect of the PADE' approximation at the higher frequencies.

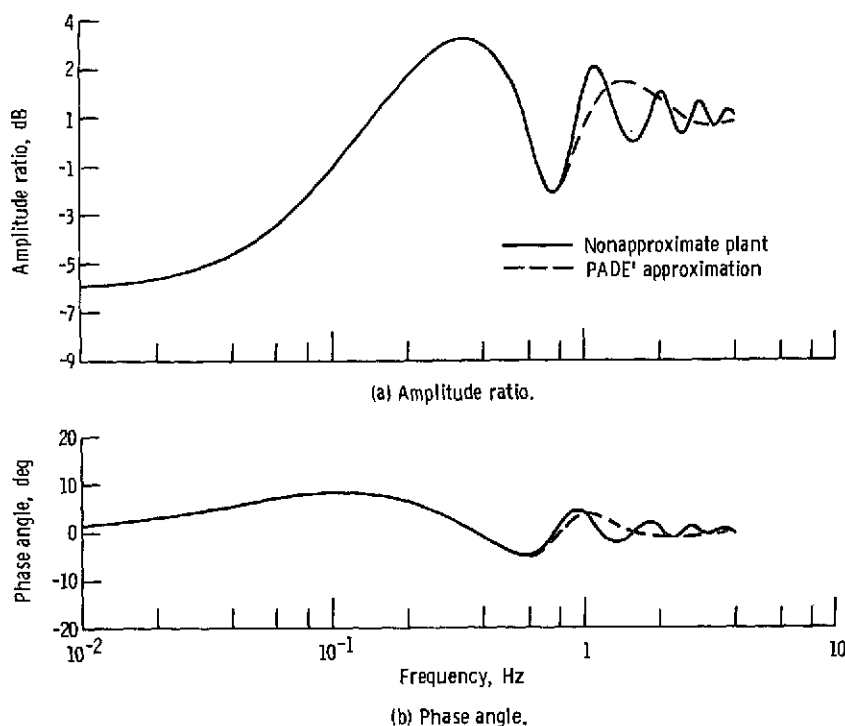


Figure 14. - Typical transfer function results, for jet-engine-control problem.

Applications: Some Comments

Execution time. - A summary plot of reduction rate as a function of problem size for the applications studied is presented in figure 15. Generally, the program reduces more quickly for smaller problem size, as would be expected.

Storage. - Four terms are involved in considerations of storage for this program; they are related by the equation

PROGRAM STORAGE + INITIAL EQUATION STORAGE

$$+ X_{\text{STORAGE}} + G_{\text{STORAGE}} = \text{CONSTANT}$$

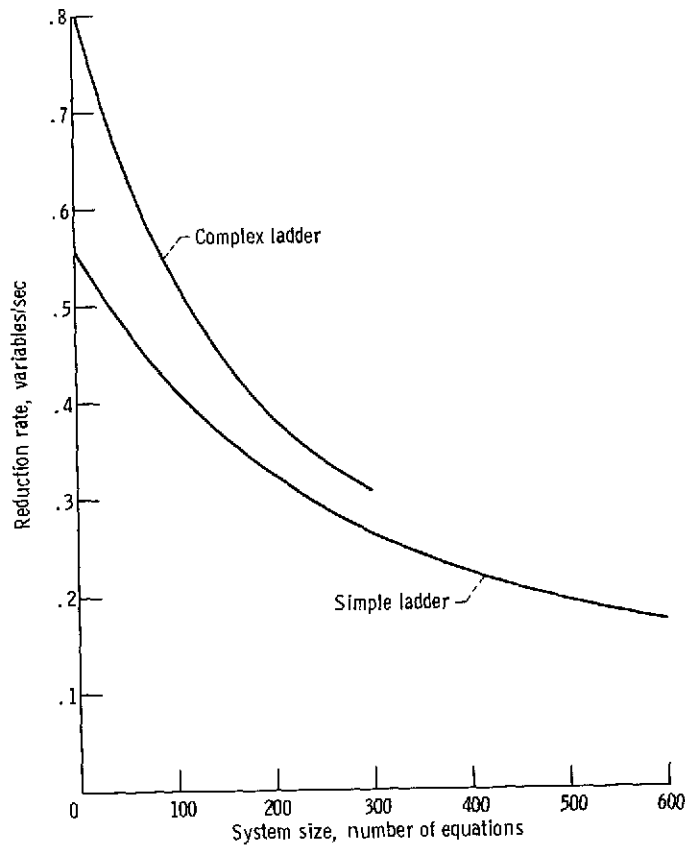


Figure 15. - Comparison of reduction rate as function of problem size for complex and simple ladders.

Since program storage is fixed when considering problem capability for a given computer, we have

$$\text{INITIAL EQUATION STORAGE} + X_{\text{STORAGE}} + G_{\text{STORAGE}} = \text{CONSTANT}$$

Now for large problems with relatively few inputs

$$N_{\text{EQ}} = \text{NUMBER OF EQUATIONS} \approx \text{NUMBER OF X's} = N_{\text{X}}$$

and for a given class of problem we can write

$$X_{\text{STORAGE}} = K'N_{\text{EQ}}$$

Also, it is clear that

$$\text{INITIAL EQUATION STORAGE} = K''N_{\text{EQ}}$$

$$G_{\text{STORAGE}} = K'''N_G$$

Combining these results yields

$$K'N_{\text{EQ}} + K''N_{\text{EQ}} + K'''N_G = \text{CONSTANT}$$

Hence,

$$N_{\text{EQ}} + KN_G = \text{CONSTANT}$$

Here N_{EQ} is the original number of equations and N_G is the total number of G's (original plus super G's). This relation then should be useful in setting or changing array sizes for either (1) different computers or (2) problems where the relation of N_G to N_{EQ} varies substantially.

CONCLUSIONS

Techniques have been established and a computer program written to allow the computer reduction of large arbitrary block diagrams. The techniques used involve symbolic manipulation of the defining equations by means of the FORMAC symbolic computer language. With the program, transfer functions can be determined for any output variable to any or all input variables. Since the primary objective of the work was to handle quite large and complex block diagrams, the solution is not formed as a single relationship for a desired transfer function. The solution, instead, is determined as a set of algebraic equations. Each of these equations, called super G's, is defined in terms of the original system G's and the super G's which precede it.

The transfer functions are represented as a set of nested equations. This form has the advantage of being considerably more compact than the single relationship. Also, since the solution-set relations can be output from the computer as they are formed, the critical problem of computer storage is alleviated. Further, the nested form of the solution set allows straightforward numerical evaluation.

The program is premised on the reduction of the block diagram by loops. When this is achieved, the solution is automatically scaled so that effective large powers of frequency do not occur. Also, the denominators are such that the possibility of zero-divides is small.

Two forms of the solution set are possible at the option of the user.

A program has been written to evaluate the solution set. This evaluation yields the real and imaginary parts and the phase angle and magnitude and log magnitude ratios of the transfer functions.

The advantages of the technique developed in the present study over previous techniques are as follows:

1. As in the predecessor program, the arrangement of the input data in the form of arrays and the matrix manipulation for each frequency point are not required. (The symbolic solution set need be generated only once and then is reevaluated for each frequency.)

2. Unlike the predecessor program, the generation of a solution set instead of a single function allows the solution of considerably more complex problems, that is, systems involving as many as 600 equations and a total of 1200 G's.

The user input to the reduction program consists of two basic pieces of information: (1) the algebraic equations representing the block diagram; and (2) the order string, which controls the manner in which the reduction is performed. The first part represents a minimal effort on the part of the user. The determination of the order string does pose a small burden for the user. However, usually the consequence of a poor choice for the order string is a relatively small increase in the size of the solution set.

The computing time required for the program varies with the size of the problem being solved. Typical rates are 0.6 variable per second for small problems to an initial rate of 0.1 variable per second for the larger problems.

Lewis Research Center,
National Aeronautics and Space Administration,
Cleveland, Ohio, October 5, 1973,
501-24.

APPENDIX A

SYMBOLS

DENOM	denominator of super G
G	transfer function for block in original block diagram
G _{SUPER}	function defining part of solution set
i	$\sqrt{-1}$
K	constant
N()	number of ()
S	Laplace variable
X	signal or variable in a block diagram
ω	circular frequency, rad/sec
Subscripts:	
a, b, c, . . . ,	index numbers 1, 2, . . .
j, k, n	
EQ	equations
i	inputs
os	order string
v	variables

APPENDIX B

ORDER STRING

The order string is a list of the block diagram variables. The order of the variables occurring in the list is the order in which they are to be reduced in the program. The variables are separated by commas. For example, X_a, X_b, X_c indicates eliminate variable X_a , then X_b , then X_c . Separation of a pair of variables by double commas indicates that a super G substitution is to be made at that point.

The program logic is premised on reduction of the block diagram by loops. The loops of the block diagram are analogous to the cycles or circuits of graph theory (refs. 4 and 5). That is, a loop is a progression of variables in a block diagram that closes on itself. Variables which split off (nodes) and leave the loop or those which enter the loop (through a summer) will be called communicating spurs, or simply spurs.

The suggested best approach then will be to identify from the block diagram those loops having the least number of communicating spurs. The variables composing the loop, less the communicating spur variables, if possible, then form an order substring. The order of reduction of the variables forming the loop does not appear to be important. In the example of figure 16, the loop comprised of X_3, X_4, X_{10} has only two spurs,

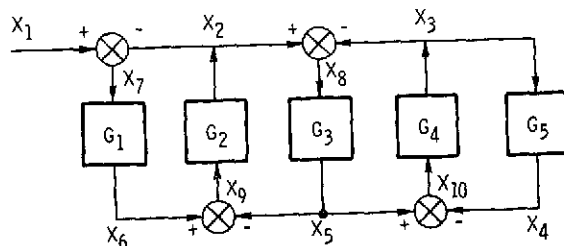


Figure 16. - Block diagram used to show reduction of order string.

namely X_5 and X_3 . Hence, an appropriate substring would be X_4, X_{10} or X_{10}, X_4 . Elimination of this loop would leave a new loop with variables X_5, X_3 , and X_8 with spurs X_5 and X_2 giving a substring X_8, X_3 . After the reduction of each loop, a super G substitution should be made, that is, separation by double commas. Hence, the order string for this reduction might be

$$X_{10}, X_4, , X_3, X_8, , X_5, X_9, , X_2, X_7$$

where we have considered X_6 to be the output variable.

While it is not always possible to get an end loop, that is, one with only two spurs,

the program appears to be quite forgiving; and even taking internal loops as shown in the text, gives rise to the same general forms. This will generate a larger number of super G's, however.

Several checks can be made after an order string has been selected:

- (1) All variables in the problem must be represented in the order string except the output and the inputs (which, of course, are not eliminated in the reduction).
- (2) No variable can be represented more than once.
- (3) From algebraic theory,

$$N_V - N_{EQ} = N_i$$

for the original system of equations. And, for the order string,

$$(N_V)_{OS} = N_V - N_i - 1$$

Hence

$$(N_V)_{OS} = N_{EQ} - 1$$

This check is also made by the program.

The choice of the order string for very large or very complex (interactive) diagrams may be difficult. Occasionally, for such cases the solution generated will be valid only over some limited frequency band. This is usually recognized by an instability occurring in the numerical solution above some frequency. In such cases, it may be necessary to change the order string to achieve a better solution form.

APPENDIX C

PROGRAM IMPLEMENTATION

The complete reduction and numerical evaluation of a block diagram is done in two separate programs. The reduction program is called REDUCE II and is written in FORMAC, and the evaluation program is called EVAL II and is in FORTRAN. FORMAC is an algebraic manipulation language. FORMAC stands for FORmula MAnipulation Compiler. It is an experimental language developed by IBM, and it runs on an IBM 7094/7044 computer. Bond describes FORMAC in reference 3. There are other algebraic languages which might be used in block diagram reduction. These languages are detailed by Sammet in reference 6. Two programs are necessary to maximize block-diagram-size capability. This approach separates the numerical evaluation from the reduction process. This separation is made since the numerical evaluations are performed more efficiently in FORTRAN than in FORMAC. The two-program approach also gives the user the ability to change component descriptions in EVAL II.

The program listings and flow charts are given in appendix D.

REDUCTION PROGRAM - REDUCE II

REDUCE II is the main program in the block diagram reduction. Initially, the block diagram expressions, the inputs and the output, are read and counted. The reduction order string is examined for algebraic compatibility. That is,

$$\text{Number of variables in order string} = \text{Number of expressions} - 1$$

Since the user may solve for the ratio of an output to an input or an output to all the inputs (see User's Manual (appendix E) for details), the block diagram inputs not used in a specified transfer function are set to zero.

The reduction proceeds by choosing a variable to eliminate, solving for that variable in one of the equations, and substituting the solution for that variable in the remaining equations. Subroutine INSTRN finds the variables in a reduction substring and puts their subscripts in common block STRING. Subroutine SEARCH picks the equations for elimination and substitution in the reduction STRING. SEARCH obtains the variable to be eliminated from the information contained in common block STRING. The general rule is to take the simplest equation as the one to be eliminated. By simplest is meant the equation with the fewest variables. If the variable due for elimination is in more than two equations, some more selective rules are employed. These rules are embodied in

the following priority schedule, which has as its basis identification of the equations in the loop specified by the order substring (when possible):

(1) If another variable in the reduction substring is contained in two or more equations that contain the variable to be eliminated, pick the simplest equation of this new subset of equations to substitute into the other equations that contain the variable to be eliminated.

(2) If there are no more variables in the reduction substring or if rule 1 is not satisfied, look for other variables in common among the equations that contain the variable to be eliminated. If two or more equations contain a variable in common (other than the variable to be eliminated), pick the simplest of these as the equation to be eliminated. If neither rule 1 nor rule 2 can be followed, the simplest equation is picked as the one to be eliminated. Further, if only one (or no) equation contains the variable to be eliminated, an error message is written out and execution is stopped. With this method, the number of equations and variables is reduced by one at each step. The variables that appear in the transfer function are, of course, never eliminated. The final equation contains only the variables of the transfer function and the G-functions.

In the reduction process, new combinations of G's (functions) are formed in subroutine SUPERG. It should be noted that the program assumes that an expression is an equation. That is, if $G(1)*X(1)+X(2)$ is the FORMAC expression, then $G_1X_1 + X_2 = 0$ is the implied equation. An expression prior to super G substitution might look like

$$(1.+G(1)*G(2))*X(1)+G(3)*G(4)*X(5)-G(5)*X(6)$$

The SUPERG subroutine would pick $(1.+G(1)*G(2))$ as a denominator and construct new coefficients such as $G(6)$ and $G(7)$, where

$$G(6)=G(3)*G(4)/(1.+G(1)*G(2))$$

and

$$G(7)=-G(5)/(1.+G(1)*G(2))$$

SUPERG would punch these new coefficients in FORTRAN in the following style:

$$\text{DENOM}(1)=1.+G(1)*G(2)$$

$$G(6)=G(3)*G(4)$$

$$G(6)=G(6)/\text{DENOM}(1)$$

$$G(7)=-G(5)$$

$$G(7)=G(7)/\text{DENOM}(1)$$

Upon leaving subroutine SUPERG this expression would be $X(1)+G(6)*X(5)+G(7)*X(6)$.

The user has the option of selecting one of two forms for a super G. It is possible to always have a denominator of the form

$$1.+G_a * G_b * G_c * G_d + G_e * G_f * G_g + G_k * G_l * G_m \dots$$

This can be done by picking a coefficient of some variable and adding 1.0 to it. This new term can be divided into all the coefficients of the variables in an expression. This process tends to generate more super G's than when the super G's are allowed to form naturally. By punching the word ARTIFICIAL on the first data card to REDUCE II this form of super G will be produced whenever SUPERG finds a coefficient with two or more terms. If the user does not specify ARTIFICIAL or NATURAL (1.0 is not added to coefficients), an error message is printed out and execution stops.

The output of the REDUCE II program is punched on cards and printed on paper. The cards plus the user's data supply all the information for the EVAL II program. See the user's manual for further information of card input and output. Since the program should be as easy to use and as reliable as possible, the program input is given in algebraic terms for the most part. The user does not have to give a count of how many variables, expressions, inputs, and functions are to follow, as was required in the predecessor of this program. The programs interpret the user's data for this information. The only nonalgebraic piece of data is the first card, which specifies what form the user desires the super G's to have. An attempt has been made to make the programs efficient in terms of execution time. The subroutine COUNTX was written to be faster than the corresponding FORMAC routines that could have been used. Auxiliary array sizes have been kept as small as possible to maximize block-diagram-size capability. It is possible to have a block diagram that is so large that it would be stored on an auxiliary storage device (tape or disk file). If this does happen, there will be a substantial increase in execution time because moving information to and from an auxiliary device is inherently slow. REDUCE II does not call on SIN, COS, TANH, ATAN, ALOG, DUMP, PDUMP, FMCDIF, EXPDMP, or FMCDMP. Using the dummy subroutines SIN, COS, TANH, ATAN, ALOG, DUMP, PDUMP, FMCDIF, EXPDMP, and FMCDMP allows us to use the storage space normally assigned to these routines.

The user may, for any particular job, change any of the dimensions of the program. In particular, if more inputs are desired, the array INPUT should be lengthened. If more equations or variables are needed, the arrays EQ and X should be changed. Also the value of MAX(1) must be changed. If some other number of functions (G's) is to be used, the G array and MAX(2) should be changed accordingly.

EVALUATION PROGRAM - EVAL II

The EVAL II program evaluates the cards REDUCE II punched out. The user inserts some of these cards directly into EVAL II as FORTRAN coding. The remainder is numerical data to identify transfer functions. The program covers a frequency band of FSTART to FEND in steps of DELTAF. The output of EVAL II consists of a tabulation of the transfer functions for each frequency point. Also a set of CALCOMP plots for the frequency band can be obtained. The written information gives a transfer function number, the frequency point, the real and imaginary parts of the transfer function, the absolute value and phase angle of the transfer function, and the magnitude of the transfer function in decibels, based on $\text{dB} = 20 \log_{10} (\text{absolute value})$. The plots are of magnitude against frequency and phase angle against frequency. These plots can be made on a linear or semilogarithmic set of axes. The user's manual (appendix E) gives more information on the actual use of EVAL II.

SUBPROGRAMS

REDUCE II uses the following subprograms that are not supplied with either FORTRAN, FORMAC, or this report. These subprograms must be supplied by the user:

<u>Function</u>	<u>Description</u>
ALS(N, X)	Accumulator left shift of X by N binary places
IARS(N, X)	Accumulator right shift of X by N binary places
LGR(N, X)	Logical right shift of X by N binary places
AND(X1, X2)	Logical intersection of X1 and X2
OR(X1, X2)	Logical union of X1 and X2

EVAL II uses the following subprograms that are part of the CALCOMP plotting package. These programs must be user supplied since CALCOMP has proprietary rights on their use. They are LINE, SCALE, AXIS, SYMBOL, NUMBER, and PLOT.

APPENDIX D

DESCRIPTION, FLOW CHARTS, AND LISTINGS FOR COMPUTER PROGRAMS

DESCRIPTION

Reduction Program - REDUCE II

The main program REDUCE II reads the input data, interprets data, and does the actual block diagram reduction. It prints and punches out the transfer function generated.

Subroutine COUNT counts the number of variables in an expression. It returns the number of variables and/or the variables to the calling program.

Subroutine SEARCH finds expressions containing the variable to be eliminated. It constructs a list of the variable to be eliminated, the expression to be eliminated, and the equations to be substituted into.

Subroutine SUPERG creates the super G's or combinations of functions formed in the reduction process.

Subroutine SOUT outputs FORMAC expressions. This output consists of a printed statement, a punched card, or both.

Subroutine INSTRN reads reduction substrings and provides a count of the number of variables and the variables in the substring.

DELETE, REMOVE, FC, and NBR are used to remove \$ from FORMAC expressions and to convert floating-point exponents to fixed-point exponents.

Subroutine COS with entry points SIN, TANH, ATAN, ALOG, DUMP, PDUMP, FMCDIF, EXPDMP, and FMCDMP is a dummy subroutine that is not called. It provides entry-point names that are the same as subprograms referenced by FORMAC but are not executed by the programs of this report. This prevents the equivalent subprograms from being loaded and conserves storage space.

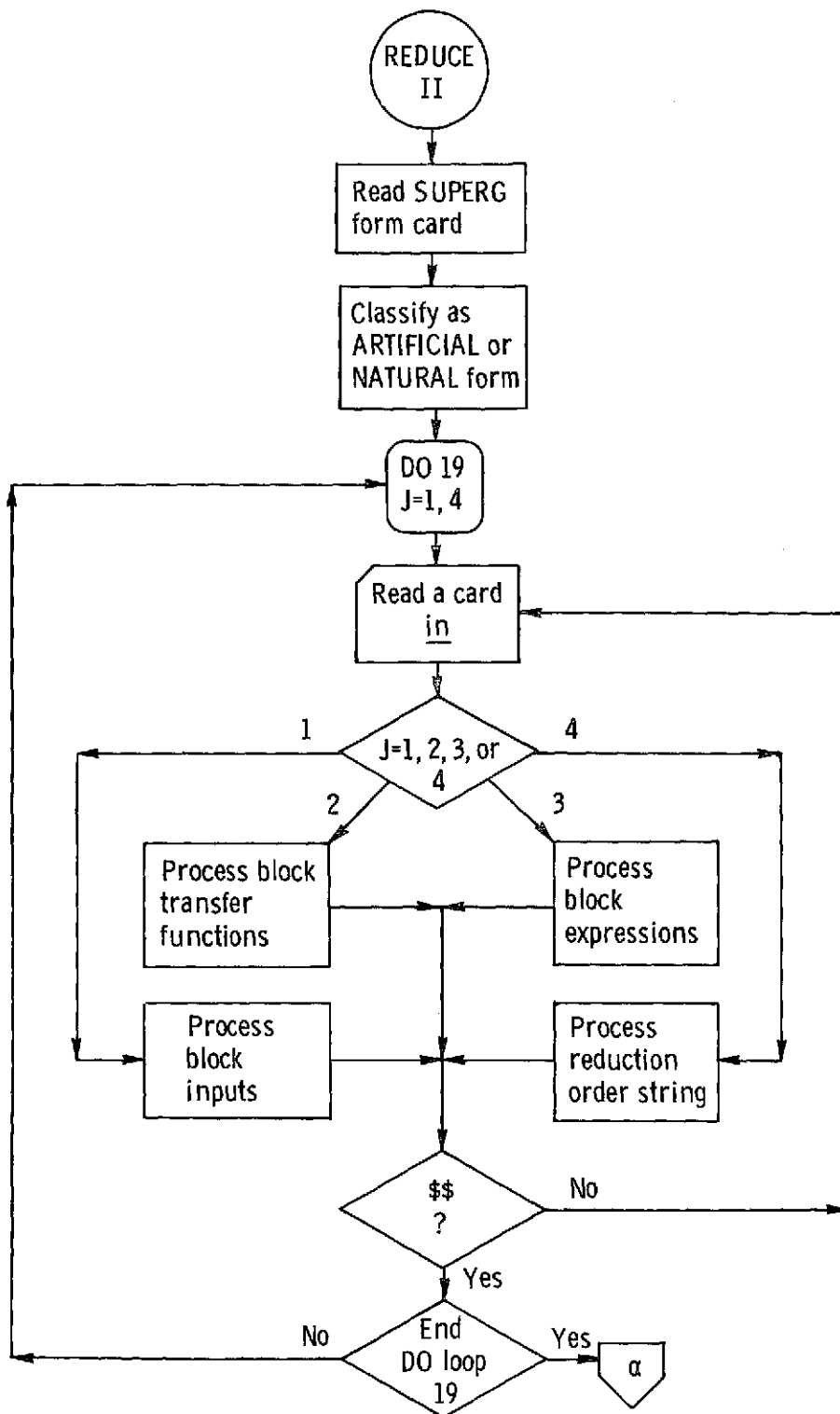
Evaluation Program - EVAL II

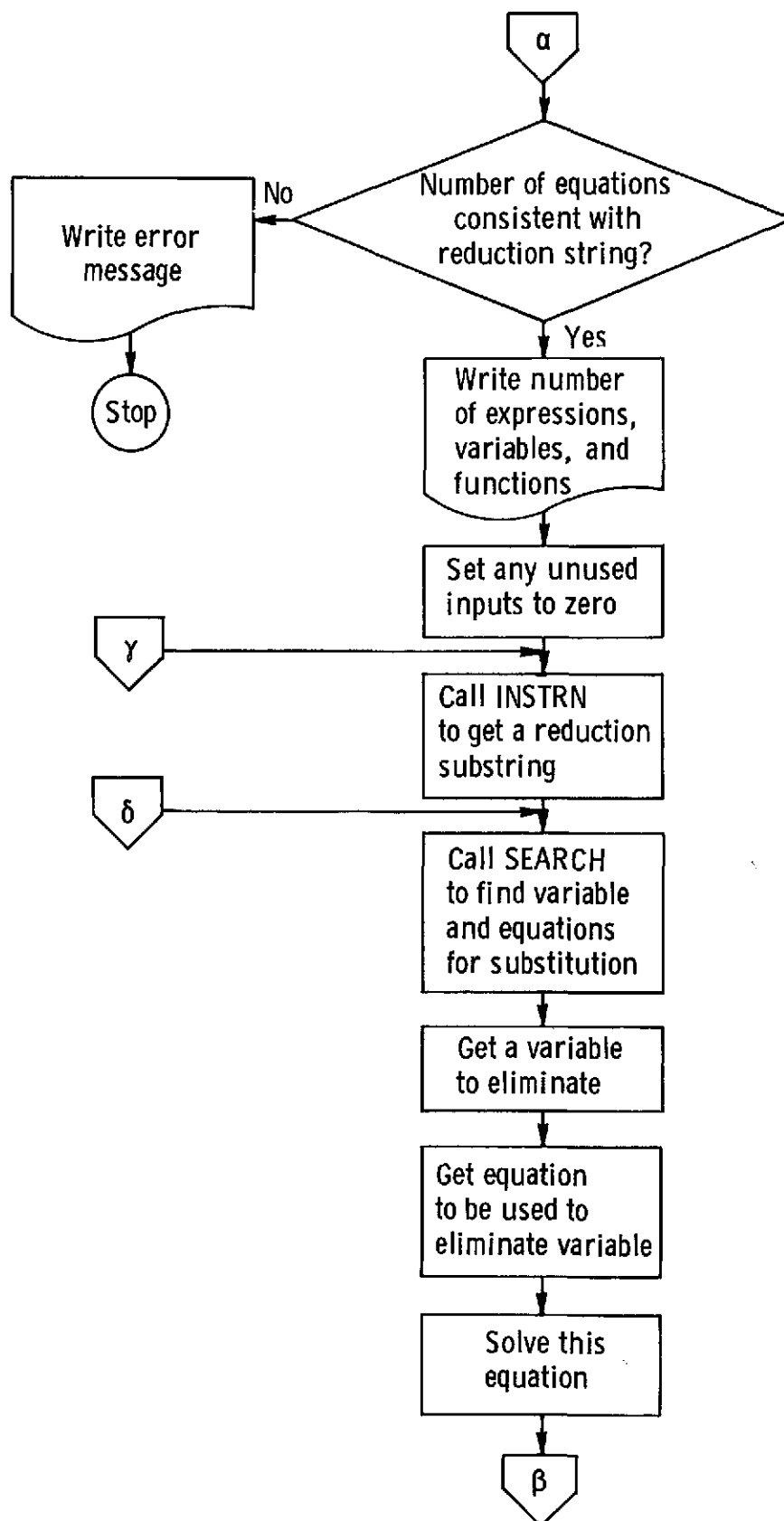
The main program EVAL II reads and writes all the numerical input and output. It calls the subprograms that evaluate the super G's and the transfer functions.

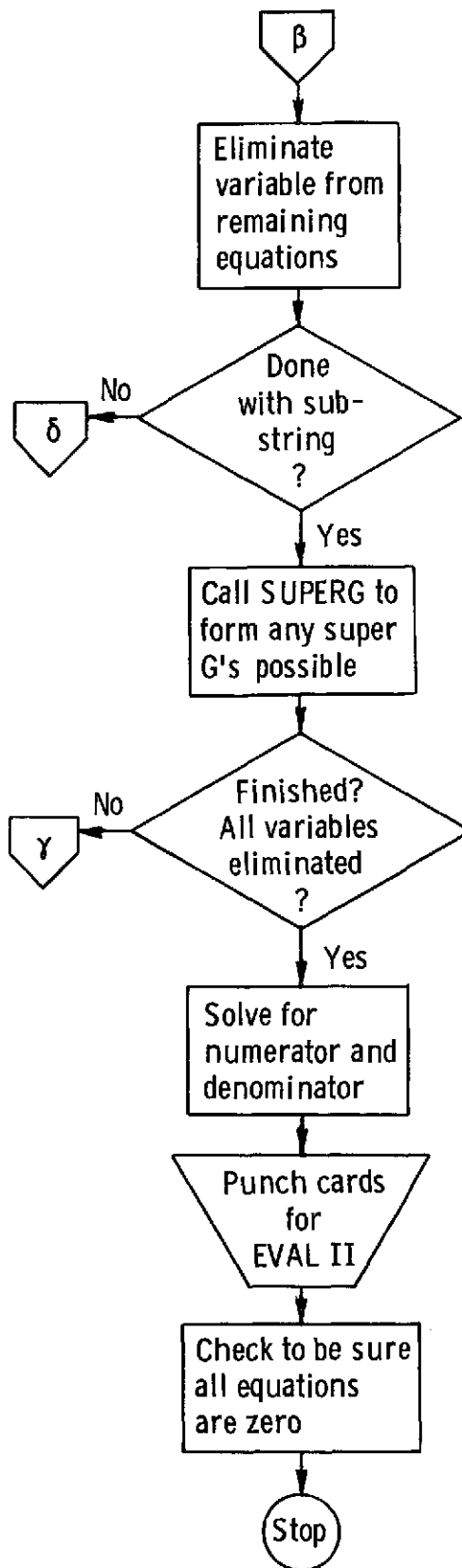
The function subprogram EXPFX, SINFX, COSFX, SINHFX, COSHFX, SQRTFX evaluates the supplied system functions.

The G's, super G's, and transfer function cards (NO=, DO=) are inserted in subroutine COEFF. The actual evaluation of the transfer function occurs in COEFF.

Reduction Program - REDUCE II







SYMARG	A	1
ATOMIC X(601),G(1202)	A	2
COMMON /TRANS/ ARTIF		
DIMENSION IN(70), OUT(17), NEQ(100), EQ(601), INPUT(5), NXARRY(30)	A	3
1, MINXG(2), GORX(2), MAX(2), LSAVE(50)	A	4
DIMENSION IARTIF(3),NATUR(3)		
LOGICAL LOCATE,TEST,FINISH,DONE,ARTIF	A	5
INTEGER OUT		
REAL IS,IT,NUM	A	6
EQUIVALENCE (IN(1),OUT(1),NEQ(1)), (MINXG(1),M), (MINXG(2),MG)	A	7
EQUIVALENCE (PLUS1,ARTIF)		
DATA IARTIF(1),NATUR(1)/15HARTIFICIAL FORM,13HNATURAL FORM /		
DATA MAX/600,1200/	A	8
DATA DR/6H\$00000/	A	9
DATA XX/6HK00000/	A	10
DATA MINXG,GORX/2*0,1HX,1HG/	A	11
C*****	A	12
C M IS THE NUMBER OF VARIABLES	A	13
C M1 IS THE NUMBER OF EQUATIONS	A	14
C IK IS THE NUMBER OF INPUTS	A	15
C MG IS THE NUMBER OF FUNCTIONS AT INPUT	A	15
C*****	A	17
1 CONTINUE	A	21
PLUS1=3.		
READ(5,42) (IN(I),I=1,3)		
DO 100 I=1,3		
IF(IN(I).EQ.IARTIF(I)) PLUS1=PLUS1+1.		
IF(IN(I).EQ.NATUR(I)) PLUS1=PLUS1-1.		
100 CONTINUE		
IF(PLUS1.NE.0..AND.PLUS1.NE.6.) GO TO 380		
C*****	A	18
C READ THE BLOCK DIAGRAM PARTS	A	19
C*****	A	20
NX=0	A	22
M1=1	A	23
IK=0	A	24
MG=0	A	24A
M=0	A	24B
DO 19 J=1,4	A	25
NN=0	A	26
PREV=BL	A	27
2 K=1	A	28
3 K1=14*(K-1)+1	A	29
K2=K1+13	A	30
READ (5,42) (IN(L),L=K1,K2)	A	31
GO TO (4,9,13,17),J	A	32
C*****	A	33
C INTERPRET THE BLOCK DIAGRAM INPUTS	A	34
C*****	A	35
4 CONTINUE	A	36
DO 5 I=1,80	A	37
F=FC(IN(K1),I)	A	38
IF (F.EQ.DR) IK=IK+1	A	39
IF (F.EQ.DR.AND.PREV.EQ.DR) GO TO 6	A	40
PREV=F	A	41
5 CONTINUE	A	42
K=K+1	A	43
GO TO 3	A	44

6	JJ=0	A	45
	IK=IK-1	A	46
	IF (IK.GT.5) GO TO 35	A	47
	DO 7 JJJ=1,IK	A	48
	LET INPUT(JJJ)=ALGCON IN(1),JJ	A	49
7	CONTINUE	A	50
	WRITE (6,54)	A	51
	DO 8 L=1,IK	A	52
	Q=0.0	A	53
	LET Q = BCDCON INPUT(L),OUT,17	A	54
8	WRITE (6,51) OUT(2)	A	55
	GO TO 19	A	56
C*****			
C	INTERPRET THE DESIRED BLOCK DIAGRAM OUTPUT	A	57
C*****			
9	CONTINUE	A	60
	JQ=0	A	61
	DO 10 I=1,80	A	62
10	IF (FC(IN(K1),I).EQ.DR) JQ=JQ+1	A	63
	JJ=0	A	64
	LET NUM = ALGCON IN(1),JJ	A	65
	IF (JQ.EQ.2) GO TO 11	A	66
	LET DEN = ALGCON IN(1),JJ	A	67
11	CONTINUE	A	68
	Q=0.0	A	69
	LET Q = BCDCON NUM,OUT,17	A	70
	IF (JQ.EQ.3) GO TO 12	A	71
	WRITE (6,46) OUT(2)	A	72
	WRITE (6,49)	A	73
	GO TO 19	A	74
12	CONTINUE	A	75
	WRITE (6,47) OUT(2)	A	76
	Q=0.0	A	77
	LET Q = BCDCON DEN,OUT,17	A	78
	WRITE (6,48) OUT(2)	A	79
	WRITE (6,49)	A	80
	GO TO 19	A	81
C*****			
C	INTERPRET THE BLOCK DIAGRAM EXPRESSIONS	A	82
C*****			
13	CONTINUE	A	85
	Q=1.	A	86
	DONE=.FALSE.	A	87
	DO 14 I=1,80	A	88
	F=FC(IN(K1),I)	A	89
	IF (F.EQ.DR) Q=0.	A	90
	IF (F.EQ.DR.AND.PREV.EQ.DR) DONE=.TRUE.	A	90
	PREV=F	A	91
14	CONTINUE	A	92
	WRITE (6,53) M1,(IN(KK),KK=K1,K2)	A	93
	K=K+1	A	94
	IF (K.GT.5) GO TO 38	A	95
	IF (Q.NE.0.) GO TO 3	A	96
	DO 16 MM=1,2	A	97
	CALL COUNT (IN(1),GORX(MM),NXS,NXARRY,0)	A	98
	IF (NXS.EQ.0) GO TO 16	A	99
	DO 15 NN=1,NXS	A	100
15	MINXG(MM)=MAXQ(MINXG(MM),NXARRY(NN))	A	101
	IF (MINXG(MM).LE.MAX(MM)) GO TO 16	A	102
	GO TO (33,32),MM	A	103

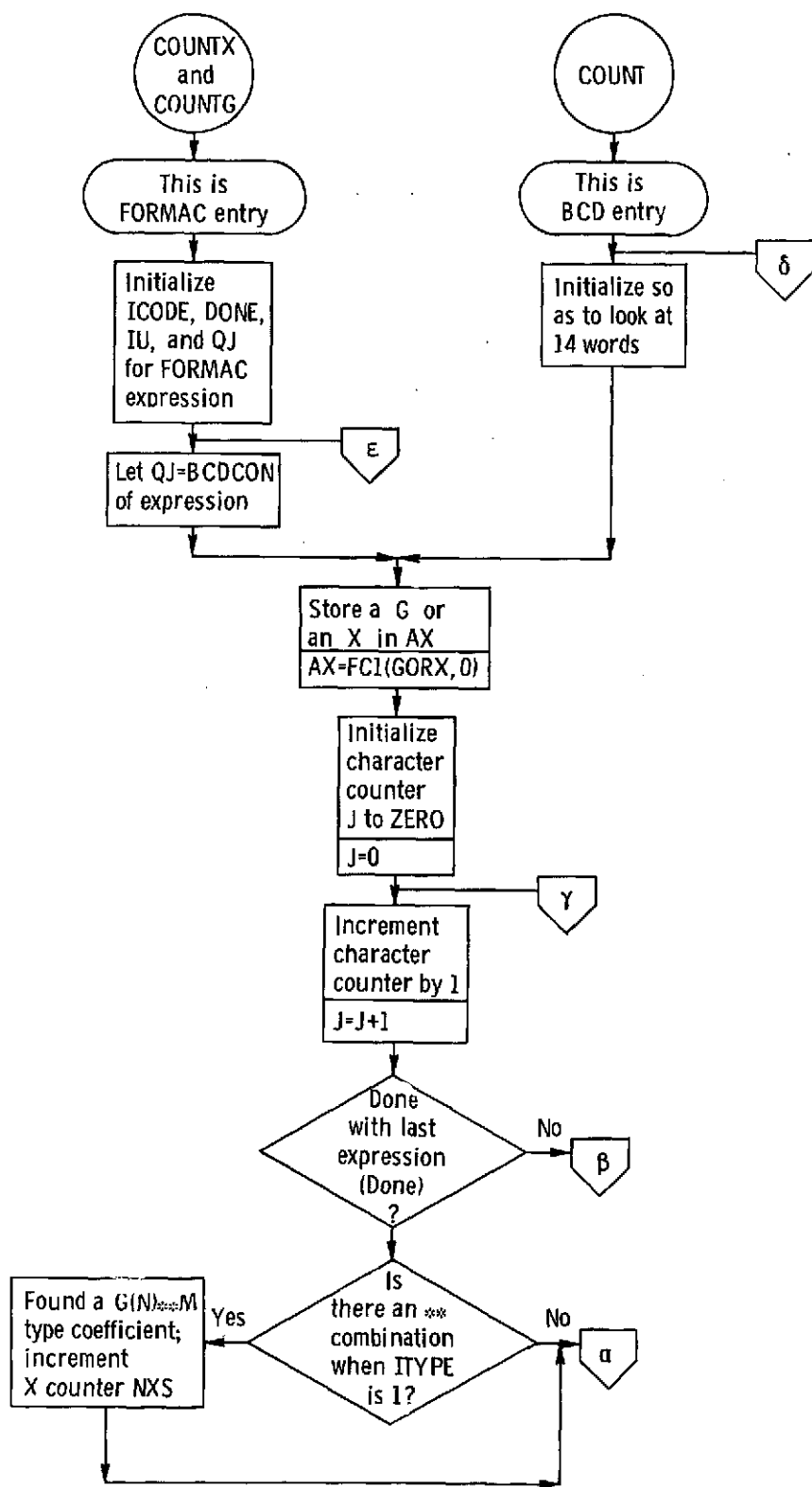
16	CONTINUE	A 104
	IF (M1.GT.MAX(1)) GO TO 34	A 105
	JJ=0	A 106
	LET EQ(M1)=ALGCON IN(1),JJ	A 107
	LET EQ(M1)=EXPAND EQ(M1)	A 108
	M1=M1+1	A 109
	IF (.NOT.DONE) GO TO 2	A 110
	M1=M1-1	A 111
	GO TO 19	A 112
	C*****	A 113
C	INTERPRET AND WRITE THE BLOCK REDUCTION ORDER	A 114
	C*****	A 115
17	NN=NN+1	A 116
	IF (NN.EQ.1) WRITE (6,44)	A 117
	WRITE (6,53) NN, (IN(L), L=K1, K2)	A 118
	DO 18 I=1,80	A 119
	CHAR=FC(IN(K1), I)	A 120
	IF (CHAR.EQ.XX) NX=NX+1	A 121
18	IF (CHAR.EQ.DR) GO TO 19	A 122
	GO TO 2	A 123
19	CONTINUE	A 124
	IF (NX.NE.M1-1) GO TO 37	A 125
	C*****	A 126
C	BACKSPACE THE INPUT UNIT	A 127
	C*****	A 128
	DO 20 L=1, NN	A 129
20	BACKSPACE 5	A 130
	WRITE (6,45) M, M1, MG	A 131
	WRITE (6,39)	A 132
	C*****	A 133
C	INITIALIZE AND SET UP EQUATIONS FOR SOLUTION	A 134
	C*****	A 135
C		A 136
	IF (JQ.EQ.2) GO TO 23	A 137
C	REPLACE THE INPUTS BY ZERO IF NOT DEN OR NUM	A 138
C		A 139
	DO 22 L=1, M1	A 140
	DO 21 J=1, IK	A 141
	LET TEST = MATCH ID, NUM, INPUT(J)	A 142
	IF (TEST) GO TO 21	A 143
	LET TEST = MATCH ID, DEN, INPUT(J)	A 144
	IF (TEST) GO TO 21	A 145
	LET EQ(L) = SUBST EQ(L), (INPUT(J), 0)	A 146
21	CONTINUE	A 147
22	CONTINUE	A 148
	C*****	A 149
23	CONTINUE	A 150
	C*****	A 151
C	REDUCE THE EQUATIONS	A 152
	C*****	A 153
24	CONTINUE	A 154
	C*****	A 155
C	GET THE REDUCTION STRING	A 156
	C*****	A 157
	CALL INSTRN (FINISH)	A 158
	LK=0	A 159
C		A 160
C	GET A VARIABLE TO ELIMINATE	A 161
C		A 162
25	CONTINUE	A 163

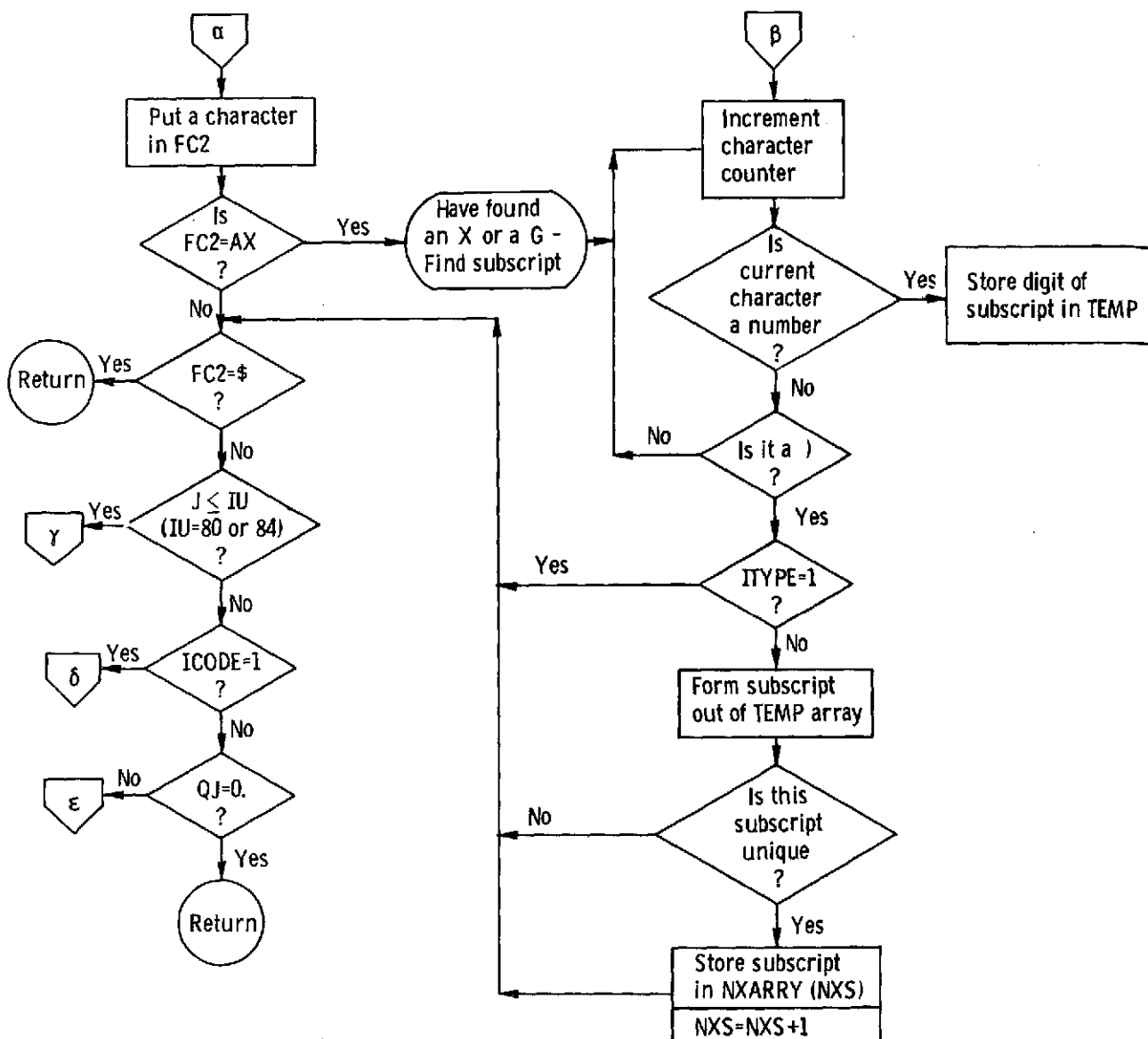
	CALL SEARCH (X,EQ,M,M1,NEQ,DONE)	A 164
	II=1	A 165
	J=NEQ(II)	A 166
	IF (J.EQ.0) GO TO 27	A 167
C		A 168
C	GET AN EQUATION CONTAINING THE VARIABLE	A 169
C		A 170
	II=II+1	A 171
	L=NEQ(II)	A 172
C		A 173
C	SOLVE THE EQUATION	A 174
C		A 175
	LET RR = EQ(L)	A 176
	LET EQ(L)=0.	A 177
	LET IT = COEFF RR,X(J)	A 178
	LET RR = EXPAND RR-IT*X(J)	A 179
C		A 180
C	ELIMINATE THE VARIABLE IN THE REMAINING EQUATIONS	A 181
C		A 182
26	II=II+1	A 183
	L=NEQ(II)	A 184
	IF (L.EQ.0) GO TO 27	A 185
	LK=LK+1	A 186
	LSAVE(LK)=L	A 187
	LET IS = COEFF EQ(L),X(J)	A 188
	LET EQ(L) = EXPAND EQ(L)-IS*X(J)	A 189
	LET EQ(L) = EXPAND IS*RR-IT*EQ(L)	A 190
	GO TO 26	A 191
27	CONTINUE	A 192
	ERASE IS,IT	A 193
	IF (.NOT.DONE) GO TO 25	A 194
	IF(FINISH) GO TO 280	
	DO 28 MM=1,LK	A 195
	NN=LK-MM+1	A 196
	L=LSAVE(NN)	A 197
C	*****	A 198
C	CREATE SOME SUPER G'S	A 199
C	*****	A 200
	CALL SUPERG (EQ(L),MG,G,X,MAX(2),M)	A 201
28	CONTINUE	A 202
	GO TO 24	
C		A 204
C		A 205
280	L=NEQ(II-1)	
C	*****	A 207
C	SOLVE FOR NUMERATOR AND DENOMINATOR	A 208
C	*****	A 209
	LET R = EQ(L)	A 210
	LET RD = COEFF R,NUM	A 211
	LET EQ(L)=EQ(L)-RD*NUM	A 212
	LET EQ(L)=EXPAND EQ(L)	
	LET RD = EXPAND -1*RD	A 214
	PUNCH 61	A 215
	CALL SOUT(RD,2,1H)	
	CALL COUNTX (NUM,1HX,NXS,NXARRY,0)	A 217
	NNUM=NXARRY(1)	A 218
	IF (JQ.EQ.3) IK=1	A 220
	DO 30 I=1,IK	A 222
	IF (JQ.EQ.3) GO TO 29	A 223
	LET DEN=INPUT(I)	A 224

29	CONTINUE	A 225
	CALL COUNTX (DEN,1HX,NXS,NXARRY,0)	A 226
	OUT(I)=NXARRY(I)	A 227
	LET RN = COEFF R,DEN	A 229
	LET EQ(L)=EQ(L)-RN*DEN	A 230
	LET EQ(L)=EXPAND EQ(L)	
C	*****	A 232
C	WRITE NUMERATOR AND DENOMINATOR	A 233
C	*****	A 234
	WRITE (6,43) NNUM,OUT(I)	A 235
	WRITE (6,50)	A 236
	PUNCH 60, 1	A 237
	CALL SOUT(RN,3,1H)	
	WRITE (6,52)	A 239
	CALL SOUT (RD,1,1H)	A 240
30	CONTINUE	A 241
	CALL COMOUT	A 242
	PUNCH 41, NNUM, IK, (OUT(I), I=1, IK)	
	ERASE RN,RD	A 243
C	*****	A 244
C	CHECK ON THE COMPLETEDNESS OF THE SOLUTION	A 245
C	*****	A 246
	LET R=0.	A 247
	DO 31 L=1,M1	A 248
	LET TEST= MATCH 1D,EQ(L),R	A 249
	IF (TEST) GO TO 31	A 250
	WRITE (6,62) L,L	A 251
	CALL SOUT (EQ(L),1,1H)	
31	CONTINUE	A 253
	GO TO 1	A 254
C	*****	A 255
C	WRITE ERROR MESSAGES	A 256
C	*****	A 257
32	CONTINUE	A 258
	WRITE (6,57) MAX(2)	A 259
	GO TO 36	A 260
33	WRITE (6,55) MAX(1)	A 261
	GO TO 36	A 262
34	WRITE (6,56) MAX(1)	A 263
	GO TO 36	A 264
35	WRITE (6,58)	A 265
36	STOP	A 266
37	WRITE (6,40)	A 267
	GO TO 36	A 268
38	CONTINUE	A 269
	WRITE (6,59)	A 270
	GO TO 36	A 271
380	WRITE(6,63)	
	STOP	
C		A 272
C		A 273
39	FORMAT (//10X,33H* * * OUTPUT FROM REDUCE II * * *)	A 274
40	FORMAT (10X,114H**ERROR** NUMBER OF VARIABLES IN REDUCTION STRING	A 275
	1IS NOT CONSISTENT WITH NUMBER OF EXPRESSIONS--EXECUTION STOPPED)	A 276
41	FORMAT (15)	A 277
42	FORMAT (13A6,A2)	A 278
43	FORMAT (1HK,10X,20HTRANSFER FUNCTION X(,13,4H)/X(,13,2H))	A 279
44	FORMAT (23HKTHE REDUCTION ORDER IS,//)	A 280
45	FORMAT (34H0THE LARGEST VARIABLE SUBSCRIPT IS,15,/,29H THE NUMBER	A 281
	1OF EXPRESSIONS IS,15,/,38H THE LARGEST FUNCTION (G) SUBSCRIPT IS,I	A 282

24)		A 283
46	FORMAT (21HKTHE SOLUTION IS FOR ,A6,14H TO THE INPUTS)	A 284
47	FORMAT (21HKTHE SOLUTION IS FOR ,A6,2HTO)	A 285
48	FORMAT (1H*,29X,A6)	A 286
49	FORMAT (30HKTHE BLOCK DIAGRAM EXPRESSIONS,//)	A 287
50	FORMAT (1HK,15X,13HTHE NUMERATOR)	A 288
51	FORMAT (5X,9A6)	A 289
52	FORMAT (1HK,15X,15HTHE DENOMINATOR)	A 290
53	FORMAT (3X,I4,2X,13A6,A2)	A 291
54	FORMAT (25H1THE BLOCK DIAGRAM INPUTS,//)	A 292
55	FORMAT (20H **ERROR** MORE THAN,I4,10H VARIABLES)	A 293
56	FORMAT (20H **ERROR** MORE THAN,I4,10H EQUATIONS)	A 294
57	FORMAT (20H **ERROR** MORE THAN,I4,10H FUNCTIONS)	A 295
58	FORMAT (43H **ERROR** MORE THAN 5 BLOCK DIAGRAM INPUTS)	A 296
59	FORMAT (59H **ERROR** MORE THAN 5 CARDS FOR A BLOCK DIAGRAM EXPRES	A 297
	1SION)	A 298
60	FORMAT (6X,3HND(,I2,2H)=)	A 299
61	FORMAT (6X,3HD0=)	A 300
62	FORMAT (//,10X,69H***** THE SOLUTION FOR THIS PROBLEM MAY BE IN ER	A 301
	1ROR BECAUSE EQUATION ,I4,31H WAS NOT ELIMINATED, EQUATION ,I4,7HI	A 302
	2S*****)	A 303
63	FORMAT (10X, 40HINVALID OPTION FOR THE SUPER G FORM CARD)	
	END	A 304-

Subroutines COUNTX, COUNTG, and COUNT

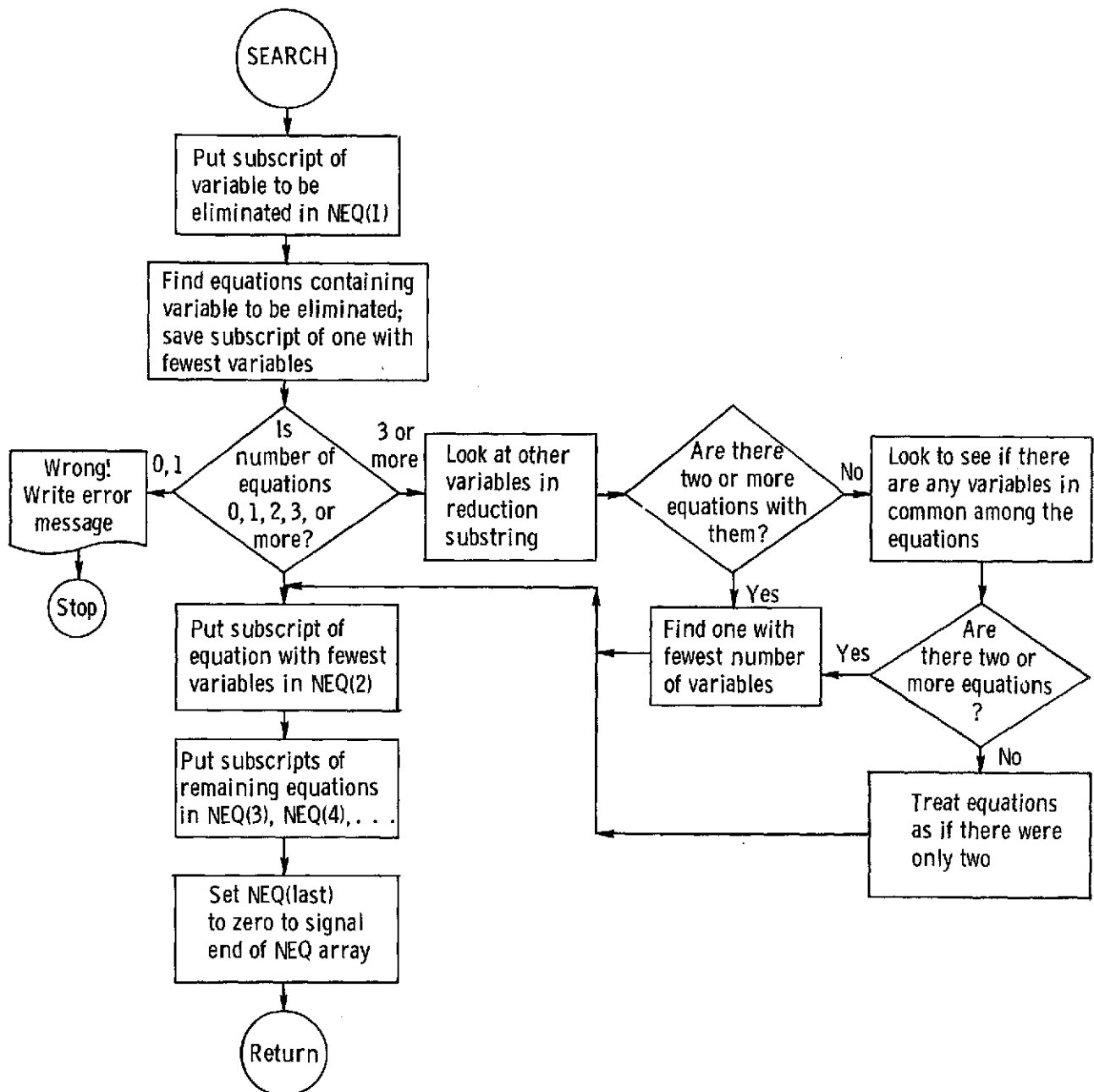




	SUBROUTINE COUNTX (EQ,GORX,NXS,NXARRY,ITYPE)	B	1
	ENTRY COUNTG(EQ,NXS,GORX,ITYPE)	B	2
	SYMMARG EQ	B	3
	DIMENSION NXARRY(1), MTEMP(4), OUT(15), TEMP(4), OTEMP(14)	B	4
	DIMENSION FC2(1)	B	5
	EQUIVALENCE (MTEMP,TEMP)	B	6
	EQUIVALENCE (OUT(2),OTEMP(1))	B	7
	LOGICAL NBR,DONE	B	8
	LOGICAL ZERO	B	9
	DATA AST,DL,RP/6H*00000,6H\$00000,6H)00000/	B	10
	NXS=0	B	11
	ICODE=0	B	12
	DONE=.TRUE.	B	13
	IU=84	B	14
	QJ=0.	B	15
1	CONTINUE	B	16
	LET QJ=BCDCON EQ,OUT,15	B	17
	GO TO 4	B	18
	ENTRY COUNT (ARRAY,GORX,NXS,NXARRY,ITYPE)	B	19
	DIMENSION ARRAY(1)	B	20
	ICODE=1	B	21
	DONE=.TRUE.	B	22
	NXS=0	B	23
	IU=80	B	24
	K=0	B	25
2	K=K+1	B	26
	K1=(K-1)*14+1	B	27
	K2=K1+13	B	28
	L=0	B	29
	DO 3 I=K1,K2	B	30
	L=L+1	B	31
3	OTEMP(L)=ARRAY(I)	B	32
4	CONTINUE	B	33
	IF (.NOT.DONE) GO TO 5	B	34
	AX=FC1(GORX,0)	B	35
	PREV1=AX	B	36
5	CONTINUE	B	37
	J=0	B	38
6	J=J+1	B	39
	IF (.NOT.DONE) GO TO 8	B	40
	FC2=FC(OTEMP,J)	B	41
	IF (ITYPE.NE.1) GO TO 7	B	42
	IF (PREV1.EQ.AST.AND.FC2.EQ.AST) NXs=NXS+1	B	43
	PREV1=FC2	B	44
7	CONTINUE	B	45
	IF (FC2.NE.AX) GO TO 14	B	46
	DONE=.FALSE.	B	47
	NXS=NXS+1	B	48
	KTR=0	B	49
	J=J+2	B	50
	IF (J.GT.IU) GO TO 15	B	51
8	CONTINUE	B	52
	DO 10 J2=J,IU	B	53
	J3=J2	B	54
	FC2=FC(OTEMP,J2)	B	55
	IF (FC2.EQ.RP) GO TO 9	B	56
	IF (.NOT.NBR(FC2,1)) GO TO 10	B	57
	KTR=KTR+1	B	58

	TEMP(KTR)=ARS(30,FC2)	B	59
	IF (J2.EQ.IU) GO TO 15	B	60
	GO TO 10	B	61
9	CONTINUE	B	62
	DONE=.TRUE.	B	63
	GO TO 11	B	64
10	CONTINUE	B	65
11	CONTINUE	B	66
	J=J3	B	67
	IF (.NOT.DONE) GO TO 15	B	68
	IF (ITYPE.EQ.1) GO TO 14	B	69
	NXARRY(NXS)=0	B	70
	ITEN=1	B	71
	DO 12 II=1,KTR	B	72
	KTR1=KTR-II+1	B	73
	NXARRY(NXS)=ITEN*MTEMP(KTR1)+NXARRY(NXS)	B	74
12	ITEN=ITEN*10	B	75
	IF (NXS.EQ.1) GO TO 14	B	76
	NXS1=NXS-1	B	77
	DO 13 II=1,NXS1	B	78
	IF (NXARRY(NXS).NE.NXARRY(II)) GO TO 13	B	79
	NXS=NXS-1	B	80
	GO TO 14	B	81
13	CONTINUE	B	82
14	CONTINUE	B	83
	DONE=.TRUE.	B	84
	IF (FC2.EQ.DL) GO TO 16	B	85
	IF (J.LT.IU) GO TO 6	B	86
15	CONTINUE	B	87
	IF (ICODE.EQ.1) GO TO 2	B	88
	IF (QJ.NE.0.) GO TO 1	B	89
16	CONTINUE	B	90
	RETURN	B	91
	END	B	92-

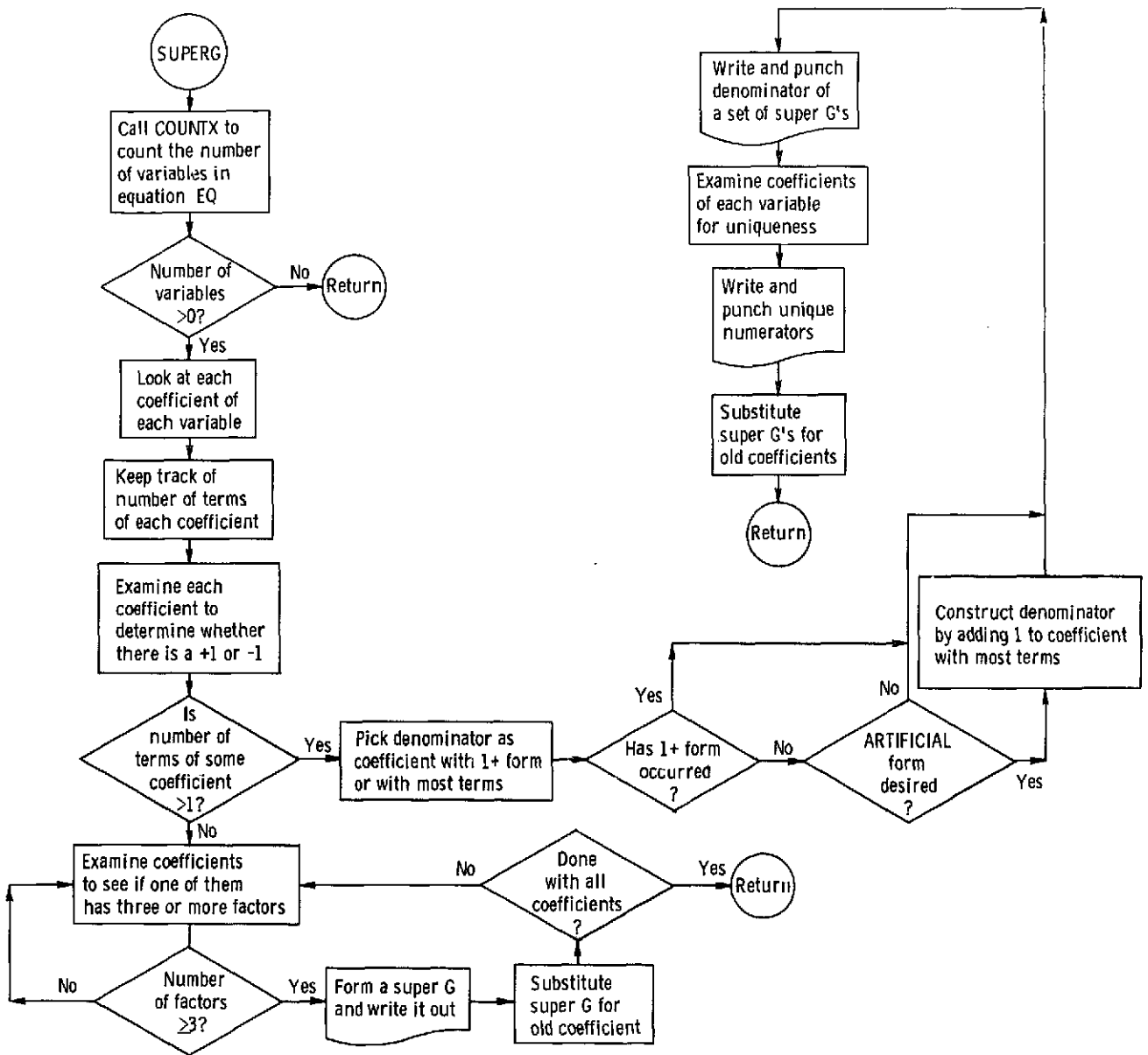
Subroutine SEARCH



SUBROUTINE SEARCH (X,EQ,MX,MEQ,NEQ,DONE)	C	1
DIMENSION NEQ(1), NARRAY(30), EQ(1)	C	2
COMMON /STRING/ IA(200),M	C	3
SYMARG X,EQ	C	4
ATOMIC X(1)	C	5
LOGICAL DONE,Q	C	6
DATA II/0/	C	7
DONE=.FALSE.	C	8
II=II+1	C	9
NEQ(1)=IA(II)	C	10
L=0	C	11
MIN=999	C	12
DO 2 I=1,MEQ	C	13
CALL COUNTX (EQ(I),IHX,NXS,NARRAY,0)	C	14
IF (NXS.EQ.0) GO TO 2	C	15
DO 1 J=1,NXS	C	16
K=NARRAY(J)	C	17
IF (K.NE.NEQ(1)) GO TO 1	C	18
L=L+1	C	19
NEQ(L+2)=I	C	20
IF (NXS.GE.MIN) GO TO 2	C	21
MIN=NXS	C	22
IMIN=I	C	23
GO TO 2	C	24
CONTINUE	C	25
CONTINUE	C	26
IMSAVE=IMIN	C	27
IF (L-2) 3,4,9	C	28
ERROR ONLY ONE EQUATION WITH VAR X(NEQ(1))	C	29
WRITE (6,17) NEQ(1)	C	30
STOP	C	31
NEQ(2)=IMIN	C	32
L1=L+1	C	33
L2=L+2	C	34
DO 6 I=3,L1	C	35
IF (NEQ(I).NE.IMIN) GO TO 6	C	36
I1=I+1	C	37
DO 5 J=I1,L2	C	38
NEQ(J-1)=NEQ(J)	C	39
GO TO 7	C	40
CONTINUE	C	41
CONTINUE	C	42
NEQ(L2)=0	C	43
IF (I1.NE.M) GO TO 8	C	44
II=0	C	45
DONE=.TRUE.	C	46
CONTINUE	C	47
RETURN	C	48
IF (II.EQ.M) GO TO 13	C	49
I1=II+1	C	50
DO 12 I=I1,M	C	51
IS=0	C	52
MIN=999	C	53
DO 11 J=1,L	C	54
K=NEQ(J+2)	C	55
CALL COUNTX (EQ(K),IHX,NXS,NARRAY,0)	C	56
DO 10 N=1,NXS	C	57
IF (NARRAY(N).NE.IA(I)) GO TO 10	C	58

	IS=IS+1	C	59
	IF (NXS.GE.MIN) GO TO 11	C	60
	MIN=NXS	C	61
	IMIN=K	C	62
	GO TO 11	C	63
10	CONTINUE	C	64
11	CONTINUE	C	65
	IF (IS.LT.2) GO TO 12	C	66
	GO TO 4	C	67
12	CONTINUE	C	68
13	L1=L-1	C	69
	DO 16 I=1,L1	C	70
	K=NEQ(I+2)	C	71
	CALL COUNTX (EQ(K),1HX,NXS,NARRAY,0)	C	72
	J=I+1	C	73
	DO 15 N=J,L	C	74
	K1=NEQ(N+2)	C	75
	DO 14 N1=1,NXS	C	76
	N2=NARRAY(N1)	C	77
	IF (N2.EQ.NEQ(1)) GO TO 14	C	78
	LET Q= FIND EQ(K1),APP,ALL,(X(N2))	C	79
	IF (.NOT.Q) GO TO 14	C	80
	CALL COUNTG (EQ(K1),NX1,1HX,1)	C	81
	IMIN=K	C	82
	IF (NX1.LT.NXS) IMIN=K1	C	83
	GO TO 4	C	84
14	CONTINUE	C	85
15	CONTINUE	C	86
16	CONTINUE	C	87
	IMIN=IMSAVE	C	88
	GO TO 4	C	89
C		C	90
17	FORMAT (10X,36H**** ONLY ONE EQUATION CONTAINING X(,14,6H) ****)	C	91
	END	C	92-

Subroutine SUPERG

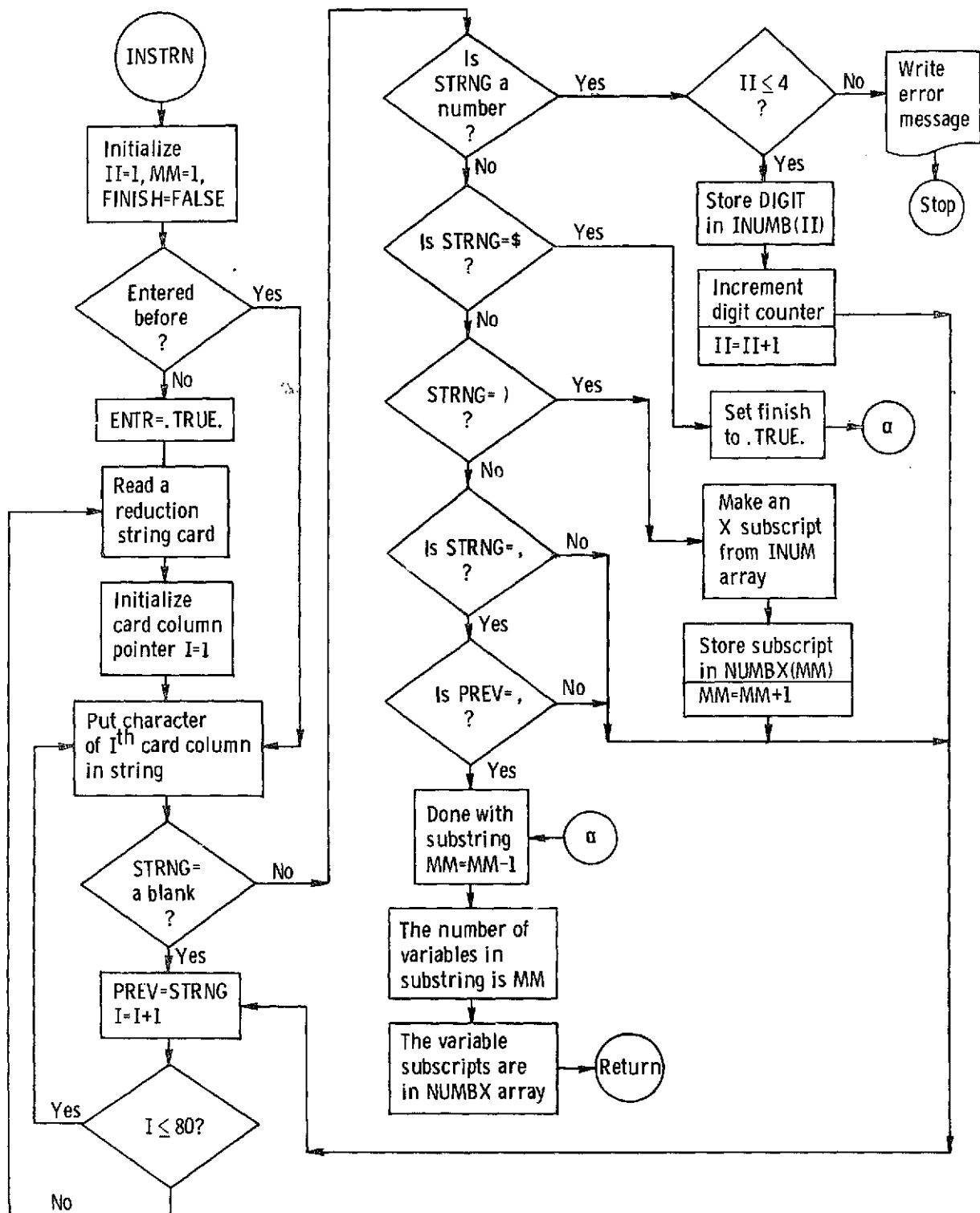


SUBROUTINE SUPERG (EQ,MG,G,X,MAXG,MX)	D	1
SYMARG EQ,X,G	D	2
ATOMIC X(1),G(1)	D	3
DIMENSION NARRAY(50)	D	4
DIMENSION ISAME(50)	D	5
COMMON /TRANS/ ARTIF		
LOGICAL TRUTH	D	6
LOGICAL FIRST	D	7
LOGICAL PRESG	D	8
LOGICAL YES	D	9
LOGICAL ARTIF		
DATA FIRST/.TRUE./	D	10
DATA MD/0/	D	11
IF (MG.GT.MAXG) RETURN	D	12
LET EQSAVE=EQ	D	13
MAX=-1	D	14
COUNT THE NUMBER OF X'S IN EQUATION EQ	D	15
CALL COUNTX (EQ,1HX,NXS,NARRAY,0)	D	16
IF (NXS.EQ.0) GO TO 19	D	17
DO 5 K=1,NXS	D	18
I=NARRAY(K)	D	19
LET RR=COEFF EQ,X(I)	D	20
LET IQ=CENSUS RR,TERM	D	21
LET YES= FIND RR,APP,ALL,(1.)	D	22
IF (YES) GO TO 1	D	23
LET YES= FIND RR,APP,ALL,(-1.)	D	24
IF (YES) GO TO 1	D	25
IQ=-IQ	D	25
CONTINUE	D	27
IF (IABS(IQ).EQ.1) GO TO 5	D	28
IF (MAX.GT.0.AND.IQ.GT.0) GO TO 2	D	29
IF (MAX.LT.0.AND.IQ.GT.0) GO TO 3	D	30
IF (MAX.LT.0.AND.IQ.LT.0) GO TO 4	D	31
GO TO 5	D	32
IF (IQ.LT.MAX) GO TO 5	D	33
MAX=IQ	D	34
L=I	D	35
GO TO 5	D	36
IF (IQ.LT.MAX) GO TO 3	D	37
CONTINUE	D	38
IF (MAX.NE.-1) GO TO 7	D	39
DO 6 K=1,NXS	D	40
I=NARRAY(K)	D	41
LET RR=COEFF EQ,X(I)	D	42
CALL COUNTG (RR,NGS,1HG,1)	D	43
IF (NGS.LT.3) GO TO 6	D	44
FORM A NEW SUPER G	D	45
MG=MG+1	D	46
IF (MG.GT.MAXG) GO TO 20	D	47
L=1	D	48
LET EQ = EQ - RR * X(L)	D	49
LET EQ=EXPAND EQ+ G(MG)*X(L)	D	50
WRITE (6,24)	D	51
WRITE (6,21) MG	D	52
PUNCH 21, MG		
CALL SOUT(RR,3,1H+)		
CONTINUE	D	54
GO TO 19	D	55

C	DIVISION SEARCH AND CONSTRUCTION OF SUPER G'S	D	56
7	CONTINUE	D	57
	PRESG=.FALSE.	D	58
	LET RR=COEFF EQ,X(L)	D	59
	LET EQ=EQ-RR*X(L)	D	60
	LET DD=1.	D	61
	IF (.NOT.ARTIF.OR.MAX.GT.0) GO TO 8	D	62
	LET SS=RR	D	63
	LET RR=RR+1.	D	64
	PRESG=.TRUE.	D	65
8	CONTINUE	D	66
	MD=MD+1	D	67
	WRITE (6,24)	D	68
	PUNCH 22,MD		
	WRITE (6,22) MD	D	69
	CALL SOUT(RR,3,1H+)		
	IF (.NOT.PRESG) GO TO 9		
	MG=MG+1		
	IF (MG.GT.MAXG) GO TO 20		
	WRITE(6,24)		
	WRITE(6,21) MG		
	CALL SOUT(SS,1,1H+)		
	LET DD=G(MG)		
	PUNCH 27,MG,MD,MD		
	WRITE(6,23) MG,MG,MD		
9	CONTINUE	D	72
	KTR=0	D	73
	PRESG=.FALSE.	D	74
	LET EQ=EXPAND EQ+DD*X(L)	D	75
	KTR1=KTR	D	76
	DO 18 I=1,NXS	D	77
	N=NARRAY(I)	D	78
	IF (N.EQ.L) GO TO 18	D	79
	IF (KTR.EQ.0) GO TO 11	D	80
	DO 10 J=1,KTR	D	81
10	IF (N.EQ.IABS(ISAME(J))) GO TO 18	D	82
11	KTR1=KTR1+1	D	83
	ISAME(KTR1)=N	D	84
	LET SS=COEFF EQ,X(N)	D	85
	DO 15 J=1,NXS	D	86
	K=NARRAY(J)	D	87
	IF (K.EQ.L.OR.K.EQ.N) GO TO 15	D	88
	IF (KTR.EQ.0) GO TO 13	D	89
	DO 12 KK=1,KTR	D	90
12	IF (K.EQ.IABS(ISAME(KK))) GO TO 15	D	91
13	CONTINUE	D	92
	LET TT= COEFF EQ,X(K)	D	93
	IS=1	D	94
	LET TRUTH=MATCH ID,SS,TT	D	95
	IF (TRUTH) GO TO 14	D	96
	LET TRUTH= MATCH ID,SS,-TT	D	97
	IF (.NOT.TRUTH) GO TO 15	D	98
	IS=-1	D	99
14	KTR1=KTR1+1	D	100
	ISAME(KTR1)=K*IS	D	101
15	CONTINUE	D	102
16	CONTINUE	D	103
	MG=MG+1	D	104
	IF (MG.GT.MAXG) GO TO 20	D	105
	WRITE (6,24)	D	106

	WRITE (6,21) MG	D 107
	PUNCH 21, MG	
	CALL SQUT(SS,3,1H+)	
	WRITE (6,23) MG, MG, MD	D 109
	PUNCH 23, MG, MG, MD	
	LET DD=G(MG)	D 110
	L1=KTR+1	D 112
	DO 17 J=L1, KTR1	D 113
	M=IABS(ISAME(J))	D 114
	S=ISIGN(1, ISAME(J))	D 115
	LET EQ=EQ-S*SS*X(M)	D 116
	LET EQ= EXPAND EQ+S*DD*X(M)	D 117
17	CONTINUE	D 118
	ERASE DD, TT, SS	D 119
	KTR=KTR1	D 120
	IF (KTR.EQ.NXS) GO TO 19	D 121
18	CONTINUE	D 122
19	CONTINUE	D 123
	ERASE RR	D 124
	RETURN	D 125
20	WRITE (6,26)	D 126
	LET EQ=EQSAVE	D 127
	RETURN	D 128
	ENTRY COMOUT	D 129
	MD=MAX0(MD, 1)	
	PUNCH 25, MG, MD	D 130
	RETURN	D 131
C		D 132
C		D 133
21	FORMAT (7X, 2HG(, I4, 2H)=)	D 134
22	FORMAT (7X, 6HDENOM(, I4, 2H)=)	
23	FORMAT (7X, 2HG(, I4, 4H)=G(, I4, 8H)/DENOM(, I4, 1H))	
24	FORMAT (1HK)	D 137
25	FORMAT (6X, 20HCOMPLEX G(, I4, 8H), DENOM(, I4, 1H))	D 138
26	FORMAT (105HK**** WARNING THE NUMBER OF SUPER FUNCTIONS (G'S) EXCEEDS THE MAXIMUM NUMBER OF FUNCTIONS (G'S) PERMITTED, /, 10X, 43HTHEREFORE SUBSTITUTION PROCESS STOPPED ****)	D 139
		D 140
27	FORMAT(7X, 2HG(, I4, 9H)=(DENOM(, I4, 12H)-1.)/DENOM(, I4, 1H))	D 141
	END	D 142-

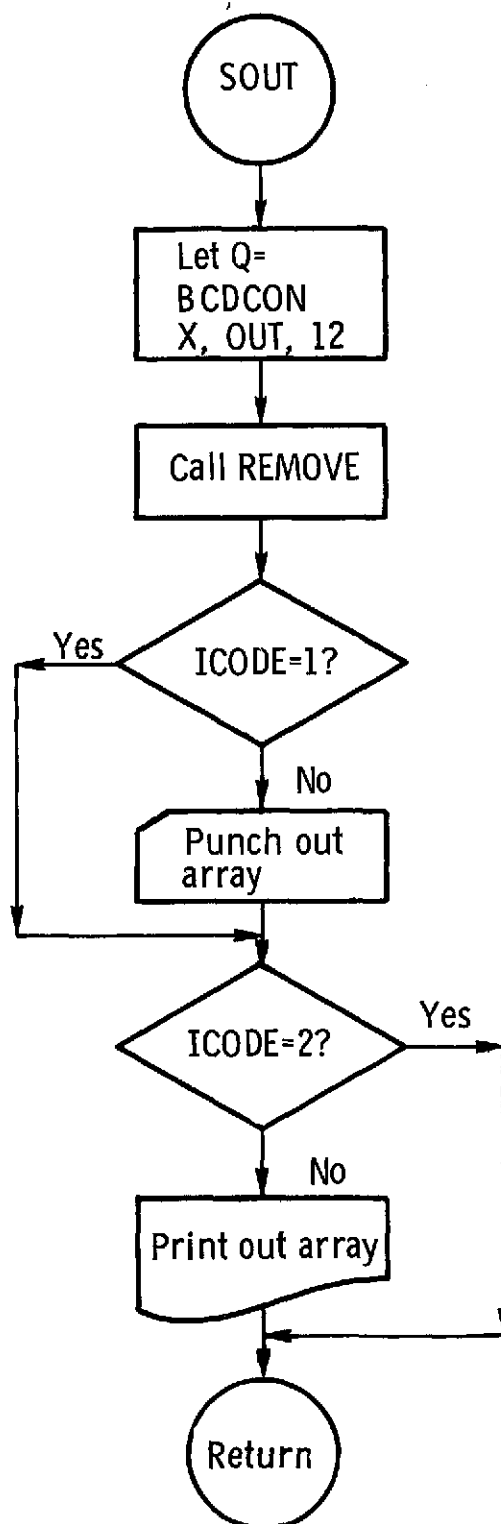
Subroutine INSTRN



	SUBROUTINE INSTRN (FINISH)	E	1
	COMMON /STRING/ NUMBX(200),MM	E	2
	DIMENSION ASTRNG(14), INUM(4)	E	3
	LOGICAL ENTR	E	4
	DATA ENTR/.FALSE./	E	5
	LOGICAL FINISH	E	8
	DATA BLANK,DOLRSN,RIGHTPR,COMMA/1H ,1H\$,1H),1H,/	E	6
	DATA INUM/4*0/	E	7
	DATA MBL/0006060606060/		
	FINISH=.FALSE.	E	9
	II=1	E	10
	MM=1	E	11
	IF (ENTR) GO TO 2	E	12
	ENTR=.TRUE.	E	13
1	READ (5,10) (ASTRNG(J),J=1,14)	E	14
	I=1	E	15
2	CONTINUE	E	16
	STRNG=OR(FC(ASTRNG,I),MBL)		
	IF (STRNG.EQ.BLANK) GO TO 8	E	17
C	NOT A BLANK,SEARCH FOR A NUMBER	E	18
	NUMBER=LGR(30, STRNG)	E	19
	IF (NUMBER.LT.0.OR.NUMBER.GT.9) GO TO 3	E	20
C	FOUND ONE OF THE INTEGERS N OF THE X SUBSCRIPT X(NNNN)	E	21
	IF (II.GT.4) GO TO 9	E	22
	INUM(II)=NUMBER	E	23
	II=II+1	E	24
	GO TO 8	E	25
3	IF (STRNG.NE.DOLRSN) GO TO 4	E	26
C	DONE WITH ALL INPUT STRINGS,TERMINATE BUFFERS AND RETURN	E	27
	FINISH=.TRUE.	E	28
	GO TO 7	E	29
4	IF (STRNG .NE.RIGHTPR) GO TO 6	E	30
C	TERMINATE NUMBER BUFFER AND CONSTRUCT NNNN OF X(NNNN)	E	31
	II=II-1	E	32
	ISUM=0	E	33
	ITEN=1		
	DO 5 J=1,II	E	34
	L=II-J+1	E	35
	ISUM=ISUM+INUM(L)*ITEN	E	36
	ITEN=ITEN*10		
	INUM(L)=0	E	37
5	CONTINUE	E	38
	IF (ISUM.GT.600) GO TO 9		
	NUMBX(MM)=ISUM	E	39
	MM=MM+1	E	40
	II=1	E	41
	GO TO 8	E	42
6	IF (STRNG .NE.COMMA) GO TO 8	E	43
	IF (PREV.NE.COMMA) GO TO 8	E	44
C	TERMINATE CURRENT STRING BUFFER	E	45
7	CONTINUE	E	46
	MM=MM-1	E	47
	I=I+1	E	48
	RETURN	E	49
8	PREV= STRNG	E	50
	I=I+1	E	51
	IF (I.LE.80) GO TO 2	E	52
	GO TO 1	E	53

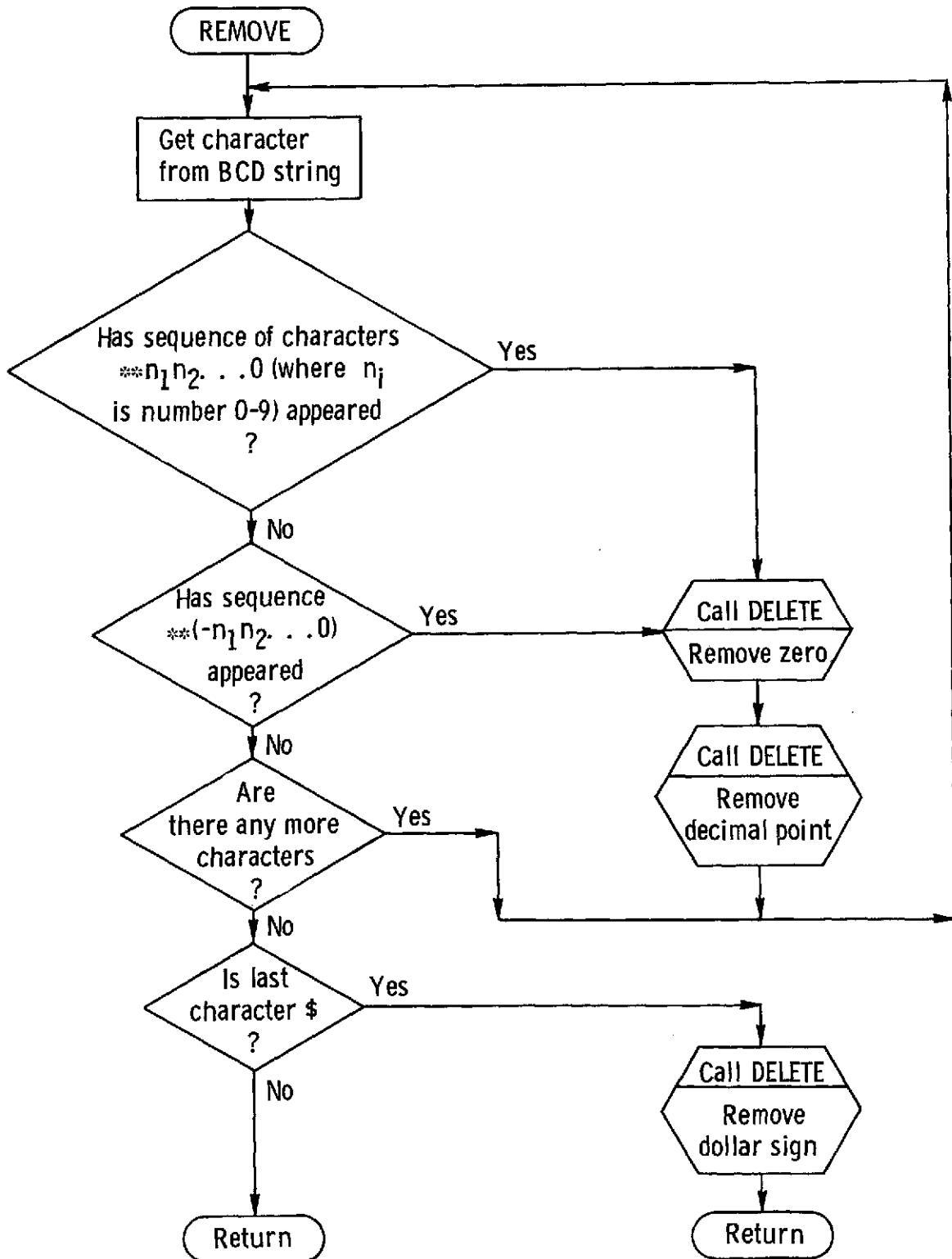
C	WRITE ERROR MESSAGES	E	54
9	CONTINUE	E	55
	WRITE (6,11)	E	56
	STOP	E	57
C		E	58
10	FORMAT (13A6,A2)	E	60
11	FORMAT (10X,45H SUBSCRIPT TOO LARGE FOR THIS VERSION)	E	61
	END	E	62-

Subroutine SOUT



	SUBROUTINE SUB1 (A, ICODE, PRNTP)		
	DIMENSION OUT(12)	F	2
	SYNARG X	F	3
	DATA BLANK/1H /		
C		F	4
C	ICODE=1 PRINT	F	5
C	ICODE=2 PUNCH	F	6
C	ICODE=3 PRINT AND PUNCH	F	7
C		F	8
	C=PRNTP		
1	CONTINUE	F	9
	LET Q= BCDCON X,OUT,12	F	10
	CALL REMOVE (OUT)	F	11
	IF (ICODE.EQ.1) GO TO 2	F	12
	PUNCH 4, (OUT(I),I=2,12)	F	13
	IF (ICODE.EQ.2) GO TO 3	F	14
2	WRITE(6,5) C,(OUT(I),I=2,12)		
	C=BLANK		
3	IF (Q.NE.0.) GO TO 1	F	16
	RETURN	F	17
C		F	18
4	FORMAT (5X,1H*,11A6)	F	19
5	FORMAT(A1,19X,11A6)		
	END	F	21-

Subroutine REMOVE



	SUBROUTINE REMOVE (X)	1
	INTEGER X(1)	2
	LOGICAL NBR	3
	DATA AAST,AMINUS,AE,ALP,ARP,ADP,AZERO/6H*00000,6H-00000,6HE00000,6	4
	1H(00000,6H)00000,6H.00000,6H000000/,MSW/1/	5
	DATA ADLR,K/6H\$00000,1/	6
	LMAX=X(1)+6	7
	L=7	8
1	GO TO (2,3,4,6),K	9
2	IF (FC(X,L).NE.AAST) GO TO 11	10
	GO TO 12	11
3	IF (FC(X,L).NE.AAST) GO TO 11	12
	GO TO 13	13
4	IF (FC(X,L).EQ.ALP) GO TO 14	14
5	IF (NBR(X,L)) GO TO 7	15
	GO TO 11	16
6	IF (FC(X,L).NE.AMINUS) GO TO 11	17
	L=L+1	18
	MSW=2	19
	GO TO 5	20
7	L=L+1	21
	IF (NBR(X,L)) GO TO 7	22
	IF (FC(X,L).NE.ADP) GO TO 11	23
	L=L+1	24
	IF (FC(X,L).NE.AZERO) GO TO 11	25
	L=L+1	26
	GO TO (8,9),MSW	27
8	IF (L.EQ.LMAX+1) GO TO 10	28
	IF (NBR(X,L).OR.FC(X,L).EQ.AE) GO TO 11	29
	GO TO 10	30
9	MSW=1	31
	IF (L.EQ.LMAX+1) GO TO 10	32
	IF (FC(X,L).NE.ARP) GO TO 11	33
10	CALL DELETE (X,L-1)	34
	CALL DELETE (X,L-2)	35
11	K=1	36
	GO TO 15	37
12	K=2	38
	GO TO 15	39
13	K=3	40
	GO TO 15	41
14	K=4	42
15	L=L+1	43
	IF (L.LE.LMAX) GO TO 1	44
	IF (FC(X,LMAX).NE.ADLR) RETURN	45
	K=1	46
	CALL DELETE (X,LMAX)	47
	RETURN	48
	END	49-

FUNCTION FC (X,L)	1
DIMENSION X(1)	2
DATA MASK/07700000000000/	3
LM1=L-1	4
IW=LM1/6+1	5
FC=AND(ALS(6*MOD(LM1,6),X(IW)),MASK)	6
RETURN	7
ENTRY FC1(X,L)	8
FC=AND(ALS(L,X),MASK)	9
RETURN	10
END	11-

SUBROUTINE DELETE (X,L)	1
DIMENSION X(L), ZERO(6), BLANK(6)	2
DATA ZERO/000777777777,077007777777,077770077777,077777007777,	3
1077777770077,077777777700/,BLANK/060000000000,000600000000,000	4
20060000000,000000060000,000000006000,000000000060/	5
LM1=L-1	6
IW=LM1/6+1	7
IP=MOD(LM1,6)+1	8
X(IW)=OR(AND(X(IW),ZERO(IP)),BLANK(IP))	9
RETURN	10
END	11-

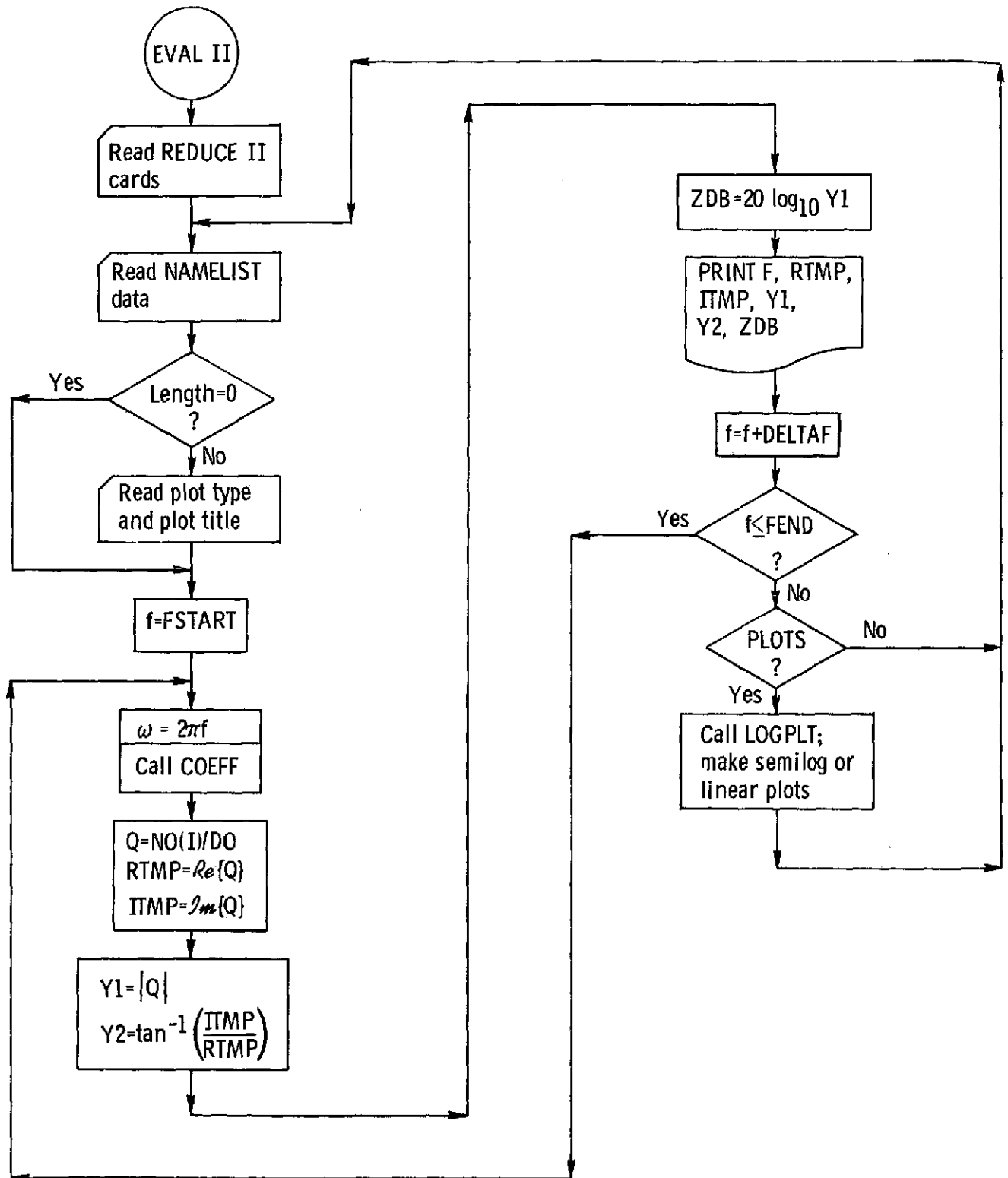
LOGICAL FUNCTION NBR(X,L)	1
REAL X(I)	2
N=LGR(30,FC(X,L))	3
NBR=.FALSE.	4
IF ((N.GE.0).AND.(N.LE.9)) NBR=.TRUE.	5
RETURN	6
END	7-

```

SUBROUTINE COS(X)
ENTRY SIN(X)
ENTRY TANH(X)
ENTRY ATAN(X)
ENTRY ALOG(X)
ENTRY DUMP(X)
ENTRY PDUMP(X)
ENTRY FMCDIF(X)
ENTRY EXPDMP(X)
ENTRY FMCDMP(X)
STOP
END

```

Evaluation Program - EVAL II



REAL ITMP,K,LENGTH	1
INTEGER PLTTY	2
COMPLEX NO,DO,Q	3
COMMON /ARRAY/ BA(14),NNUM,NN	4
COMMON /CEVAL/ T(10),Z(10),WN(10),K(10),NEXP,NSIN,NCOS,NSINH,NCOSH	5
1,NSQRT	6
COMMON /OMEGA/ W,DO,NO(5)	7
COMMON /NONLIN/ EXPA(5),SINA(5),COSA(5),EXPB(5),SINB(5),COSB(5),EX	8
IPC(5),SINC(5),COSC(5),EXPD(5),SIND(5),COSD(5),SINHA(5),COSHA(5),SQ	9
2RTA(5),SINH8(5),COSHB(5),SQRTB(5),SINHC(5),COSHC(5),SQRTC(5),SINH	10
2(5),COSHD(5)	11
COMMON /CLPLOT/ XPEN,YPEN,NX,NY,IPEN,XLABEL(10),YLABEL(10)	12
DIMENSION Y1(604,5), Y2(604,5), KKK(6), P(14), X(604)	13
DIMENSION NDEN(5)	14
DATA LENGTH/0./	15
DATA LOGPLO/6HLOGPLO/	16
DATA CONV/57.2957795/	17
DATA YDB/3HDB./	18
DATA (KKK(J),J=2,6),P(1), (P(L),L=3,14)/50,1,1,0,601,3.,2*0.,10.,2*	19
10.,10.,5*0.,90./	20
DATA TWOPI/6.2831853/	21
DATA XLAB/1HF/	22
DATA YLAB/3HABS/	23
DATA ZLAB/SHANGLE/	24
DATA NK,NWN,NT,NZ/4*0/	25
NAMelist /INPUT/ NEXP,NSIN,NCOS,EXPA,SINA,COSA,EXPB,SINB,COSB,EXPC	26
1,SINC,COSC,EXPD,SIND,COSD,NSINH,NCOSH,NSQRT,SINHA,COSHA,SQRTA,SINH	27
2B,COSHB,SQRTB,SINHC,COSHC,SQRTC,SINH8,COSHD,NK,K,NT,T,NZ,Z,NWN,WN,	28
2FSTART,FEND,DELTA F,LENGTH	29
C READ THE NUMERATOR AND DENOMINATOR INFORMATION SUPPLIED BY REDUCE II	
READ (5,12) NNUM,IK,(NDEN(I),I=1,IK)	30
C READ THE NAMELIST INPUT. NOTE THAT THE PROGRAM ALWAYS RETURNS HERE	
1 READ (5,INPUT)	31
WRITE (6,18)	32
IUPPER=1	33
C CHECK FOR A PLOTTING REQUEST.	
IF (LENGTH.EQ.0.) GO TO 2	34
IUPPER=2	35
C PLOTTING TO BE DONE. READ IN PLOT TITLE AND PLOT TYPE	
READ (5,30) BA	36
WRITE (6,31) BA	37
READ (5,30) PLTTY	38
2 CONTINUE	39
C EXAMINE THE VARIOUS NAMELIST VARIABLE TO GET THE INPUT IDENTIFIED,	
C ON THE PROGRAM OUTPUT LISTING	
IF (NEXP.NE.0) WRITE (6,19) (I,EXPA(I),EXPB(I),EXPC(I),EXPD(I),I=1	40
1,NEXP)	41
IF (NSIN.NE.0) WRITE (6,20) (I,SINA(I),SINB(I),SINC(I),SIND(I),I=1	42
1,NSIN)	43
IF (NCOS.NE.0) WRITE (6,21) (I,COSA(I),COSB(I),COSC(I),COSD(I),I=1	44
1,NCOS)	45
IF (NSINH.NE.0) WRITE (6,22) (I,SINHA(I),SINH8(I),SINHC(I),SINH8(I	46
1),I=1,NSINH)	47
IF (NCOSH.NE.0) WRITE (6,23) (I,COSHA(I),COSHB(I),COSHC(I),COSHD(I	48
1),I=1,NCOSH)	49
IF (NSQRT.NE.0) WRITE (6,24) (I,SQRTA(I),SQRTB(I),SQRTC(I),I=1,NSQ	50
1RT)	51
IF (NK.NE.0) WRITE (6,25) (I,K(I),I=1,NK)	52
IF (NT.NE.0) WRITE (6,26) (I,T(I),I=1,NT)	53

	IF (NZ.NE.0) WRITE (6,27) (I,Z(I),I=1,NZ)	54
	IF (NWN.NE.0) WRITE (6,28) (I,WN(I),I=1,NWN)	55
	WRITE (6,13) (I,NNU,NDEN(I),I=1,IK)	56
	WRITE (6,29) FSTART,FEND,DELTA F	57
	WRITE (6,14)	58
	IF (DELTA F.EQ.0.0) GO TO 1	59
C	START THE MAIN PROGRAM LOOP. IUPPER =1 IF THERE ARE NO PLOTS	
C	2 IF PLOTS ARE TO BE MADE	
	DO 8 NTYPE=1,IUPPER	60
	IF (NTYPE.EQ.2) GO TO 3	61
	DF=DELTA F	62
	GO TO 4	63
3	DF=(FEND-FSTART)/600.	64
4	J=0	65
	F=FSTART	66
5	W=TWOPI*F	67
	IF (J.GE.604) GO TO 8	68
	J=J+1	69
C	THE CALL TO COEFF EVALUATES THE TRANSFER FUNCTION AT S=I*W	
	CALL COEFF	70
	X(J)=F	71
	DO 7 I=1,IK	72
	Q=N0(I)/DO	73
	RTMP=REAL(Q)	74
	ITMP=AIMAG(Q)	75
	Y1(J,I)=0.	76
	Y2(J,I)=0.	77
	ZDB=0.	78
	IF (RTMP.EQ.0..AND.ITMP.EQ.0.) GO TO 6	79
	Y1(J,I)=CABS(Q)	80
	ZDB=20.*ALOG10(Y1(J,I))	81
	Y2(J,I)=ATAN2(ITMP,RTMP)*CONVT	82
6	CONTINUE	83
	IF (PLTTYP.EQ.LOGPLO.AND.NTYPE.EQ.2) Y1(J,I)=ZDB	84
	IF (NTYPE.EQ.2) GO TO 7	85
	IF (I.EQ.1.AND.IK.GT.1) WRITE (6,15)	86
	WRITE (6,16) I,F,RTMP,ITMP,Y1(J,I),Y2(J,I),ZDB	87
7	CONTINUE	88
	F=F+DF	89
	IF (F.LE.FEND) GO TO 5	90
8	CONTINUE	91
C	CONTINUE ON WITH THE PLOTTING IF IT IS CALLED FOR	
	IF (LENGTH.EQ.0.0) GO TO 1	92
	KKK(6)=J	93
	P(2)=AINT(LENGTH+.5)	94
	NX=-1	95
	XLABEL(1)=XLAB	96
	DO 11 I=1,IK	97
	P(6)=0.	98
	P(7)=0.	99
	NY=3	100
	IF (PLTTYP.EQ.LOGPLO) GO TO 9	101
	KKK(1)=4	102
	YLABEL(1)=YLAB	103
	GO TO 10	104
9	CONTINUE	105
	KKK(1)=2	106
	IF (I.GT.1) KKK(1)=-2	107
	YLABEL(1)=YDB	108
10	CONTINUE	109

	NN=NDEN(I)	110
C	MAKE THE AMPLITUDE RATIO PLOT	111
	CALL LOGPLT (X,Y1(1,I),KKK,P)	112
	WRITE (6,17)	113
	IF (PLTTY.EQ.LOGPLO) KKK(1)=-2	114
	P(6)=-200.00	115
	P(7)=200.00	116
	YLABEL(1)=ZLAB	117
	NY=5	
C	MAKE THE PHASE ANGLE PLOT	118
	CALL LOGPLT (X,Y2(1,I),KKK,P)	119
	WRITE (6,17)	120
11	CONTINUE	121
	GO TO 1	122
C		123
C		124
12	FORMAT (15)	125
12	FORMAT (50X,27HNUMBER TRANSFER FUNCTION,(/,52X,12,9X,2HX(,12,4H	126
	1)/X(,12,1H)))	127
14	FORMAT (//,3X,6HNUMBER,5X,9HFREQUENCY,13X,9HREAL PART,9X,14HIMAGIN	128
	ARY PART,6X,14HABSOLUTE VALUE,6X,11HPHASE ANGLE,9X,16HAMPLITUDE IN	129
	2 DB.)	130
15	FORMAT (1HK)	131
16	FORMAT (15,6F20.6)	132
17	FORMAT (10X,9HPLOT MADE)	133
18	FORMAT (1H1,//,36H FORTRAN EVALUATION OF FORMAC OUTPUT)	134
19	FORMAT (1H0,3X,1HI,5X,5HEXPA ,10X,5HEXPB ,10X,5HEXPC ,10X,5HEXPD ,	135
	1/,15,4E15.5))	136
20	FORMAT (1H0,3X,1HI,5X,5HSINA ,10X,5HSINB ,10X,5HSINC ,10X,5HSIND ,	137
	1/,15,4E15.5))	138
21	FORMAT (1H0,3X,1HI,5X,5HCOSA ,10X,5HCOSB ,10X,5HCOSC ,10X,5HCOSD ,	139
	1/,15,4E15.5))	140
22	FORMAT (1H0,3X,1HI,5X,5HSINHA,10X,5HSINHB,10X,5HSINHC,10X,5HSINHD,	141
	1/,15,4E15.5))	142
23	FORMAT (1H0,3X,1HI,5X,5HCOSHA,10X,5HCOSHB,10X,5HCOSHC,10X,5HCOSHD,	143
	1/,15,4E15.5))	144
24	FORMAT (1H0,3X,1HI,5X,5HSQRTA,10X,5HSQRTB,10X,5HSQRTC,/,15,3E15.5	145
	1))	146
25	FORMAT (1H0,3X,1HI,5X,1HK,/,15,E15.5))	147
26	FORMAT (1H0,3X,1HI,5X,1HT,/,15,E15.5))	148
27	FORMAT (1H0,3X,1HI,5X,1HZ,/,15,E15.5))	149
28	FORMAT (1H0,3X,1HI,5X,2HWN,/,15,E15.5))	150
29	FORMAT (//,8H FSTART=F15.5,5X,5HFEND=F15.5,5X,7HDELTA F=F15.5)	151
30	FORMAT (13A6,A2)	152
31	FORMAT (34HOCALCOMP PLOTS HAVE BEEN REQUESTED,/,5X,13A6,A2)	153-
	END	

Subroutine COEFF

	1
1	2
2	3
3	4
4	5
5	6
6	7
7	8
8	9
9	10
10	11
11	12
12	13
13	14
14	15
15	16
16	17
17	18
18	19
19	20
20	21
21	22
22	23
23	24
24	25
25	26
26	27
27	28
28	29
29	30
30	31
31	32
32	33
33	34
34	35
35	36
36	37
37	38
38	39
39	40-

```

SUBROUTINE COEFF
C      PUT REDUCE II OUTPUT IN THIS SUBROUTINE
      REAL K
C*****
C* * THE COMPLEX STATEMENT PUNCHED BY REDUCE II FOLLOWS THIS CARD * * *
C*****
      LOGICAL DONE
      DATA DONE/.FALSE./
      COMPLEX NO,DO,EXPF, SINF, COSF, SINHF, COSHF, SQRTF, S
      COMPLEX EXPF(5), SINF(5), COSF(5), SINHF(5), COSHF(5), SQRTF(5)
      COMMON /CEVAL/ T(10), Z(10), WN(10), K(10), NEXP, NSIN, NCOS, NSINH, NCOSH
1, NSQRT
      COMMON /OMEGA/ W, DO, NO(5)
      IF (NEXP.EQ.0) GO TO 2
      DO 1 I=1, NEXP
1      EXPF(I)=EXPF(I)
2      IF (NSIN.EQ.0) GO TO 4
      DO 3 I=1, NSIN
3      SINF(I)=SINF(I)
4      IF (NCOS.EQ.0) GO TO 6
      DO 5 I=1, NCOS
5      COSF(I)=COSF(I)
6      IF (NSINH.EQ.0) GO TO 8
      DO 7 I=1, NSINH
7      SINHF(I)=SINHF(I)
8      IF (NCOSH.EQ.0) GO TO 10
      DO 9 I=1, NCOSH
9      COSHF(I)=COSHF(I)
10     IF (NSQRT.EQ.0) GO TO 12
      DO 11 I=1, NSQRT
11     SQRTF(I)=SQRTF(I)
12     CONTINUE
      S=CMPLX(0.0, W)
C*****
C* * * THE USER'S FUNCTIONS (G(S)'S) ARE INSERTED AFTER THESE CARDS * *
C* * * THE G'S MUST BE FOLLOWED BY THE SUPER G'S, THE NUMERATOR, AND * *
C* * * DENOMINATOR CARDS REDUCE II PUNCHED * * *
C*****
      RETURN
      END

```

Function EXPFX

COMPLEX FUNCTION EXPFX(I)	1
COMPLEX X,Y	2
COMMON /OMEGA/ W,DO,NO(5)	3
COMMON /NONLIN/ EXPA(5),SINA(5),COSA(5),EXPB(5),SINB(5),COSB(5),EX	4
IPC(5),SINC(5),COSC(5),EXPD(5),SIND(5),COSD(5),SINHA(5),COSHA(5),SQ	5
ZRTA(5),SINHB(5),COSHB(5),SQRTB(5),SINHC(5),COSH(5),SQRTC(5),SINH	6
3(5),COSHD(5)	7
X=CMPLX(EXPC(I)-EXPA(I)*W**2,EXPB(I)*W)	8
Y=EXPD(I)*CSQRT(X)	9
EXPFX=CEXP(Y)	10
GO TO 1	11
ENTRY SINFX(I)	12
X=CMPLX(SINC(I)-SINA(I)*W**2,SINB(I)*W)	13
Y=SIND(I)*CSQRT(X)	14
EXPFX=CSIN(Y)	15
GO TO 1	16
ENTRY COSFX(I)	17
X=CMPLX(COSC(I)-COSA(I)*W**2,COSB(I)*W)	18
Y=COSD(I)*CSQRT(X)	19
EXPFX=CCOS(Y)	20
GO TO 1	21
ENTRY SINHFX(I)	22
X=CMPLX(SINHC(I)-SINHA(I)*W**2,SINHB(I)*W)	23
Y=SINH(5)*CSQRT(X)	24
X1=REAL(Y)	25
Y1=AIMAG(Y)	26
EXPFX=CMPLX(SINH(X1)*COS(Y1),COSH(X1)*SIN(Y1))	27
GO TO 1	28
ENTRY COSHFX(I)	29
X=CMPLX(COSH(5)-COSHA(I)*W**2,COSHB(I)*W)	30
Y=COSHD(5)*CSQRT(X)	31
X1=REAL(Y)	32
Y1=AIMAG(Y)	33
EXPFX=CMPLX(COSH(X1)*COS(Y1),SINH(X1)*SIN(Y1))	34
GO TO 1	35
ENTRY SQRTFX(I)	36
X=CMPLX(SQRTC(I)-SQRTA(I)*W**2,SQRTB(I)*W)	37
EXPFX=CSQRT(X)	38
RETURN	39
END	40-

Subroutine CALTIT

SUBROUTINE CALTIT	1
COMMON /ARRAY/ BA(14),NDEN,NNUM	2
DIMENSION FUNC(4)	3
DATA FUNC(1)/20HTRANSFER FUNCTION X /	4
AD=NDEN	5
AN=NNUM	6
CALL SYMBOL (-1.5,1.,.15,BA,90.,80)	7
CALL SYMBOL (-1.0,1.,.15,FUNC,90.,19)	8
CALL NUMBER (-.85,3.4,.100,AD,90.,-1)	9
CALL SYMBOL (-1.,3.52,.15,2H/X,90.,2)	10
CALL NUMBER (-.85,3.70,.100,AN,90.,-1)	11
RETURN	12
END	13-

Block Data

```

BLOCK DATA
COMMON /CLPLOT/ XPEN,YPEN,NX,NY,IPEN,XL(10),YL(10)
DATA XPEN,YPEN,IPEN/2*0.,-3/
END

```

Subroutine LOGPLT

```

C      SUBROUTINE LOGPLT (XDOWN,YACROS,KKK,P)
C
C      THIS LOG PLOTTING PROGRAM WAS WRITTEN BY MR. BERT HENRY OF
C      LEWIS RESEARCH CENTER. IT WAS MODIFIED BY MR. JERRY LENHART AND
C      MR. JOHN RIEHL ALSO OF LEWIS RESEARCH CENTER
C
C      THIS IS A GENERAL ROUTINE FOR MAKING LOG-LOG AND SEMI-LOG CALCOMP
C      PLOTS ON PLAIN PAPER.
C
C      THIS SUBROUTINE UTILIZES THE SAME CONVENTIONS AS CALPLT EXCEPT FOR
C      KKK(1),P(3),P(4),P(6), AND P(7) AS INDICATED BELOW.
C      THE ROUTINE EXAMINES KKK(1) TO DETERMINE WHICH AXIS WILL
C      REQUIRE A LOG SCALE, THEN EXAMINES THE APPROPRIATE DATA
C      TO DETERMINE THE NUMBER OF CYCLES REQUIRED. IF THE NUMBER
C      OF CYCLES DOES NOT EXCEED 7 OR 15 ( Y OR X AXIS RE-
C      SPECTIVELY ), THE GRIDS ARE DRAWN
C      PERPENDICULAR TO THE LOG AXIS AT EVEN VALUES IN EACH CYCLE
C      IF MORE THAN 7 OR 15 CYCLES ARE REQUIRED, AN APPROPRIATE
C      MESSAGE IS PRINTED AND CONTROL IS RETURNED TO THE CALL-
C      ING PROGRAM.
C
C      FOR THE LINEAR SCALE, THE ROUTINE WILL COMPUTE THE SCALE IF AND ONLY
C      IF BOTH P(3) AND P(4), OR P(6) AND P(7), ARE SET TO 0.0
C      FOR THE X OR Y AXIS RESPECTIVELY. GRID LINES WILL BE
C      DRAWN PERPENDICULAR TO THE AXIS AT THE TICK MARKS WHICH
C      ARE CONTROLLED BY P(8).
C
C      A DESCRIPTION OF THE SUBROUTINES ARGUMENTS FOLLOWS--,
C      XDOWN IS THE NAME OF THE ARRAY CONTAINING THE VARIABLE TO BE PLOTTED
C      AS THE ABSCISSA
C      YACROS = THE NAME OF THE ARRAY CONTAINING THE VARIABLE TO BE PLOTTED
C      THE ORDINATE
C
C      KKK(1) = 1, IF Y AXIS ONLY IS LOGARITHMIC
C      KKK(1) = 2, IF X AXIS ONLY IS LOGARITHMIC
C      KKK(1) = 3, IF BOTH X AND Y AXES ARE LOGARITHMIC
C      KKK(1) = 4, IF BOTH X AND Y AXES ARE LINEAR
C      *** IF KKK(1) IS NEGATIVE THE APPROPRIATE NON-LINEAR DATA IS
C      ASSUMED TO BE IN LOG BASE 10 FORM. IF POSITIVE THEN THE DATA
C      WILL BE TRANSFORMED TO LOG BASE 10 AND LEFT IN THIS FORM.
C      KKK(2) = USED TO CONTROL SYMBOLS PLACED ON DATA POINTS
C      KKK(2) 0, FOR ONLY A LINE PLOT
C      KKK(2) 1,2,3, ETC, WILL PRODUCE A SYMBOL AT EVERY DATA POINT, OR
C      EVERY KKK(2) DATA POINTS
C      ---- A NEGATIVE KKK(2) WILL SUPPRESS THE LINE BETWEEN DATA POINTS
C      KKK(3) = THE NUMBER OF CURVES TO BE PLOTTED (KN)
C      KKK(4) = THE REPEAT CYCLE IN CASE VALUES ARE IN A MIXED ARRAY
C      KKK(5) = THE DESIRED SYMBOL
C      KKK(6) - KKK(KN+5) = THE NUMBER OF POINTS IN EACH CURVE
C      P(1) = 1.0, OPTION FOR DUPX, AS USED IN PLOTMY
C      P(1) = 2.0, OPTION FOR DUPY, AS USED IN PLOTMY
C      P(1) = 3.0, OPTION FOR NODUP, AS USED IN PLOTMY
C      P(2) = THE MAXIMUM WIDTH OF THE PLOTTED LINE
C      *****NOTE*****
C      IF ABSCISSA VALUES ARE LINEAR, THEN
C      P(3) = MINIMUM VALUE OF ABSCISSA ARRAY OF DATA
C      P(4) = MAXIMUM VALUE OF ABSCISSA ARRAY OF DATA
C      IF ABS(KKK(1)) = 1 AND EITHER P(3) OR P(4) IS NON-ZERO, THEN THE X

```

C	SCALE WILL NOT BE COMPUTED BY THE PLOT ROUTINE.	59
C	P(5) = THE MAXIMUM HEIGHT OF THE PLOTTED	60
C	MUST NOT EXCEED 10. INCHES.	61
C	*****NOTE*****	62
C	IF ORDINATE VALUES ARE LINEAR, THEN	63
C	P(6) = THE MINIMUM VALUE OF THE ORDINATE ARRAY OF DATA	64
C	P(7) = THE MAXIMUM VALUE OF THE ORDINATE ARRAY OF DATA	65
C	IF ABS(KKK(1)) = 2 AND EITHER P(6) OR P(7) IS NON-ZERO, THEN THE Y	66
C	SCALE WILL NOT BE COMPUTED BY THE PLOT ROUTINE.	67
C	*****NOTE*****	68
C	IF EITHER X OR Y ARE LINEAR, THEN	69
C	P(8) = DIV, (WILL CAUSE A TICK MARK TO BE PLACED AT EVERY 10.0/DIV IN	70
C	*****NOTE*****	71
C	P(9) - P(10),= THE COORDINATES OF THE STARTING POINT OF THE ABCISSA	72
C	P(11) - P(12),= THE COORDINATES OF THE STARTING POINT OF THE ORDINATE	73
C	P(13) = THE ANGLE IN (DEGREES) OF THE ABCISSA AXIS	74
C	P(14) = THE ANGLE IN (DEGREES) OF THE ORDINATE AXIS	75
C	P(15) = NON-ZERO IF DATA IS TO BE ROTATED PER P(13) AND P(14)	76
C		77
C	NOTE*****	78
C	THE FOLLOWING CARD IS NEEDED IN THE CALLING PROGRAM	79
C	COMMON /CLPLOT/ XPEN,YPEN,NX,NY,IPEN,XLABEL(10),YLABEL(10)	80
C	WHERE-	81
C	XPEN AND YPEN GENERATES THE INCREMENTS NECESSARY TO MOVE FROM CUR	82
C	POSITION TO XPEN,YPEN-----NORMALLY=0.0	83
C	IPEN=3, FOR PEN UP	84
C	IPEN=2, FOR PEN DOWN	85
C	IPEN=-3 OR-2 ,PROVIDES A NEW REFERENCE POINT AT (XPEN,YPEN) RELATIVE	86
C	THE CURRENT REFERENCE POINT	87
C	TITLES	88
C	XLABEL = THE NAME OF THE ALPHABETIC ARRAY OF DATA FOR THE ORDINATE AX	89
C	YLABEL = THE NAME OF THE ALPHABETIC ARRAY OF DATA FOR THE ABCISSA AXI	90
C	NX= THE NUMBER OF CHARACTERS IN THE ORDINATE AXIS TITLE, A MINUS NX P	91
C	THE ANNOTATION ON THE CLOCKWISE SIDE OF THE AXIS INSTEAD OF THE	92
C	COUNTER CLOCKWISE SIDE	93
C	NY= THE NUMBER OF CHARACTERS IN THE ABCISSA AXIS TITLE, A MINUS NY P	94
C	THE ANNOTATION ON THE CLOCKWISE SIDE OF THE AXIS INSTEAD OF THE	95
C	COUNTER CLOCKWISE SIDE	96
C	COMMON /CLPLOT/ XPEN,YPEN,NX,NY,IPEN,XLABEL(10),YLABEL(10)	97
C	COMMON /SPECL/ TEST,ORGSET,SPASET	98
C	COMMON /XCPIDX/ NBLNO,IRUNO,CPIID(8)	99
C	DIMENSION SAVARA(4)	100
C	DIMENSION XDOWN(1), YACROS(1), KKK(1), P(1)	101
C	EQUIVALENCE (STR,ISTR)	102
C	DATA RUNMES/6HRUN NC/	103
C	DATA BLKMES/6HBLK NC/	104
C	DATA INITAL/50/	105
C	DATA STR/05C00000000000/	106
C	DATA SPACER/8./	107
C	IF (INITAL.EQ.50) GO TO 3	108
1	IF (P(1).EQ.4.0) GO TO 2	109
C	IF (IPEN.NE.(-3)) GO TO 5	110
C	IF (XPEN.EQ.STR) XPEN=0.	111
C	IF (YPEN.EQ.STR) YPEN=0.	112
C	GO TO 4	113
2	CALL PLOT (XPEN,YPEN,IPEN)	114
C	RETURN	115
3	XTPEN=0.0	116
C	YTPEN=0.0	117
C	ITPEN=-3	118

	XSPAC=SPACER	119
	IF (P(1).EQ.STR) P(1)=3.0	120
	IF (P(2).EQ.STR) P(2)=10.0	121
	IF (P(3).EQ.STR) P(3)=0.	122
	IF (P(4).EQ.STR) P(4)=0.	123
	IF (P(5).EQ.STR) P(5)=10.0	124
	IF (P(6).EQ.STR) P(6)=0.	125
	IF (P(7).EQ.STR) P(7)=0.	126
	IF (P(8).EQ.STR) P(8)=10.0	127
	IF (P(9).EQ.STR) P(9)=0.	128
	IF (P(10).EQ.STR) P(10)=0.	129
	IF (P(11).EQ.STR) P(11)=0.	130
	IF (P(12).EQ.STR) P(12)=0.	131
	IF (P(13).EQ.STR) P(13)=0.	132
	IF (P(14).EQ.STR) P(14)=90.0	133
	IF (P(15).EQ.STR) P(15)=0.	134
	IF (KKK(1).EQ.ISTR) KKK(1)=1	135
	IF (KKK(2).EQ.ISTR) KKK(2)=0	136
	IF (KKK(3).EQ.ISTR) KKK(3)=1	137
	IF (KKK(4).EQ.ISTR) KKK(4)=1	138
	IF (KKK(5).EQ.ISTR) KKK(5)=1	139
	IF (KKK(6).EQ.ISTR) KKK(6)=1	140
	INITAL=0	141
	CALL PLOT (XTPEN,YTPEN,ITPEN)	142
	FBLOND=NBLOND	143
	CALL SYMBOL (0.0,1.0,0.2,CPIID(1),90.0,24)	144
	CALL SYMBOL (0.5,1.0,0.2,RUNMES,90.0,6)	145
	CALL SYMBOL (0.5,2.5,0.2,IRUND,90.0,6)	146
	CALL SYMBOL (0.5,4.0,0.20,BLKMES,90.0,6)	147
	CALL NUMBER (0.5,6.0,0.20,FBLOND,90.0,-1)	148
	XTPEN=10.0	149
	CALL PLOT (XTPEN,YTPEN,ITPEN)	150
	GO TO 1	151
4	CALL PLOT (XPEN,YPEN,IPEN)	152
5	NXI=-1	153
	FBLOND=NBLOND	154
	CALL SYMBOL (-3.5,0.0,0.15,BLKMES,0.0,6)	155
	CALL NUMBER (-2.5,0.0,0.15,FBLOND,0.0,-1)	156
	YTPEN=0.0	157
	XTPEN=2.0	158
	ITPEN=-3	159
	CALL PLOT (XTPEN,YTPEN,ITPEN)	160
C	CHECK FOR SCALING IN DUPX OPTION	161
	JX=1	162
	JY=1	163
	IF (P(3).NE.0.) GO TO 6	164
	IF (P(4).EQ.0.) JX=2	165
6	IF (P(6).NE.0.) GO TO 7	166
	IF (P(7).EQ.0.) JY=2	167
7	J=IABS(KKK(1))	168
	IPOPT=P(1)	169
	KN=KKK(3)	170
	NPTS=0	171
	DO 8 I=1,KN	172
8	NPTS=NPTS+KKK(I+5)	173
C	TRANSLATE AND ROTATE DATA IF DESIRED	174
	IF (P(3).NE.3.) GO TO 9	175
C	IF (P(15).EQ.0.) GO TO 63	176
	CALL TRNSFM (XDOWN,YACROS,NPTS,P(13),P(14))	177
C	SETUP NUMBER OF POINTS FOR DUPX, AND DUPY	178

5	NSPTS=KN*KKK(6)	179
	NPT=KKK(6)	180
	IF (KKK(6).EQ.0) GO TO 29	181
	GC TO (10,11,12),IPCPT	182
C	SETUP FOR AXIS SUBROUTINE	183
C	CHECK FOR DUPX,DUPY OR NODUP OPTION	184
10	NP1=NPT	185
	NP2=NSPTS	186
	GC TO 13	187
11	NP1=NSPTS	188
	NP2=NPT	189
	GC TO 13	190
12	NP1=NPTS	191
	NP2=NPTS	192
13	GC TO (14,19,18,14),J	193
14	GC TO (15,16),JX	194
15	XMIN=P(3)	195
	DELX=(P(4)-P(3))/P(2)	196
	GC TO 17	197
16	CALL SCALE (XDOWN,P(2),NP1,KKK(4),P(8),XMIN,DELX)	198
17	CALL AXGRID (P(9),P(10),XLABEL,NX,P(2),P(13),XMIN,DELX,P(8),P(5),P(14))	199
	IF (J.EQ.4) GO TO 19	200
18	CALL GRID (P(11),P(12),YLABEL,NY,YACROS,NP2,KKK(1),P(5),P(14),P(2),P(13),YMIN,DELY,7)	201
	GO TO (24,24,23,24),J	202
19	GC TO (20,21),JY	203
20	YMIN=P(6)	204
	DELY=(P(7)-P(6))/P(5)	205
	GO TO 22	206
21	CALL SCALE (YACROS,P(5),NP2,KKK(4),P(8),YMIN,DELY)	207
22	CALL AXGRID (P(11),P(12),YLABEL,NY,P(5),P(14),YMIN,DELY,P(8),P(2),P(13),15)	208
	IF (J.EQ.4) GO TO 24	209
23	CALL GRID (P(9),P(10),XLABEL,NX,XDOWN,NP1,KKK(1),P(2),P(13),P(5),P(14),XMIN,DELX)	210
C	SETUP FOR ENTERING LINE AND AXIS SUBROUTINES	211
24	CONTINUE	212
	K2=0	213
	JJJ2=0	214
	DO 28 IND=1,KN	215
	K3=IND	216
	K4=K2	217
	IKSYMB=KKK(5)+IND-1	218
	ISYM=2	219
	IF (KKK(2).EQ.999) ISYM=KN+K3+5	220
C	SETUP FOR CHECKING DUPX,DUPY,OR NODUP OPTION	221
C		222
	GC TO (25,26,27),IPCPT	223
C	DUPX OPTION FOR LINE	224
C		225
25	IF (KKK(6).EQ.0) GO TO 28	226
	K2=K2+KKK(6)	227
	CALL LINE (XDOWN,YACROS(K4+1),KKK(6),KKK(4),KKK(1),IKSYMB,XMIN,DELY,YMIN,DELY)	228
	GC TO 28	229
C	DUPY OPTION FOR LINE	230
C		231
26	IF (KKK(6).EQ.0) GO TO 28	232
	K2=K2+KKK(6)	233
		234
		235
		236
		237
		238

	CALL LINE (XDOWN(K4+1),YACROS,KKK(6),KKK(4),KKK(1SYM),IKSYMB,XMIN,	239
	1DELX,YMIN,DELY)	240
	GO TO 28	241
C	NODLP OPTION FOR LINE	242
C		243
27	IF (KKK(K3+5).EQ.0) GO TO 28	244
	K2=K2+KKK(K3+5)	245
	K1=K2	246
	JJJ2=K2+2	247
	CALL LINE (XDOWN(K4+1),YACROS(K4+1),KKK(K3+5),KKK(4),KKK(1SYM),IKS	248
	1YMB,XMIN,DELX,YMIN,DELY)	249
28	CONTINUE	250
	CALL CALTIT	251
	XPEN1=P(2)+XSPAC	252
	IPEN=XPEN1	253
	XPEN1=IPEN	254
	YPEN=0.0	255
	IPEN=-3	256
	CALL PLOT (XPEN1,YPEN,IPEN)	257
	XSPAC=SPACER	258
29	RETURN	
	END	259-

Subroutine GRID

```

C THIS SUBROUTINE WILL DRAW AXIS WITH LOG SCALE AND ITS GRID LINES 1
C SUBROUTINE GRID (X,Y,BCD,NN,XX,N,M,SIZE,THETA,HGT,THTY,XXMIN,XXDEL 2
C J,KCYMAX) 3
C WHERE- X,Y IS THE COORDINATE OF THE STARTING POINT OF THE AXIS. 4
C BCD IS THE LOCATION OF ALPHA INFORMATION FOR AXIS TITLE. 5
C NN IS THE NUMBER OF CHARACTERS IN BCD TITLE. A NEGATIVE 6
C NN PLACES THE TITLE ON THE CLOCKWISE SIDE OF THE AXIS 7
C LINE AND VICE-VERSA 8
C XX IS THE NAME OF THE ARRAY IN THE AXIS DIRECTION 9
C N IS THE NUMBER OF POINTS GIVEN IN THE XX ARRAY 10
C M IS POSITIVE IF THE XX ARRAY IS TO BE CONVERTED TO LOG 11
C BASE 10. FOR NEGATIVE M THE XX ARRAY VALUES WILL BE 12
C TAKEN AS LOG BASE 10 VALUES 13
C SIZE IS THE LENGTH OF THE AXIS TO BE PLOTTED IN INCHES 14
C THETA IS THE ANGLE IN DEGREES OF THE AXIS MEASURED IN 15
C COUNTER-CLOCKWISE DIRECTION FROM THE X AXIS. 16
C HGT IS THE LENGTH OF THE OTHER AXIS IN INCHES 17
C THTY IS THE ANGLE IN DEGREES OF THE OTHER AXIS MEASURED 18
C COUNTER-CLOCKWISE FROM THE X AXIS. 19
C 20
C DIMENSION XX(1), TIC(9), XSPC(9), YSPC(9), VAL(5) 21
C DATA (TIC(I),I=1,9)/.0457575,.0511525,.057992,.0669467,.0791813,.0 22
C 19691,.1249387,.1760913,.30103/ 23
C DATA (VAL(I),I=1,5)/8.,6.,4.,2.,1./ 24
C DATA RAD/.0174532925/ 25
C KATE=1 26
C XMN=1.E28 27
C XMAX=-XMN 28
C DO 2 I=1,N 29
C IF (M.LT.0) GO TO 1 30
C XX(I)=ALOG10(XX(I)) 31
C 1 IF (XX(I).GT.XMAX) XMAX=XX(I) 32
C IF (XX(I).LT.XMIN) XMIN=XX(I) 33
C 2 CONTINUE 34
C KXMAX=XMAX 35
C XMAXK=KXMAX 36
C IF (XMAX.GT.XMAXK) XMAXK=XMAXK+1. 37
C KXMIN=XMIN 38
C XMINK=KXMIN 39
C IF (XMIN.LT.XMINK) XMINK=XMINK-1. 40
C KXCYC=XMAXK-XMINK 41
C IF (KXCYC.GT.7.AND.KCYMAX.EQ.7) GO TO 13 42
C IF (KXCYC.GT.15.AND.KCYMAX.EQ.15) GO TO 14 43
C SCALEX=SIZE/FLOAT(KXCYC) 44
C XPMN=XMINK 45
C XXDEL=VAL(5)/SCALEX 46
C NCX=5*KXCYC 47
C NCXPTS=9*KXCYC 48
C CTH=THETA*RAD 49
C STH=SIN(CTH) 50
C CTH=COS(CTH) 51
C CTHY=(THTY-90.)*RAD 52
C STHY=SIN(CTHY) 53
C CTHY=COS(CTHY) 54
C DO 3 I=1,9 55
C XSPC(I)=TIC(I)*CTH*SCALEX 56
C 3 YSPC(I)=TIC(I)*STH*SCALEX 57
C XN=X+CTH*SIZE 58

```

	YN=Y+STH*SIZE	59
	XNX=XN	60
	YNY=YN	61
	CALL PLOT (XN,YN,3)	62
	DC 4 I=1,NOXPTS	63
	JJ=I-1	64
	KK=MOD(JJ,9)+1	65
	XN=XN-XSPC(KK)	66
	YN=YN-YSPC(KK)	67
4	CALL SYMBOL (XN,YN,.1,13,THETA,-2)	68
	DO 5 I=1,4	69
	XSPC(I)=XSPC(2*I-1)+XSPC(2*I)	70
5	YSPC(I)=YSPC(2*I-1)+YSPC(2*I)	71
	XSPC(5)=XSPC(9)	72
	YSPC(5)=YSPC(9)	73
	XNU=XNX-STHY*HGT	74
	YNU=YNY+CTHY*HGT	75
	KOTO=1	76
	IF (ABS(XSPC).LT.1.E-3) KOTO=2	77
	DO 8 I=1,NOX	78
	JJ=I-1	79
	KK=MOD(JJ,5)+1	80
	CALL PLOT (XNU,YNU,3)	81
	CALL PLOT (XNX,YNY,2)	82
	XNX=XNX-XSPC(KK)	83
	YNY=YNY-YSPC(KK)	84
	XNU=XNU-XSPC(KK)	85
	YNU=YNU-YSPC(KK)	86
	GC TO (6,7),KOTO	87
6	TEMP=YNU	88
	YNU=YNY	89
	YNY=TEMP	90
	GC TO 8	91
7	TEMP=XNU	92
	XNU=XNX	93
	XNX=TEMP	94
8	CONTINUE	95
	CALL PLOT (0.,0.,3)	96
	NCTE=NOX+1	97
	DXB=-.05	98
	DYB=-.05*(1.-3.*STH)+SIGN(.15,NN)	99
	DXC=SIZE/2.-f.12*FLCAT((IABS(NN)+7)/2))	100
	DYC=(-.075+SIGN(.375,NN))	101
	XN=X+DXB*CTH-DYB*STH	102
	YN=Y+DYB*CTH+DXB*STH	103
	SPC=.20	104
	SPS=.06	105
	XNT=SQRT(DXC**2+DYC**2)	106
	DO 12 I=1,NCTE	107
	JJ=I-1	108
	KK=MOD(JJ,5)	109
	LL=5-KK	110
	IF (KK.NE.0) GO TO 9	111
	CALL SYMBOL (XN,YN,.1,2H10,0.,2)	112
	XT=XN+SPC	113
	YT=YN+SPS	114
	CALL NUMBER (XT,YT,.07,XMINK,0.,-1)	115
	XMINK=XMINK+1.	116
	GC TO 10	117
9	CALL NUMBER (XN,YN,.1,VAL(LL),0.,-1)	118

10	XN=XN+XSPC(LL)	119
	YN=YN+YSPC(LL)	120
	GO TO (11,12),KATE	121
11	IF (XNT.GT.SQRT(XN**2+YN**2)) GO TO 12	122
	XI=X+DXC*CTH-DYC*STH	123
	YT=Y+DYC*CTH+DXC*STH	124
	CALL SYMBOL (XI,YT,.14,BCD,THETA,IABS(NN))	125
	KATE=2	126
12	CONTINUE	127
	RETURN	128
13	WRITE (6,17)	129
	GO TO 15	130
14	WRITE (6,16)	131
15	CONTINUE	132
	STOP	133
C		134
16	FORMAT (33HONLY 15 CYCLES ALLOWED FOR X-AXIS)	135
17	FORMAT (32HONLY 7 CYCLES ALLOWED FOR Y-AXIS)	136
	END	137-

Subroutine TRNSFM

SUBROUTINE TRNSFM (X,Y,N,THETX,THETY)	1
DIMENSION X(1), Y(1)	2
RETURN	3
END	4-

Subroutine AXGRID

```

C THIS SUBROUTINE WILL DRAW A LINEAR AXIS WITH ITS GRID LINES 1
C SUBROUTINE AXGRID (X,Y,BCD,N,SIZE,THETA,XMIN,DX,DV,HGT,THTY) 2
C 3
C WHERE- X,Y IS THE COORDINATE OF THE STARTING POINT OF THE AXIS. 4
C BOTH ARE FLOATING POINT AND PAGE INCHES. 5
C BCD IS THE LOCATION OF ALPHA INFORMATION FOR AXIS TITLE. 6
C USUALLY VARIABLE NAME. (NORMALLY SET UP WITH LITERAL) 7
C N IS THE NUMBER OF CHARACTERS IN BCD TITLE. A NEGATIVE 8
C N PLACES THE ANNOTATION ON THE CLOCKWISE SIDE OF AXIS 9
C LINE AND VICE-VERSA. 10
C SIZE IS THE LENGTH OF THE AXIS TO BE DRAWN. SIZE IS 11
C FLOATING POINT AND SHOULD BE MULTIPLY OF (10.0/DIV). 12
C THETA IS THE ANGLE OF THE AXIS MEASURED COUNTER-CLOCKWISE 13
C FROM X AXIS. THETA IS FLOATING POINT DEGREES. 14
C XMIN IS THE VALUE OF VARIABLE AT THE FIRST POINT OF THE 15
C AXIS. XMIN IS FLOATING POINT. (SEE NOTE) 16
C DX IS THE DIFFERENCE BETWEEN SECOND AND FIRST VALUE OF 17
C VARIABLE ALONG AXIS. DX IS FLOATING POINT. (SEE NOTE) 18
C DV IS THE NUMBER OF DIVISION PER INCH OF PAPER TO BE USED 19
C DV IS FLOATING POINT. (MAY BE 10.0,20.0,25.0,25.4) 20
C HGT IS THE LENGTH OF THE OTHER AXIS 21
C THTY IS THE ANGLE OF THE OTHER AXIS TO BE USED. 22
C NOTE- THE SECOND VERSION OF SCALE PLACES XMIN IN VARIABLE(J*K+1)AND 23
C DX IN VARIABLE(J*K+K+1). WHERE J IS NUMBER OF ELEMENTS IN 24
C ARRAY AND K IS THE REPEAT CYCLE OF MIXED ARRAY. 25
C 26
C DIV=DV 27
C TWO=2.0 28
C IF (DIV.LT.1..OR.DIV.GT.25.4) DIV=10.0 29
C TH=THETA*.0174532925 30
C THTY=(THTY-90.)*.0174532925 31
C STHY=SIN(THTY) 32
C CTHY=COS(THTY) 33
C CTH=COS(TH) 34
C STH=SIN(TH) 35
C DIVA=DIV 36
C IF (DIV-20.0) 1,2,2 37
C DIVA=2.0*DIV 38
C TWO=1.0 39
C SPACE=10.0/DIVA 40
C DXB=-.05*(1.+2.*CTH) 41
C DYB=-.05*(1.-5.*STH)+SIGN(.15,N) 42
C DXC=SIZE/2.-(.12*FLCAT((IABS(N))/2)) 43
C DYC={-.075+SIGN(.575,N)} 44
C DNOTE=SIZE/SPACE/2.0+1.0 45
C NNOTE=DNOTE 46
C IF ((DNOTE-FLOAT(NOTE)).GT.0.99) NOTE=NOTE+1 47
C SPC=CTH*SPACE*2.0 48
C SPS=STH*SPACE*2.0 49
C XN=X+DXB*CTH-DYB*STH 50
C YN=Y+DYB*CTH+DXB*STH 51
C ADY=ABS(DX)*10.0/DIV 52
C EX=0.0 53
C IF (ADY) 3,7,3 54
C IF (ADY-100.0) 6,4,4 55
C ADY=ADY/10.0 56
C EX=EX+1.0 57
C GO TO 3 58

```

5	ADY=ADY*10.0	59
	EX=EX-1.0	60
6	IF (ADY-1.) 5,7,7	61
7	ABSV=XMIN/10.0*EX	62
	NADY=ADY	63
	IF (ABS(ADY-FLOAT(NADY)).GT..99) ADY=IFIX(ADY+SIGN(.01,ADY))	64
	ADY=SIGN(ADY,DX)*TWC	65
	NT=SQRT(DXC**2+DYC**2)	66
	DO 10 I=1,NTIC	67
	CALL NUMBER (XN,YN,.1,ABSV,0.,0)	68
	ABSV=ABSV+ADY	69
	XN=XN+SPC	70
	YN=YN+SPS	71
	IF (NT) 10,8,10	72
8	XT=X+DXC*CTH-DYC*STH	73
	YT=Y+DYC*CTH+DXC*STH	74
	CALL SYMBOL (XT,YT,.14,BCD,THETA,IABS(N))	75
	IF (EX) 9,10,9	76
9	XT=XT+.12*FLOAT(IABS(N))*CTH	77
	YT=YT+.12*FLOAT(IABS(N))*STH	78
	CALL SYMBOL (XT,YT,.14,7H(X10),THETA,7)	79
	XT=XT+(.12*5.*CTH-.06*STH)	80
	YT=YT+(.12*5.*STH+.06*CTH)	81
	CALL NUMBER (XT,YT,.08,EX,THETA,-1)	82
10	NT=NT-1	83
	DNTIC=DIV*SIZE/10.0+1.0	84
	NTIC=DNTIC	85
	IF ((DNTIC-FLOAT(NTIC)).GT.0.99) NTIC=NTIC+1	86
	XN=X+CTH*SIZE	87
	YN=Y+STH*SIZE	88
	XNX=XN	89
	YNY=YN	90
	XNU=XNX-STHY*HGT	91
	YNU=YNY+CTHY*HGT	92
	SPC=CTH*10.0/DIV	93
	SPS=STH*10.0/DIV	94
	CALL PLOT (XN,YN,3)	95
	XN=FLOAT(NTIC-1)*SPC+X	96
	YN=FLOAT(NTIC-1)*SPS+Y	97
	DO 11 I=1,NTIC	98
	CALL SYMBOL (XN,YN,0.2*SPACE,13,THETA,-2)	99
	XN=XN-SPC	100
11	YN=YN-SPS	101
	NTIC=NTIC-1	102
	KOTO=1	103
	IF (ABS(SPS).LT.1.E-03) KOTO=2	104
	DO 14 I=1,NTIC	105
	CALL PLOT (XNU,YNU,3)	106
	CALL PLOT (XNU,YNU,3)	107
	CALL PLOT (XNX,YNY,2)	108
	XNX=XNX-SPC	109
	YNY=YNY-SPS	110
	XNU=XNU-SPC	111
	YNU=YNU-SPS	112
	GO TO (12,13),KOTO	113
12	TEMM=XNU	114
	XNU=XNX	115
	XAX=TEMM	116
	GO TO 14	117
13	TEMM=YNU	118
	YNU=YNY	119
	YNY=TEMM	120
14	CONTINUE	121
	RETURN	122
	END	123

APPENDIX E

USER'S MANUAL

HOW TO USE REDUCE II

The input to REDUCE II consists of five basic pieces of information:

- (1) A card indicating whether the super G form is ARTIFICIAL or NATURAL
- (2) The block diagram inputs
- (3) The transfer function (or functions) desired
- (4) A set of algebraic expressions representing the block diagram
- (5) A sequence of variables separated by commas representing the reduction order string

With the exception of the first card, the input data can be punched anywhere on a card.

Examples of Input to REDUCE II

Examples corresponding to the five basic types of input are described as follows:

- (1) This card must have ARTIFICIAL or NATURAL punched on it starting in card column 1.

- (2) The block diagram inputs are specified as, for example,

$$X(7)\$X(5)\$X(1)\$\$$$

A dollar sign separates each input. Two dollar signs in succession (no blanks between them) indicate the end of the block diagram inputs. There may be no more than five inputs for a block diagram as the program is currently dimensioned, and only one card may be used.

- (3) The desired transfer function for the block diagram is given by, for example,

$$X(2)\$X(1)\$\$ \quad \text{or} \quad X(2)\$\$$$

When two variables are indicated, REDUCE II solves the block diagram for the ratio of the first variable given (the output) to the second (an input). When one variable is given, REDUCE II solves for the ratio of this variable to all the inputs. Again two dollar signs in succession indicate the end of this information, and only one card may be used.

- (4) Block diagram expressions are written as

$$(\pm N \pm G(A) * G(B) * \dots * G(F)) * X(B) \pm G(M) * G(N) * \dots * X(C) \pm \dots \$$$

where A, B, C, ... are integers, N is a numerical constant, the G(i)'s are functions, and the X(i)'s are variables. This allows very general forms that consist of variables X together with their coefficients, which are the sums and products of G's and constants. Notice again that a dollar sign terminates an expression. No more than five cards may be used per expression. An example of an expression card is

$$X(1)+X(2)-X(3)+G(4)*X(9)+(1.+G(1)*G(2))*X(4)\$$$

FORTRAN notation is used to indicate subscripts and arithmetic operations. Also the =0 to make this a mathematical equation is implied. On the very last expression, the user must use two dollar signs in succession. This indicates to REDUCE II that there are no more expression cards to follow.

(5) The reduction order string terminates the input to REDUCE II. Typically, it is

$$X(A), X(B), X(C), , X(D), X(E), , X(F), \dots X(M)\$$$

where the A, B, C, ... are integers. The double commas partition the string into substrings and indicate a super G substitution. The dollar sign terminates the reduction string and should not be immediately preceded by any commas. An example is

$$X(2), X(5), X(6), , X(10), X(7), , X(8)\$$$

There must be no repetition of a variable in the reduction string. All variables but the output and inputs must be represented in the reduction string. Any number of cards may be used. Notice also that one dollar sign terminates the reduction string. These are all the data that REDUCE II needs.

REDUCE II Output

The output consists mainly of a set of cards. Included in these cards are the super G's, the transfer function (or functions), and the transfer function identifiers. EVAL II uses this punched output in several places. The punched deck, after execution of REDUCE II, appears in the sequence shown in figure 17.

REDUCE II prints a copy of the super G cards and the transfer function. Also the user's input is printed. Should REDUCE II detect an error, a message is printed and execution is usually stopped. A list of the messages and their causes follows:

Message	Cause
(1) More than 600 variables	The number of variables exceeds the maximum allowed.

Message

Cause

- | | |
|---|--|
| (2) More than 600 equations | The number of equations exceeds the maximum allowed. |
| (3) More than 1200 functions | The number of G functions before the reduction starts exceeds the maximum allowed. |
| (4) More than five block diagram inputs | The number of block diagram inputs exceeds the maximum allowed. |
| (5) More than five cards for a block diagram expression | Block diagram algebraic expressions may not use more than five cards. |
| (6) The solution may be in error because equation ____ was not eliminated, equation ____ is | A variable used in the block diagram was not eliminated. This is because it was not included in the order string. |
| (7) Number of variables in order string is not consistent with the number of expressions - execution stopped | There are probably one or more block diagram expressions missing, or there is a mistake in the order string. Check the input data. |
| (8) Only one equation containing X() | Only one equation was found containing the variable indicated. This indicates an error in the order string or in an equation. This error message will also be printed if there are <u>no</u> equations with the variable indicated. |
| (9) Warning - the number of super functions (super G's) exceeds the maximum number of functions (G's) permitted, therefore substitution process stopped | No more super G's will be created since the dimension of G is exceeded. Although the super G substitution process will stop, the reduction process will continue. It is likely that the expressions will become very large and that FORMAC storage space will be exceeded. |
| (10) Subscript too large for this version | Subroutine INSTRN has found a subscript larger than 600 in the reduction string. |
| (11) Invalid option specified on super G from card | User has not specified NATURAL or ARTIFICIAL form. |

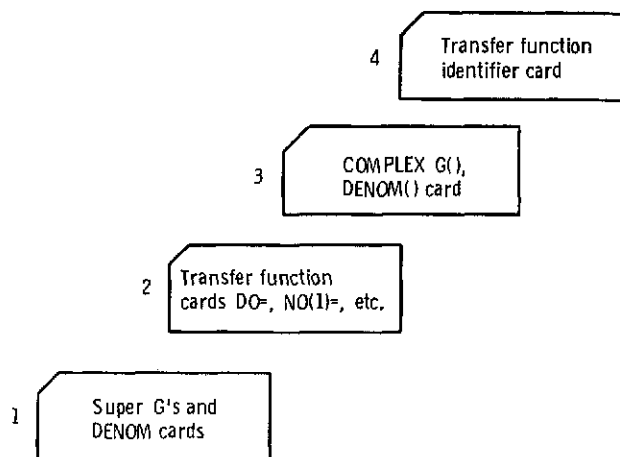


Figure 17. - REDUCE II output card order.

HOW TO USE EVAL II

Before EVAL II can be used, the output from REDUCE II must be rearranged. The FORTRAN-like cards go into subroutine COEFF of EVAL II. The other cards are data to identify transfer functions. They also tell EVAL II how many transfer functions are to be evaluated for any particular run. The cards shown in figure 17 are regrouped as shown in figure 18.

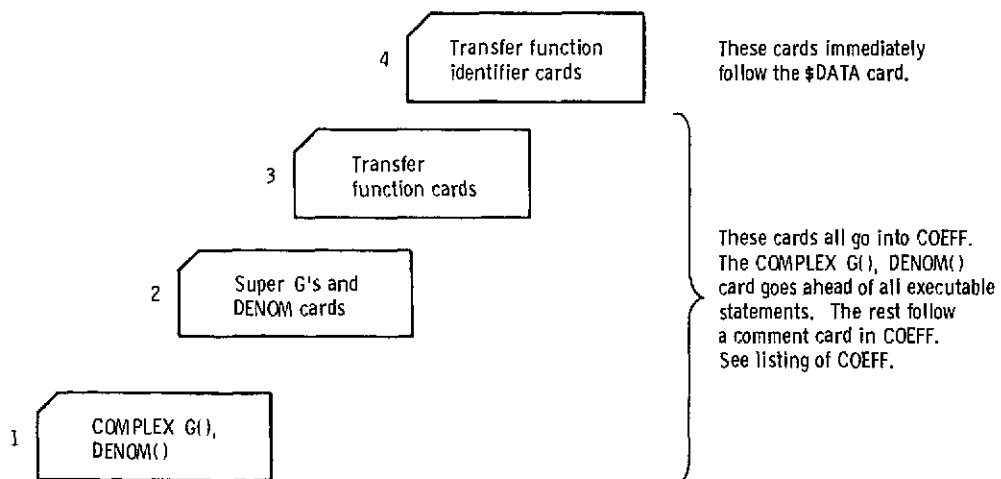


Figure 18. - REDUCE II output regrouped.

The user's functions or G's should be placed before the super G cards. These functions may be of any form as long as they are in FORTRAN. Should they be one of the following forms, the namelist input section of EVAL II can be used:

$$\sin\left(d\sqrt{as^2 + bs + c}\right) = \text{SINHFI(I)} \quad (\text{E1})$$

$$\cosh\left(d\sqrt{as^2 + bs + c}\right) = \text{COSHFI(I)} \quad (\text{E2})$$

$$\sin\left(d\sqrt{as^2 + bs + c}\right) = \text{SINF(I)} \quad (\text{E3})$$

$$\cos\left(d\sqrt{as^2 + bs + c}\right) = \text{COSFI(I)} \quad (\text{E4})$$

$$\exp\left(d\sqrt{as^2 + bs + c}\right) = \text{EXPFI(I)} \quad (\text{E5})$$

$$\sqrt{as^2 + bs + c} = \text{SQRTFI(I)} \quad (\text{E6})$$

where I is an integer constant.

EVAL II Input

Section I. - The first data cards to EVAL II are the transfer function identifiers that REDUCE II punched out.

Section II. - The next card of the EVAL input must contain \$INPUT beginning in card column 2. This starts the namelist section of EVAL II data. The following input forms may appear in any order, but all must begin in card column 2:

- (1) NEXP = Number, EXPA = List, EXPB = List, EXPC = List, EXPD = List,
- (2) NSIN = Number, SINA = List, SINB = List, SINC = List, SIND = List,
- (3) NCOS = Number, COSA = List, COSB = List, COSC = List, COSD = List,
- (4) NSINH = Number, SINHA = List, SINHB = List, SINHC = List, SINHD = List,
- (5) NCOSH = Number, COSHA = List, COSHB = List, COSHC = List, COSHD = List,
- (6) NSQRT = Number, SQRTA = List, SQRTB = List, SQRTC = List,
- (7) NK = Number, K = List,
- (8) NT = Number, T = List,
- (9) NZ = Number, Z = List,
- (10) NWN = Number, WN = List,

(11) FSTART = Initial frequency, FEND = Final frequency, DELTAF = Increment
(Frequencies are specified in hertz.)

(12) LENGTH = Length of the abscissa in inches.

Any of these forms may use more than one card as long as each card ends with a comma. The suffixes A, B, C, and D in the function names represent the variables implied in the function argument. (Note: no D in SQRT.) For example, EXPA, EXPB, EXPC, and EXPD represent the variables a, b, c, and d in the function

$$\exp\left(d\sqrt{as^2 + bs + c}\right)$$

(See eqs. (E1) to (E6) for additional forms.)

The term "Number," as used in the preceding forms, means an integer number which represents the number of a particular type of function or variable being used. For the functions, this number must not be greater than 5; for variables, not greater than 10. The term "List" means a list of values that the variables are to take on. The elements of this list must be separated by commas and must be in the proper order. For example, NK=2, K=1, 6.25E-2 would set K(1) equal to 1.0 and K(2) equal to 0.0625. For consecutive runs (runs where the transfer function form does not change), only the changed numbers need to be given on a new input. For example,

\$INPUT

K(2)=1.25E-2,

\$

A card with a \$ in card column 2 must be the very last card of section II. This terminates the namelist data.

Section III (optional). - If LENGTH in the previous section were set to zero, no plots would be made. A positive LENGTH signals EVAL II to make CALCOMP plots. This means that EVAL II needs (1) a plot title and (2) information to make linear or log plots. This information the user punches onto two separate cards.

(1) PLOT TITLE CARD - The user may use all 80 card columns for the plot title.

(2) PLOT TYPE CARD - To get a set of semilogarithmic plots, the word LOGPLOT must appear on this card. LOGPLOT must start in card column 1. A blank card is sufficient to get linear plots.

The user may run several cases of data in one execution of EVAL II. That is, many combinations of system information may be examined in sequence. To do this, the user may change any of the data values in section II. After completing the frequency band FSTART to FEND in steps of DELTAF, EVAL II returns to the statements that read the

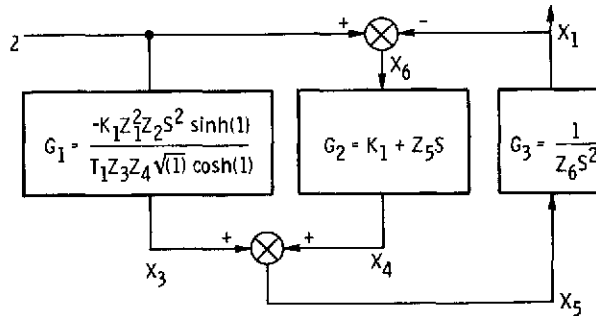
section II (namelist) data. EVAL II would read new data (or stop execution if there is no data) and start anew. Remember that if LENGTH is left greater than zero, a new plot title and new plot type information must be supplied or the program will execute improperly.

EVAL II Output

The output printed by EVAL II lists the following items: (1) All the numerical input; (2) a table to show the correspondence between the transfer function and its identifying number; (3) the frequency band FSTART to FEND in DELTAF; and (4) the identifying number, frequency (Hz), real part, imaginary part, absolute value, phase angle (deg), and magnitude (dB) of the transfer function.

The CALCOMP plots are of two types. The plots on linear axes have absolute value and phase angle as a function of frequency. Those on semilogarithmic axes have decibels as a function of frequency and phase angle as a function of frequency. Each plot is identified with the user-supplied title and the transfer function given as X_A/X_B , where A and B are integers.

A WORKED EXAMPLE



The block diagram shown is quite simple but demonstrates the use of REDUCE II. We want to solve this diagram for X_1 to X_2 using naturally formed super G's. The equations associated with the block diagram are

$$X_3 - G_1 X_2 = 0$$

$$X_4 - G_2 X_6 = 0$$

$$X_1 - G_3 X_5 = 0$$

$$X_2 - X_1 - X_6 = 0$$

$$X_3 + X_4 - X_5 = 0$$

The input data to REDUCE II for this example would be

```
NATURAL FORM
X(2)$$
X(1)$$
X(3)-G(1)*X(2)$
X(2)-X(1)-X(6)$
X(4)-G(2)*X(6)$
X(3)+X(4)-X(5)$
X(1)-G(3)*X(5)$$
X(3),X(4),,X(6),X(5)$
```

The printed output from REDUCE II for this example is

```
THE BLOCK DIAGRAM INPUTS
X(2)$
THE SOLUTION IS FOR X(1)$ TO THE INPUTS
THE BLOCK DIAGRAM EXPRESSIONS
1 X(3)-G(1)*X(2)$
2 X(2)-X(1)-X(6)$
3 X(4)-G(2)*X(6)$
4 X(3)+X(4)-X(5)$
5 X(1)-G(3)*X(5)$$
THE REDUCTION ORDER IS
1 X(3),X(4),,X(6),X(5)$
THE LARGEST VARIABLE SUBSCRIPT IS 6
THE NUMBER OF EXPRESSIONS IS 5
THE LARGEST FUNCTION (G) SUBSCRIPT IS 3
```

* * * OUTPUT FROM REDUCE II * * *

TRANSFER FUNCTION X(1)/X(2)

THE NUMERATOR
G(1)*G(3)+G(2)*G(3)

THE DENOMINATOR
G(2)*G(3)+1.0

The cards punched out by REDUCE II are

```

      DC=
      *G(2)*G(3)+1.0
      NC( 1)=
      *G(1)*G(3)+G(2)*G(3)
      CCMPLX G( 3),DENOM( 1)
1
1
2

```

The FORTRAN expressions for G_1 , G_2 , and G_3 are

$$G(1) = -K(1) * Z(1) * Z(1) * Z(2) * S * S * \text{SINH}(1) / \\ (T(1) * Z(3) * Z(4) * \text{SQRT}(1) * \text{COSH}(1))$$

$$G(2) = K(1) + Z(5) * S$$

$$G(3) = 1. / (Z(6) * S * S)$$

These expressions immediately precede the super G output in COEFF. See page 72 for a typical example. The constants associated with this example are

$$K_1 = 7.6336 \times 10^5$$

$$T_1 = 1.0416 \times 10^{-2}$$

$$Z_1 = 0.75$$

$$Z_2 = 62.4$$

$$Z_3 = 6.48 \times 10^7$$

$$Z_4 = 32.2$$

$$Z_5 = 10$$

$$Z_6 = 1$$

$$\text{SINH}(1) \longleftrightarrow \text{SINH} \left(d \cdot \sqrt{c + bs + as^2} \right)$$

$$\text{COSH}(1) \longleftrightarrow \text{COSH} \left(d \cdot \sqrt{c + bs + as^2} \right)$$

$$\sqrt{(1)} \longleftrightarrow \sqrt{c + bs + as^2}$$

where

$$a = 4.1006 \times 10^{-6}$$

$$b = 10^{-4}$$

$$c = 0$$

$$d = 3.333$$

The following cards are the input to EVAL II for this example:

```

1
1
2
$INPLT
NSINH=1, SINHA=4.100625E-6, SINHB=1.0E-4, SINHC=0., SINHD=3.3333,
NCOSH=1, COSHA=4.100625E-6, COSHB=1.0E-4, COSHC=0., COSHD=3.3333,
NSQRT=1, SQRTA=4.100625E-6, SQRTB=1.E-4, SQRTC=0.,
NK=1, K=7.76335938E6,
NT=1, T=1.0416E-2,
NZ=6, Z=750, 62.4, 6.48E7, 32.2, 10., 1.,
FSTART=1., FEND=50., DELTAF=1., LENGTH=10.,
$
A WORKED EXAMPLE
LINEAR PLOT

```

The output from EVAL II for this example is

FORTAN EVALUATION OF FORMAC OUTPUT

CALCOMP PLOTS HAVE BEEN REQUESTED

A WORKED EXAMPLE

```

1 SINHA SINHR SINHC SINHD
1 0.41006E-05 0.10000E-03 0. 0.33333E+01

1 COSHA COSHR COSMC COSMD
1 0.41006E-05 0.10000E-03 0. 0.33333E+01

1 SORTA SORTB SORTC
1 0.41006E-05 0.10000E-03 0.

1 K
1 0.76336E+06

1 J
1 0.10416E-01

1 Z
1 0.75300E+00
2 0.62400E+02
3 0.64800E+08
4 0.32200E+02
5 0.10300E+02
6 0.10300E+01
    
```

NUMBER TRANSFER FUNCTION
1 X(1)/X(2)

FSTART= 1.00000 FEND= 50.00000 DELTAF= 1.00000

NUMBER	FREQUENCY	REAL PART	IMAGINARY PART	ABSOLUTE VALUE	PHASE ANGLE	AMPLITUDE IN DB.
1	1.000000	1.000264	-0.000001	1.000264	-0.000030	0.002296
1	2.000000	1.001059	-0.000004	1.001059	-0.000238	0.009195
1	3.000000	1.002390	-0.000014	1.002390	-0.000807	0.020730
1	4.000000	1.004264	-0.000034	1.004264	-0.001930	0.036958
1	5.000000	1.006695	-0.000067	1.006695	-0.003810	0.057957
1	6.000000	1.009698	-0.000118	1.009698	-0.006671	0.083832
1	7.000000	1.013295	-0.000190	1.013295	-0.010762	0.114717
1	8.000000	1.017510	-0.000291	1.017510	-0.016364	0.150772
1	9.000000	1.022374	-0.000425	1.022374	-0.023798	0.192196
1	10.000000	1.027924	-0.000600	1.027924	-0.033437	0.239220
1	11.000000	1.034204	-0.000825	1.034204	-0.045719	0.292123
1	12.000000	1.041265	-0.001112	1.041266	-0.061162	0.351231
1	13.000000	1.049170	-0.001472	1.049172	-0.080388	0.416930
1	14.000000	1.057993	-0.001923	1.057995	-0.104148	0.489671
1	15.000000	1.067821	-0.002485	1.067824	-0.133356	0.569991
1	16.000000	1.078758	-0.003185	1.078763	-0.169141	0.658519
1	17.000000	1.090931	-0.004054	1.090938	-0.212902	0.756004
1	18.000000	1.104491	-0.005135	1.104503	-0.266397	0.863339
1	19.000000	1.119624	-0.006485	1.119643	-0.331851	0.981593
1	20.000000	1.136558	-0.008175	1.136587	-0.412119	1.112056
1	21.000000	1.155573	-0.010304	1.155619	-0.510904	1.256293
1	22.000000	1.177022	-0.013006	1.177094	-0.633071	1.416223
1	23.000000	1.201352	-0.016463	1.201465	-0.785108	1.594220
1	24.000000	1.229135	-0.020935	1.229313	-0.975805	1.793248
1	25.000000	1.261115	-0.026797	1.261400	-1.217290	2.017056
1	26.000000	1.298278	-0.034601	1.298739	-1.526637	2.270440
1	27.000000	1.341966	-0.045184	1.342707	-1.928449	2.559623
1	28.000000	1.393926	-0.059864	1.395211	-2.459133	2.892795
1	29.000000	1.456726	-0.080787	1.458964	-3.174252	3.280894
1	30.000000	1.533872	-0.111610	1.537927	-4.161703	3.738714
1	31.000000	1.630300	-0.158890	1.638024	-5.566511	4.286406
1	32.000000	1.752605	-0.235092	1.768303	-7.639974	4.951131
1	33.000000	1.907810	-0.365391	1.942485	-10.842202	5.767153
1	34.000000	2.094135	-0.602963	2.179212	-16.062666	6.765591
1	35.000000	2.254446	-1.053980	2.488654	-25.056649	7.919291
1	36.000000	2.110127	-1.819422	2.786204	-40.769007	8.900259
1	37.000000	1.178423	-2.424559	2.695768	-64.078579	8.613651
1	38.000000	0.153711	-2.014335	2.020192	-85.636267	6.107851
1	39.000000	-0.136001	-1.303576	1.310651	-95.956075	2.349741
1	40.000000	-0.071503	-0.836708	0.839758	-94.884479	-1.516920
1	41.000000	0.061374	-0.569645	0.572942	-83.850584	-4.837784
1	42.000000	0.186983	-0.412119	0.452553	-65.595722	-6.886604
1	43.000000	0.292803	-0.313532	0.428994	-46.958082	-7.350979
1	44.000000	0.380371	-0.248257	0.454217	-33.131272	-6.854729
1	45.000000	0.453432	-0.202922	0.496768	-24.109711	-6.076932
1	46.000000	0.515370	-0.170171	0.542738	-18.272824	-5.308194
1	47.000000	0.568820	-0.145730	0.587191	-14.369910	-4.624406
1	48.000000	0.615761	-0.126993	0.628721	-11.653161	-4.030847
1	49.000000	0.657672	-0.112305	0.667192	-9.690418	-3.514981
1	50.000000	0.695668	-0.100572	0.702900	-8.226227	-3.062131

PLOT MADE
PLOT MADE

REFERENCES

1. Lorenzo, Carl F.; and Swigert, Paul: Computer Program for Symbolic Reduction of Block Diagrams Using FORMAC. NASA TN D-4617, 1968.
2. Pavkovich, John M.: The Solution of Large Systems of Algebraic Equations. Tech. Rep. 33, Stanford Univ. (AD-427753), Dec. 6, 1963.
3. Bond, E. R.: User's Preliminary Reference Manual for FORMAC. Boston Advanced Programming Dept., International Business Machines, Feb. 1964.
4. Busacker, Robert G.; and Saaty, Thomas L.: Finite Graphs and Networks, An Introduction With Applications. McGraw-Hill Book Co., Inc., 1965.
5. Seshu, Sundaram; and Reed, Myril B.: Linear Graphs and Electrical Networks. Addison-Wesley Publ. Co., 1961.
6. Sammet, Jean E.: Formula Manipulation by Computer. Advances in Computers. Vol. 8. F. L. Alt and Morris Rubinoff, eds. Academic Press, 1967, pp. 47-102.

☆ U.S. GOVERNMENT PRINTING OFFICE: 1974-739-160/128